

2020-02-03 Parametric Statistics

Core mission: From a population $\{D_{\omega}\}_{\omega \in \Omega}$ find a distribution D_{ω} that best fits some set X_1, \dots, X_n of observations of some random variable X .

Once we have D_{ω} , we can do many things:

- prediction (what are likely new observations?)
- inference (what does ω mean? what does D_{ω} look like?)
- ...

population - the source of the r.v. X . $\{D_{\omega}\}$
parameter - value(s) determining a single dist. for pop.
sample - one set of actual observations X_1, \dots, X_n
statistic - some function of a sample w no use of non-sample values

Example We roll a D6 and note the face up number.
 X : outcome of the dice roll (values in .. ?)
useful model?
pop? param? sample? statistic?

Example 100 coin flips, count heads.

same Qs

What do we mean by best fitting D_0 here?

We want to not be wrong.

For some notion of error, we want the error in guessing $\hat{\theta}$ for a "true" value θ to be low.

Dfn An estimator $\hat{\theta}$ of a parameter θ is some statistic chosen with the ambition for $\hat{\theta}$ to be close to θ in value with high probability

A loss function is some function $L(\hat{\theta}, \theta)$ that measures how wrong the estimate was.

Example - $L(\hat{\theta}, \theta) = |\hat{\theta} - \theta|$ absolute error loss
- $L(\hat{\theta}, \theta) = |\hat{\theta} - \theta|^2$ squared error loss

Since statistics are themselves random-variables, $L(\hat{\theta}, \theta)$ is also a random variable. We might get a high loss even for a good estimator if we are unlucky with our sample.

The risk associated to a loss function L is the expected value $\mathbb{E}L(\hat{\theta}, \theta)$.

The risk can be estimated on a sample as the mean loss value.

In this course we will deal almost exclusively with mean squared error MSE.

Given a sample x_1, \dots, x_n , the mean squared error is

$$MSE(x) = E(\hat{\theta} - \theta)^2$$

For an estimator, there are two fundamentally important descriptors we will talk about here:

$$= E(\hat{\theta} - E\hat{\theta})^2$$

- Variance $V\hat{\theta}$ is the variance of $\hat{\theta}$ as a r.v.

Dfn - Bias $B(\hat{\theta}) = E\hat{\theta} - \theta$ is how away, on average, the estimator is.

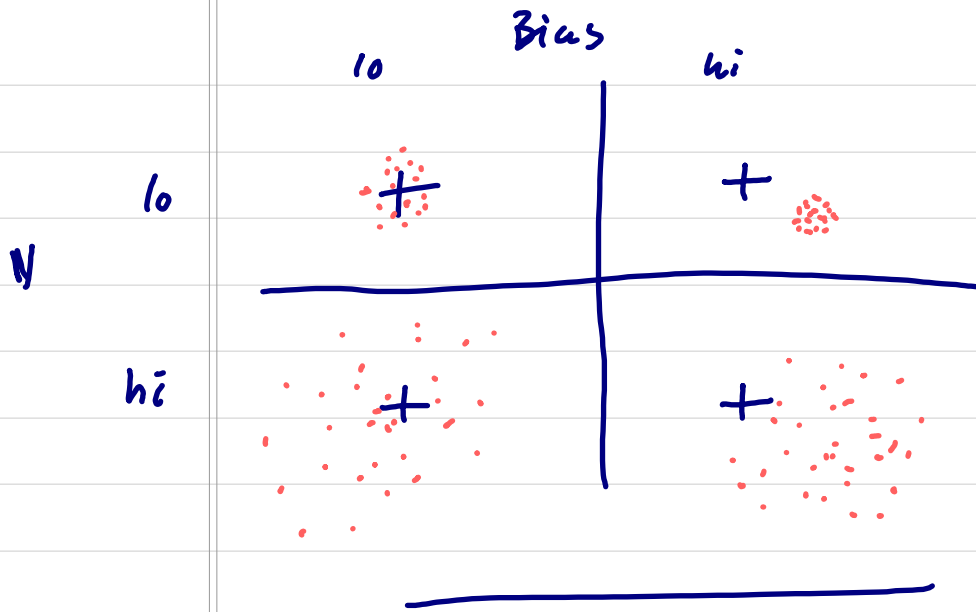
Consider MSE:

$$\begin{aligned} E(\hat{\theta} - \theta)^2 &= E\left((\hat{\theta} - E\hat{\theta}) + (E\hat{\theta} - \theta)\right)^2 = \\ &= E(\hat{\theta} - E\hat{\theta})^2 + E(E\hat{\theta} - \theta)^2 + E\left[2(\hat{\theta} - E\hat{\theta})(E\hat{\theta} - \theta)\right] \\ &= V\hat{\theta} + B(\hat{\theta})^2 + 2(\cancel{E\hat{\theta} - E\hat{\theta}})(\underbrace{E\hat{\theta} - \theta}_{\text{constant}}) \end{aligned}$$

linearity of E

This is the variance/bias decomposition - or var/bias tradeoff.

Dfn If $E(\hat{\theta}) = \theta$ then $\hat{\theta}$ is unbiased.



Side bar to var ex.

$$\mathbb{E}(x^2) = Vx + (\mathbb{E}x)^2.$$

$$\begin{aligned} Vx &= \mathbb{E}(x - \mathbb{E}x)^2 = \\ &= \mathbb{E}(x^2 - 2x\mathbb{E}x + (\mathbb{E}x)^2) = \\ &= \mathbb{E}(x^2) - 2\mathbb{E}x \cdot \mathbb{E}x + (\mathbb{E}x)^2 = \\ &= \mathbb{E}(x^2) - (\mathbb{E}x)^2. \end{aligned}$$

\bar{X} is an estimator of $\mathbb{E}X$
Unbiased?

$$\mathbb{E}\bar{X} = \mathbb{E} \frac{x_1 + \dots + x_n}{N} = \frac{\mathbb{E}x_1 + \dots + \mathbb{E}x_n}{N} \stackrel{\text{iid sample}}{=} \frac{\mathbb{E}x + \dots + \mathbb{E}x}{N} = \mathbb{E}x. \quad \checkmark$$

Variance is $\mathbb{E}(x - \mathbb{E}x)^2$. So should it be estimated as a mean, right?

$$\begin{aligned} \mathbb{E} \sum (x_i - \bar{x})^2 &= \mathbb{E} \left[\sum x_i^2 - 2\bar{x} \sum x_i + n\bar{x}^2 \right] = \\ &= \mathbb{E} \left[\sum x_i^2 - n\bar{x}^2 \right] \stackrel{\text{iid}}{=} n \mathbb{E}[x^2] - n \mathbb{E}[\bar{x}^2] = \end{aligned}$$

$$\begin{aligned} &= n(Vx + (\mathbb{E}x)^2) - n \left(\frac{Vx}{n} + (\mathbb{E}\bar{x})^2 \right) = nVx + n(\mathbb{E}x)^2 - n \frac{Vx}{n} - n(\mathbb{E}x)^2 \\ &= \frac{Vx}{n} - (\mathbb{E}x)^2 \end{aligned}$$

$$= (n-1) Vx.$$

So taking $\frac{1}{n} \sum (x_i - \bar{x})^2$ gives the wrong answer! Biased!

Biased estimators might still have lower MSE sometimes.

Example Toss a coin 100x. Call y the # of heads

$$\hat{p}_1 = y/100$$

$$\hat{p}_2 = (y+3)/106 \quad \text{ie add 3x H and 3xT virtually}$$

Model?

Bias? $B(\hat{p}_1) = E\hat{p}_1 - p = \frac{E y}{100} - p = \frac{100p}{100} - p = 0$ unbiased

$B(\hat{p}_2) = \frac{E y + 3}{106} - p = \frac{100p + 3}{106} - p = \frac{3 - 6p}{106}$ biased

Variance?

$$V\hat{p}_1 = p(1-p)/100$$

$$V\hat{p}_2 = V\left(\frac{y+3}{106}\right) = V\left(\frac{y}{106} + \frac{3}{106}\right) = V\left[\frac{y}{106}\right] = \frac{1}{106^2} V[y] = \frac{100p(1-p)}{106^2}$$

MSE?

$$MSE(\hat{p}_1) = p(1-p)/100$$

$$MSE(\hat{p}_2) = V + B^2 = \frac{1}{106^2} \left(100p(1-p) + (3-6p)^2 \right) = \frac{1}{106^2} \left(100p(1-p) + 9 - 36p + 36p^2 \right) \\ = \frac{1}{106^2} (64p(1-p) + 9)$$

MSEs intersect at $\frac{1}{2} \pm \frac{\sqrt{103/403}}{2}$. \hat{p}_2 lower MSE near $\frac{1}{2}$.

8.8 $Y_1, Y_2, Y_3 \sim \text{Exp}(\theta)$

$$f(y) = \begin{cases} \frac{e^{-y/\theta}}{\theta} & y > 0 \\ 0 & y \leq 0 \end{cases} \quad \begin{array}{l} \text{mean } \theta \\ \text{var } \theta^2 \end{array}$$

$$\hat{\theta}_1 = Y_1 \quad \hat{\theta}_2 = \frac{Y_1 + Y_2}{2} \quad \hat{\theta}_3 = \frac{Y_1 + 2Y_2}{3} \quad \hat{\theta}_4 = \min(Y_1, Y_2, Y_3) \quad \hat{\theta}_5 = \bar{Y}$$

a) biases?

b) among unbiased, which has lowest variance?

$$E\hat{\theta}_1 = \theta \quad E\hat{\theta}_2 = \frac{\theta + \theta}{2} = \theta \quad E\hat{\theta}_3 = \frac{\theta + 2\theta}{3} = \theta \quad E\hat{\theta}_5 = \frac{\theta + \theta + \theta}{3} = \theta$$

§6.7 tells us: $f_{(1)}(y) = n f(y) [1 - F(y)]^{n-1} = 3 \cdot \frac{1}{\theta} \cdot e^{-y/\theta} \cdot e^{-2y/\theta} = \text{Exp}(2\theta/3)$

So $E\hat{\theta}_4 = \frac{\theta}{3} \neq \theta$.

$$V\hat{\theta}_1 = \theta^2 \quad V\hat{\theta}_2 = \frac{1}{4}\theta^2 + \frac{1}{4}\theta^2 = \frac{1}{2}\theta^2 \quad V\hat{\theta}_3 = \frac{1}{9}\theta^2 + \frac{4}{9}\theta^2 = \frac{5}{9}\theta^2$$
$$V\hat{\theta}_5 = \frac{1}{3}\theta^2$$

8.9 Notice this is the exponential dist. again, with scale = $\theta + 1$

So $EY = \theta + 1$, so $\bar{Y} - 1$ might work

8.10 Recall if $Y \sim \text{Poisson}(\lambda)$ then $EY = \lambda$, $Var Y = \lambda$
Notice also:

$$B(\bar{Y}) = ? \quad Var(\bar{Y}) = ?$$

a) We can use \bar{Y} as an unbiased estimator.

b) Recall $Var Y = E[Y^2] - E[Y]^2$ so $E[Y^2] = Var Y + E[Y]^2$.

$$E(3Y + Y^2) = 3E[Y] + Var Y + E[Y]^2 = 3\lambda + \lambda + \lambda^2 = 4\lambda + \lambda^2.$$

c) Maybe $4\bar{Y} + \bar{Y}^2$ works?

8.12 a) $E\bar{Y} = \frac{nEY}{n} = \theta + \frac{1}{2}$ $B(\bar{Y}) = \frac{1}{2}$.

b) $\bar{Y} - \frac{1}{2}$ would work

c) Recall if $X \sim \text{Uniform}(a, b)$ then $Var X = \frac{(b-a)^2}{12}$.

$$MSE = Var \bar{Y} + B(\bar{Y})^2 = \frac{n Var Y}{n^2} + \frac{1}{4} =$$

$$= \frac{(\theta + 1 - \theta)^2}{12n} + \frac{1}{4} = \frac{1 + 3n}{12n}$$

8.13

This estimator is $n\hat{p}\hat{q}$

$$\begin{aligned}
 E[n\hat{p} - n\hat{p}^2] &= E\left[Y - \frac{Y^2}{n}\right] = EY - \frac{1}{n} EY^2 \\
 &= np - \frac{1}{n} (npq + (EY)^2) = np - \frac{1}{n} (npq + n^2 p^2) = np - pq - np^2 = \\
 &= npq - pq = (n-1)pq = \frac{n-1}{n} \cdot npq
 \end{aligned}$$

b) Use $(n-1) \left(\frac{Y}{n}\right) \left(1 - \frac{Y}{n}\right)$.