

Heavy Symmetric Top

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Angular velocity:

$$\omega = (\dot{\phi} \sin\theta \sin\psi + \dot{\theta} \cos\psi) e_1 + (\dot{\phi} \sin\theta \cos\psi - \dot{\theta} \sin\psi) e_2 + (\dot{\psi} + \dot{\phi} \cos\theta) e_3$$

Lagrangian: $I_1 = I_2$

$$L = \frac{1}{2} I_1 (\omega_1^2 + \omega_2^2) + \frac{1}{2} I_3 \omega_3^2 - Mgl \cos\theta$$

$$\begin{aligned} &= \frac{1}{2} I_1 (\dot{\phi}^2 \sin^2\theta \sin^2\psi + \dot{\theta}^2 \cos^2\psi + 2\dot{\phi}\dot{\theta} \sin\theta \sin\psi \cos\psi \\ &\quad + \dot{\phi}^2 \sin^2\theta \cos^2\psi + \dot{\theta}^2 \sin^2\psi - 2\dot{\phi}\dot{\theta} \sin\theta \sin\psi \cos\psi) \\ &\quad + \frac{1}{2} I_3 (\dot{\psi} + \dot{\phi} \cos\theta)^2 - Mgl \cos\theta \end{aligned}$$

$$\Rightarrow L = \frac{1}{2} I_1 (\dot{\theta}^2 + \dot{\phi}^2 \sin^2\theta) + \frac{1}{2} I_3 (\dot{\psi} + \dot{\phi} \cos\theta)^2 - Mgl \cos\theta$$

1. / Three conserved quantities

Energy $E = T + V$, ϕ and ψ are cyclic.

$$P_\psi = \frac{\partial L}{\partial \dot{\psi}} = I_3 (\dot{\psi} + \dot{\phi} \cos\theta) = I_3 \omega_3$$

$$P_\phi = \frac{\partial L}{\partial \dot{\phi}} = I_1 \sin^2\theta \dot{\phi} + I_3 (\dot{\psi} + \dot{\phi} \cos\theta) \cos\theta$$

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$$E = \frac{1}{2} I_1 \dot{\theta}^2 + \frac{1}{2} I_2 \dot{\phi}^2 + \frac{1}{2} I_3 \dot{\psi}^2 + \frac{1}{2} I_3 \dot{\phi}^2 \cos^2 \theta$$

$$\begin{aligned} p_\psi &= I_3 \dot{\psi} + I_3 \dot{\phi} \cos \theta \\ p_\phi &= (I_1 \sin^2 \theta + I_3 \cos^2 \theta) \dot{\phi} + I_3 \dot{\psi} \cos \theta \end{aligned} \quad \left. \begin{array}{l} \text{solve} \\ \text{for} \\ \dot{\phi} \text{ and } \dot{\psi} \end{array} \right\}$$

$$p_\psi - I_3 \dot{\psi} = I_3 \dot{\phi} \cos \theta \quad \dot{\phi} = \frac{p_\psi - I_3 \dot{\psi}}{I_3 \cos \theta}$$

$$\frac{p_\phi - I_3 \dot{\psi} \cos \theta}{I_1 \sin^2 \theta + I_3 \cos^2 \theta} = \dot{\psi} = \frac{p_\psi - I_3 \dot{\psi}}{I_3 \cos \theta}$$

$$\begin{aligned} p_\phi I_3 \cos \theta - I_3^2 \dot{\psi} \cos^2 \theta &= (p_\psi - I_3 \dot{\psi})(I_1 \sin^2 \theta + I_3 \cos^2 \theta) \\ &= p_\psi (I_1 \sin^2 \theta + I_3 \cos^2 \theta) \\ &\quad - I_3 \dot{\psi} (I_1 \sin^2 \theta + I_3 \cos^2 \theta) \end{aligned}$$

$$p_\phi I_3 \cos \theta = p_\psi (I_1 \sin^2 \theta + I_3 \cos^2 \theta) - I_3 \dot{\psi} I_1 \sin^2 \theta$$

$$\frac{p_\phi I_3 \cos \theta - p_\psi (I_1 \sin^2 \theta + I_3 \cos^2 \theta)}{-I_1 I_3 \sin^2 \theta} = \dot{\psi}$$

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$$\dot{\psi} = \frac{P\phi}{I_3} - \frac{(P\phi I_3 - P\psi I_3 \cos\theta)}{I_1 I_3 \sin^2\theta} \cos\theta$$

$$= \frac{P\phi}{I_3} - \frac{(P\phi - P\psi \cos\theta) \cos\theta}{I_1 \sin^2\theta}$$

Note: we can compare this to Tong's solution.

$$a = \frac{I_3 \omega_3}{I_1} = \frac{P\phi}{I_1} \quad b = \frac{P\phi}{I_1}$$

$$\boxed{\dot{\psi} = \frac{I_1 a}{I_3} - \frac{(b - a \cos\theta) \cos\theta}{\sin^2\theta}}$$

$$\dot{\phi} = \frac{P\psi}{I_3 \cos\theta} - \frac{1}{\cos\theta} \left(\frac{I_1 a}{I_3} - \frac{(b - a \cos\theta) \cos\theta}{\sin^2\theta} \right)$$

$$= \frac{I_1 a}{I_3 \cos\theta} - \frac{I_1 a}{I_3 \cos\theta} + \frac{(b - a \cos\theta)}{\sin^2\theta}$$

$$\boxed{\dot{\phi} = \frac{b - a \cos\theta}{\sin^2\theta}}$$

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Now recall the equation for E :

$$E = \frac{1}{2} I_1 \dot{\theta}^2 + \frac{1}{2} I_1 \dot{\phi}^2 \sin^2 \theta + \underbrace{\frac{1}{2} I_3 (\dot{\psi} + \dot{\phi} \cos \theta)^2}_{\text{const.}} + Mgl \cos \theta$$

ω_3^2

$$E' = \frac{1}{2} I_1 \dot{\theta}^2 + \frac{1}{2} I_1 \dot{\phi}^2 \sin^2 \theta + Mgl \cos \theta = \text{const.}$$

(can be dropped)

$$\begin{aligned} E' &= \frac{1}{2} I_1 \dot{\theta}^2 + \frac{1}{2} I_1 \sin^2 \theta \left(\frac{b - a \cos \theta}{\sin^2 \theta} \right)^2 + Mgl \cos \theta \\ &= \frac{1}{2} I_1 \dot{\theta}^2 + \frac{1}{2} I_1 \frac{(b - a \cos \theta)^2}{\sin^2 \theta} + Mgl \cos \theta \\ &= \frac{1}{2} I_1 \dot{\theta}^2 + V_{\text{eff}}(\theta) \end{aligned}$$

$$\text{with } V_{\text{eff}}(\theta) = \frac{I_1 (b - a \cos \theta)^2}{2 \sin^2 \theta} + Mgl \cos \theta$$

$$u = \cos \theta$$

$$\dot{u} = -\dot{\theta} \sin \theta \quad \dot{\theta} = -\frac{\dot{u}}{\sin \theta} \quad \dot{\phi}^2 = \frac{\dot{u}^2}{\sin^2 \theta} = \frac{\dot{u}^2}{1-u^2}$$

$$E' = \frac{1}{2} I_1 \frac{\dot{u}^2}{1-u^2} + \frac{I_1 (b - au)^2}{2(1-u^2)} + Mglu$$

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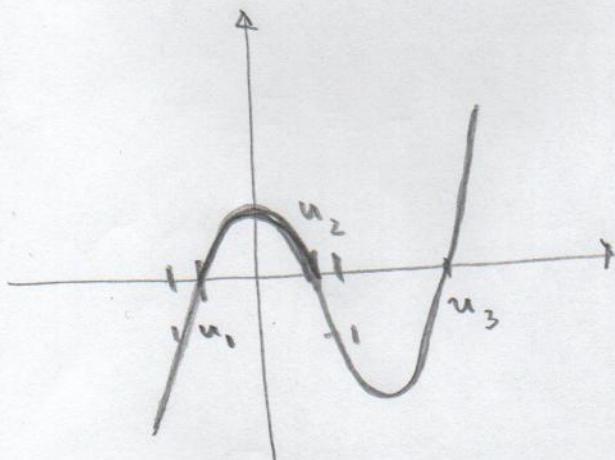
$$\frac{2E'(1-u^2)}{I_1} - (b-au)^2 - \frac{Mglu \cdot 2(1-u^2)}{I_1} = \dot{u}^2$$

$$(1-u^2) \left(\frac{2E'}{I_1} - \frac{2Mgl}{I_1} u \right) - (b-au)^2 = \dot{u}^2$$

$$\dot{u}^2 = (1-u^2)(\alpha - \beta u) - (b-au)^2$$

with $\alpha = \frac{2E'}{I_1}$ and $\beta = \frac{2Mgl}{I_1}$ and $-1 \leq u \leq 1$

$0 \leq \dot{u}^2 = f(u)$ where $f(u)$ is the cubic polynomial above.

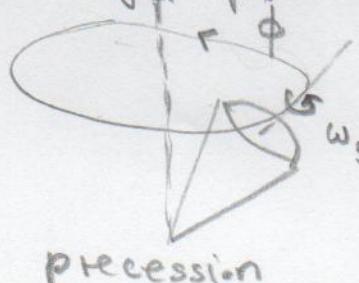


$$f(\pm 1) = -(b-a)^2 < 0$$

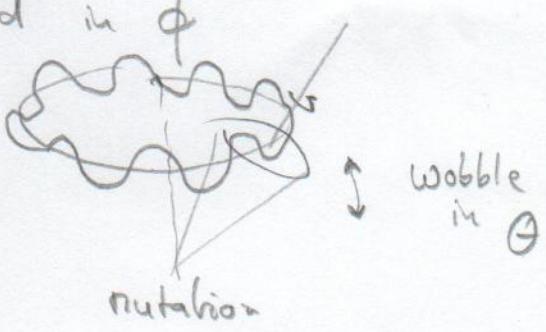
motion between u_1 and u_2
($\dot{u}^2 = f(u)$ needs to be > 0)

If $\dot{\phi} > 0$ at u_1 and u_2

the spinning top moves "forward" in $\dot{\phi}$



needs
"wobble"



nutation

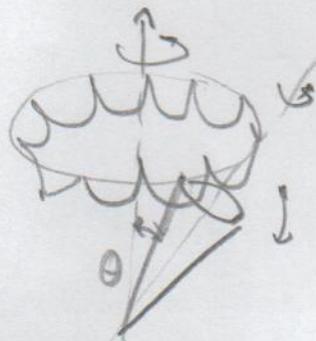
wobble
in θ

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Note that $\dot{\phi} = \frac{b - au}{1 - u^2}$

If $\dot{\phi} > 0$ at $u=u_1$, and $\dot{\phi} = 0$ at $u=u_2$,
we obtain



We can create this motion if we let the top go
at an angle.

$$f(u) = (1-u^2)(\alpha - \beta u) - (b - au)^2$$

Stability of "Sleeping Top"

spin upright, $\theta = 0$ and $\dot{\theta} = 0$. $\ddot{u}^2 = f(u)$

Since $\dot{\theta} = 0$ implies $\dot{u} = 0$, $f(u)$ needs to be zero at
this point. $\theta = 0 \Rightarrow u = \cos \theta = 1$, hence $f(1) = 0$

$$f(1) = -(b-a)^2 = 0 \Rightarrow a = b$$

Also, we had $\alpha = \frac{2E'}{I_1}$ and $\beta = \frac{2Mgl}{I_1}$

$$E' = \frac{1}{2} I_1 \dot{\theta}^2 + \frac{1}{2} I_1 \dot{\phi}^2 \sin^2 \theta + Mgl \cos \theta$$

at $\theta = 0, \dot{\theta} = 0$ we have $E' = Mgl$, hence $\alpha = \beta$

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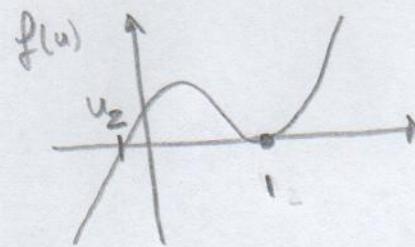
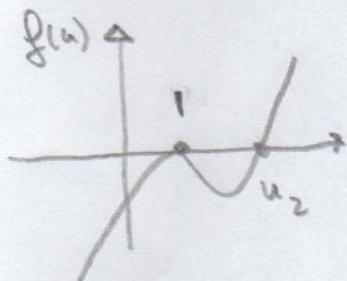
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$$f(u) = \alpha(1-u^2)(1-u) - \alpha^2(1-u)^2$$

$$= (1-u)^2 (\alpha(1+u) - \alpha^2) \text{ so } f \text{ has a}$$

double zero at $u_1 = 1$ and $u_2 = \frac{\alpha^2}{\alpha} - 1$

Now u_2 can be large or smaller u_1 .



$$\alpha = \frac{I_3 \omega_3}{I_1}$$

$$\alpha = \frac{2E}{I_1} = \frac{2Mgl}{I_1} = \beta$$

If $u_2 > 1$, then stable, if $u_2 < 1$ unstable.

$$\frac{\alpha^2}{\alpha} - 1 > 1 \quad \text{or} \quad \frac{\alpha^2}{\alpha} > 2 \quad \frac{I_3^2 \omega_3^2}{I_1^2 \cdot 2Mgl} > 2$$

$$\text{or} \quad \omega_3^2 > \frac{4Mgl I_1}{I_3^2} \quad \text{for stability.}$$