

Relativistic Dynamics

We want to formulate the laws of mechanics in invariant form:

How can we define a 4-vector describing the velocity?

$$\text{Velocity} = \frac{\text{distance}}{\text{time}} \quad d\tau^2 = \frac{ds^2}{c^2} = dt^2 - \frac{1}{c^2} (dx^2 + dy^2 + dz^2)$$

$$d\tau = dt \sqrt{1 - \frac{v^2}{c^2}} \quad \text{is a Lorentz-scalar}$$

(proper time)

4-velocity:

$$u^\mu = \frac{dx^\mu}{d\tau}$$

Check: For $\beta = \frac{v}{c} \rightarrow 0$ we recover the Newtonian limit:

$$u^1 = \frac{dx^1}{d\tau} = \frac{dx}{\sqrt{1 - \frac{v^2}{c^2}} dt} \rightarrow v_x = \frac{dx}{dt} \quad \text{for } \beta \rightarrow 0$$

Note: $u^0 = \frac{dx^0}{d\tau} = \frac{c dt}{\sqrt{1-\beta^2} dt} = \frac{c}{\sqrt{1-\beta^2}}$

4-acceleration: $a^M = \frac{du^M}{d\tau}$

How can we rewrite Newton's law?

We would like $m_0 \frac{du^M}{d\tau} = F^M$ and we need to find the appropriate F^M . Spatial components: $m_0 \frac{du^i}{d\tau} = F^i$

$$\frac{m_0}{\sqrt{1-\beta^2}} \frac{du^i}{dt} = \frac{m_0}{\sqrt{1-\beta^2}} \frac{d}{dt} \left(\frac{dx^i/dt}{\sqrt{1-\beta^2}} \right) = F^i$$

$$m_0 \frac{d}{dt} \left(\frac{1}{\sqrt{1-\beta^2}} \frac{dx^i}{dt} \right) = F^i \sqrt{1-\beta^2} \equiv F_{\text{Newton}}^i$$

$$\Rightarrow (F^1, F^2, F^3) = \frac{1}{\sqrt{1-\beta^2}} \vec{F}_{\text{Newton}}$$

What about the zero-component?

$$m_0 \frac{du^0}{dt} = F^0$$

Note:

$$\frac{d}{dt} (u_\nu u^\nu) = \frac{d}{dt} (\eta_{\mu\nu} u^\mu u^\nu) = 0$$

$$\text{as } \eta_{\mu\nu} u^\mu u^\nu = c^2 \text{ (true in rest frame)}$$

$$\Rightarrow \eta_{\mu\nu} \frac{du^\mu}{dt} u^\nu = 0 \Rightarrow \eta_{\mu\nu} F^\mu u^\nu = 0 \quad \text{or}$$

$$u^0 F^0 - u^1 F^1 - u^2 F^2 - u^3 F^3 = 0$$

$$\frac{c}{\sqrt{1-\beta^2}} F^0 - \frac{\vec{F}_{\text{Newton}} \cdot \vec{v}}{(1-\beta^2)} = 0$$

$$\Rightarrow F^0 = \frac{1}{c} \frac{\vec{F}_{\text{Newton}} \cdot \vec{v}}{\sqrt{1-\beta^2}} \quad \text{Now recall } m_0 \frac{du^0}{dt} = F^0$$

$$\Rightarrow \frac{m_0}{\sqrt{1-\beta^2}} \frac{d}{dt} \left(\frac{c}{\sqrt{1-\beta^2}} \right) = \frac{1}{c} \frac{\vec{F}_{\text{Newton}} \cdot \vec{v}}{\sqrt{1-\beta^2}}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{m_0 c^2}{\sqrt{1-\beta^2}} \right) = \vec{F}_{\text{Newton}} \cdot \vec{v}$$

↑
change of energy

$$\frac{d}{dt} (E) = \vec{F}_{\text{Newton}} \cdot \vec{v} \quad \Rightarrow$$

$$E = \frac{m_0 c^2}{\sqrt{1-\beta^2}} = mc^2$$

$$m = \frac{m_0}{\sqrt{1-\frac{v^2}{c^2}}}$$

Small v : $E = m_0 c^2 \left(1 - \frac{v^2}{c^2} \right)^{-1/2}$

$$\approx m_0 c^2 \left(1 + \frac{1}{2} \frac{v^2}{c^2} \right) = m_0 c^2 + \frac{1}{2} m_0 v^2$$

Relativistic momentum: $\vec{p} = m_0 \gamma \vec{v} = (p^1, p^2, p^3)$

$$p^\mu = m_0 u^\mu \quad p^0 = E/c \quad \left(\frac{m_0 c}{\sqrt{1-\beta}} \text{ for zero-component} \right)$$

$$p_\mu p^\mu = \eta_{\nu\mu} p^\nu p^\mu = \frac{E^2}{c^2} - \vec{p}^2 = \frac{m_0^2 c^4}{c^2}$$

← evaluated in rest frame:
 $p^0 = m_0 c$

Analytical Dynamics

Lecture 13

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⇒

$$E^2 = m_0^2 c^4 + \vec{p}^2 c^2$$

Lagrange function:

$L(\vec{r}, \dot{\vec{r}}, t)$ such that this will reproduce

$$\vec{F}_{\text{Newton}} = \frac{d}{dt} (m \dot{\vec{v}}) = -\nabla U$$

for a potential U .

$$L = -m_0 c^2 \sqrt{1 - \frac{v^2}{c^2}} - U$$

Why? $\frac{\partial L}{\partial r^k} = -\frac{\partial U}{\partial r^k}$, $\vec{r} = (r^1, r^2, r^3) \equiv (x, y, z)$

$$\frac{\partial L}{\partial \dot{r}^k} = \frac{dL}{dv} \frac{\partial v}{\partial \dot{r}^k} =$$
$$v = \sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2}$$

$$\frac{m_0 v}{\sqrt{1 - \frac{v^2}{c^2}}} \cdot \frac{\dot{r}^k}{v} = \frac{m_0 \dot{r}^k}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{m_0 \dot{r}}{\sqrt{1 - \frac{v^2}{c^2}}} \right) = -\frac{\partial U}{\partial r} \quad \text{as desired.}$$

Hamiltonian: $H = \vec{p} \cdot \vec{v} - L$

$$= \gamma (m_0 \dot{x}^2 + m_0 \dot{y}^2 + m_0 \dot{z}^2) + m_0 c^2 \sqrt{1 - \frac{v^2}{c^2}} + U$$

$$\Rightarrow H = \frac{m_0 v^2}{\sqrt{1 - \frac{v^2}{c^2}}} + m_0 c^2 \sqrt{1 - \frac{v^2}{c^2}} + U$$

$$= \frac{m_0 c^2}{\sqrt{1 - \frac{v^2}{c^2}}} + U = c \sqrt{m_0^2 c^2 + \vec{p}^2} + U$$

(last step: $\sqrt{m_0^2 c^2 + m_0^2 \gamma^2 v^2}$)

$$= m_0 c \sqrt{1 + \gamma^2 \frac{v^2}{c^2}} = m_0 c \sqrt{1 + \frac{v^2}{c^2} \frac{1}{1 - \frac{v^2}{c^2}}}$$

$$= m_0 c \sqrt{1 + \frac{v^2}{c^2 - v^2}} = m_0 c \sqrt{\frac{c^2}{c^2 - v^2}} = \frac{m_0 c}{\sqrt{1 - \frac{v^2}{c^2}}}$$

Covariant Formulation:

$$S^{\phi} = \int_{\tau_1}^{\tau_2} \mathcal{L}(x^{\mu}, u^{\mu}, \tau) d\tau$$

no forces: $\frac{d}{d\tau} (m_0 u^{\mu}) = 0$

$$\mathcal{L} = -m_0 c \sqrt{u_{\nu} u^{\nu}} = -m_0 c \sqrt{\eta_{\mu\nu} u^{\mu} u^{\nu}}$$

will yield this result:

$$\frac{\partial \mathcal{L}}{\partial x^{\mu}} = 0 \quad \frac{\partial \mathcal{L}}{\partial u^{\mu}} = \frac{-m_0 c \eta_{\mu\nu} u^{\nu}}{\sqrt{\eta_{\mu\nu} u^{\mu} u^{\nu}}} = -m_0 u_{\mu}$$

$$\Rightarrow \frac{d}{d\tau} (m_0 u_{\mu}) = 0 \quad \Rightarrow \quad \frac{d}{d\tau} (m_0 u^{\mu}) = 0$$

This action gives the correct Newtonian limit.

$$\begin{aligned} \mathcal{L} d\tau &= -m_0 c \sqrt{\eta_{\mu\nu} u^{\mu} u^{\nu}} \frac{d\tau}{dt} dt \\ &= -m_0 c \sqrt{1 - \frac{v^2}{c^2}} dt \approx -m_0 c^2 \left(1 - \frac{v^2}{2c^2}\right) dt \\ &= \left(-m_0 c^2 + \frac{m_0}{2} v^2\right) dt. \end{aligned}$$