

Last time I claimed (min, max) sufficient for Uniform $(0, \theta)$. It is enough with max:

$$L(x|\theta) = \frac{1}{\theta^n} \cdot \mathbb{1}_{(0, \theta)}(\max) \cdot \mathbb{1}_{(0, \theta)}(\min) \quad \text{so } h(\theta) = \mathbb{1}_{(0, \infty)}(\min) \text{ fulfills factorization theorem!}$$

Conditional probability

Recall that the conditional density is defined as

$$f(x|y) = f(x, y) / f(y) \quad P(x|y) = P(x, y) / P(y).$$

We define

$$E[g(X) | Y=y] = \int_{-\infty}^{\infty} g(x) f(x|y) dx$$

or

$$E[g(X) | Y=y] = \sum_x g(x) P(x|y)$$

We can define a conditional variance:

$$V[X|Y=y] = E[X^2|y] - E[X|y]^2$$

These conditional expectations and variances have properties important for our next major result.

Theorem $E X = E_Y [E[X|Y]]$

Proof
$$\begin{aligned} E_Y [E[X|Y]] &= \int_{-\infty}^{\infty} E[X|Y=y] f(y) dy = \\ &= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x f(x|y) dx \right) f(y) dy = \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x f(x|y) f(y) dx dy = \\ &= \iint_{-\infty}^{\infty} x f(x,y) dx dy = \\ &= \int_{-\infty}^{\infty} x f(x) dx = E X. \quad \square \end{aligned}$$

Theorem $V X = E_Y [V[X|Y]] + V_Y [E[X|Y]]$

Proof
$$\begin{aligned} E[V(X|Y)] + V[E(X|Y)] &= \\ &= E[E[X^2|Y]] - E[E[X|Y]^2] + E[E[X|Y]^2] - E[E(X|Y)]^2 \\ &= E[E[X^2|Y]] - E[E[X|Y]^2] + E[E[X|Y]^2] - E[E(X|Y)]^2 \\ &= E[E[X^2|Y]] - E[E[X|Y]^2] = E[X^2] - E[X]^2 = V X. \quad \square \end{aligned}$$

Our main theorem today helps us find best possible unbiased estimators.

Theorem (Rao-Blackwell)

Let $\hat{\theta}$ be unbiased for θ w finite variance.

If u is a sufficient statistic for θ , define $\hat{\theta}^* = E[\hat{\theta} | u]$.

Then, for all θ :

$$E[\hat{\theta}^*] = \theta \text{ and } V(\hat{\theta}^*) \leq V(\hat{\theta}).$$

Proof

First, we observe that by sufficiency, $\hat{\theta}^*$ does not depend on θ , so $\hat{\theta}^*$ is a statistic.

Next, observe $E\hat{\theta}^* = E_u[E[\hat{\theta} | u]] = E\hat{\theta} = \theta$.

$$\begin{aligned} \text{Furthermore } V[\hat{\theta}] &= V[E[\hat{\theta} | u]] + E[V[\hat{\theta} | u]] = \\ &= V\hat{\theta}^* + E[V[\hat{\theta} | u]] \geq V\hat{\theta}^*. \quad \square \end{aligned}$$

We can apply Rao-Blackwell again to $\hat{\theta}^*$, but this is unlikely to improve things; say that our first result was some $h(u)$. Then the next application would produce

$$E[h(u) | u] = h(u).$$

The way to improve is through a new statistic.

Minimal Sufficiency

If T is sufficient for \mathcal{D} and $T = f(T')$ for some other statistic T' , then clearly T' is also sufficient.

An "essential" sufficient statistic would be one that can be generated from every possible sufficient statistic.

Def A sufficient statistic T is minimal if for every other sufficient statistic T' , there is some f such that $T = f(T')$ (almost everywhere)

Theorem Suppose T is sufficient for \mathcal{D} and for datasets x, y :

$$L(x|\mathcal{D}) \propto L(y|\mathcal{D}) \text{ implies } T(x) = T(y)$$

Then T is minimal sufficient

Proof sketch Suppose T' is sufficient. If there is no f st. $f(T') = T$, then there are datasets x, y st. $T'(x) = T'(y)$ and $T(x) \neq T(y)$.

But then

$$L(x|\mathcal{D}) = g'(\mathcal{D}, T'(x)) h'(x) \propto g'(\mathcal{D}, T'(y)) h'(y) = L(y|\mathcal{D})$$

because $T'(x) = T'(y)$ it follows that they differ by a factor $h'(x)/h'(y)$.

By the assumption in the theorem, $T(x) = T(y)$ follows. \square

Lehmann-Scheffé

Pick two points x, y . If the likelihood ratio $\frac{L(x|\mathcal{D})}{L(y|\mathcal{D})}$ is independent of θ if and only if some $g(x) = g(y)$, then g is a minimal sufficient statistic for \mathcal{D} .

Example $Y_1, \dots, Y_n \sim \text{Bernoulli}(p)$ i.i.d.

$$L(Y|p) = \left(\frac{p}{1-p}\right)^{\sum Y_i} \cdot (1-p)^n$$

$$\text{so } \frac{L(x|p)}{L(y|p)} = \left(\frac{p}{1-p}\right)^{\sum x_i - \sum y_i}$$

p vanishes from this ratio exactly when $\sum x_i - \sum y_i = 0$.

Completeness

A statistic U is complete for \mathcal{D} if

$$E[f(U)] = 0 \quad \text{implies} \quad f(U) = 0.$$

Theorem If T is complete and sufficient, then T is minimal sufficient.

Proof Let T' be minimal sufficient. Then there is a function $f(T) = T'$.

Define $g(T') = E[T|T']$. $E[g(T')] = E[T]$ so $E[g(T') - T] = E[g(f(T)) - T] = 0$.

By completeness, $g(T') - T = 0$ so $T = g(T')$ shows that T too is minimal sufficient. \blacksquare

Def An exponential family is full rank if $T(x)$ does not have linear dependencies between entries.

Theorem The sufficient statistic T of a full rank exponential family is complete.

Def A statistic V whose distribution does not depend on θ is called ancillary.

Theorem
(Basu) If T is complete and sufficient, and V is ancillary, then T and V are independent.

Example X_1, \dots, X_n iid $N(\mu, \sigma^2)$, σ^2 known.

$$\mathcal{L}(X|\mu, \sigma^2) = \frac{1}{\underbrace{\sqrt{2\pi\sigma^2}}_A} \exp \left[\underbrace{\frac{n\mu}{\sigma^2} \bar{X}}_T - \underbrace{\frac{n\mu^2}{2\sigma^2}}_A - \underbrace{\frac{1}{2\sigma^2} \sum y_i^2}_B \right]$$

This is a full rank family, so \bar{X} is complete sufficient.

Claim The sample variance is ancillary

Proof Let $Y_i = X_i - \mu$. Then $Y_i \sim N(0, \sigma^2)$.

$\bar{Y} = \bar{X} - \mu$ so $Y_i - \bar{Y} = X_i - \bar{X}$ and it follows that

$$\frac{1}{n-1} \sum (X_i - \bar{X})^2 = \frac{1}{n-1} \sum (Y_i - \bar{Y})^2 \quad \text{and the } Y_i \text{ don't depend on } \mu.$$

Conclusion By Basu's theorem, \bar{X} and S^2 are independent!

Exercise 9.68

If U is complete sufficient for \mathcal{I} .

Claim There is a unique Minimum Variance Unbiased Estimator.

Suppose $g_1(U)$ and $g_2(U)$ are both unbiased.
Then

$$\mathbb{E}[g_1(U) - g_2(U)] = \mathcal{I} - \mathcal{I} = 0$$

so from completeness follows

$$g_1(U) - g_2(U) = 0 \quad \text{ie} \quad g_1(U) = g_2(U) \quad \text{a.e.}$$