

Joseph Maher joseph.maher@csi.cuny.edu
 office hours TuTh 1:15 - 2:15pm 4308

<http://www.math.csi.cuny.edu/~maher>

Text: Algebraic Topology, Allen Hatcher.

Hw: every two weeks. Final: take qual.

§2 Homology Introduction/motivation

problem: classify topological spaces up to homeomorphism. ← too hard.
 e.g. all subsets of \mathbb{R}^n .

simpler problem: - look at "nice" topological spaces. Is $\mathbb{R}^n \cong \mathbb{R}^m$ for $n \neq m$?
 - find invariants to help us distinguish different spaces.

example: # of connected components. Functor: $\text{Top} \rightarrow \text{Grp}$
 (path connected)

$$X = \{\text{pt}\} \mapsto 1$$

$$X = \{\text{pt}\} \sqcup \{\text{pt}\} \mapsto 2.$$

slightly fancier: $I = \begin{array}{c} \text{---} \\ \text{S} \\ \text{O} \end{array}$ $I \setminus \text{pt} \rightarrow$ disconnected
 $S' \setminus \text{pt} \cong (0,1)$ connected.

Recall: fundamental group: $\text{Top} \rightarrow \text{Group}$. easy to define,
 $X \mapsto \pi_1(X)$. hard to compute.

Example: $\pi_1(\mathbb{H}) \cong \{1\}$, $\pi_1(S^1) \cong \mathbb{Z}$, $\pi_1(T^2 \cong S^1 \times S^1) = \mathbb{Z} \oplus \mathbb{Z}$, $\pi_1(S^1 \vee S^1) = \mathbb{Z}_2^{< \infty}$.

Problem: $X = \text{simplicial complex} \rightsquigarrow \pi_1(X) \leftarrow \text{presentation } \langle a_1, a_2, \dots, a_n \mid r_1, r_2, \dots, r_e \rangle$

This [unlike] There is no algorithm to decide if a presentation gives the trivial group.

Higher dimensions: $\pi_k(X) : S^k \rightarrow X$, abelian groups, very hard to compute

$\pi_3(S^2) \cong \mathbb{Z}$. $\pi_k(S^n)$ unknown in general.

Homology : Top \rightarrow Abelian groups
 $x \mapsto H_1(x)$ more work to define, better tools
 for calculations.

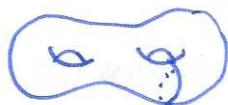
- computable

- generalized to any dimension $H_k(X)$.

Fact $H_0(X) = \text{# connected components} \cdot H_0(\mathbb{R}) \cong \mathbb{Z}$ $H_0(S^1) = \mathbb{Z}$ $H_0(T^2) \cong \mathbb{Z}^2$ $H_0(J_{\infty}) \cong \mathbb{Z}$
 $H_1(X) = \text{ab}(H_1(X)) \cong H_1(\mathbb{R}) \cong 0$ $H_1(S^1) = \mathbb{Z}$ $H_1(T^2) \cong \mathbb{Z}^2$ $H_1(J_{\infty}) \cong \mathbb{Z}$

intuition : $H_n(X) = \frac{\text{"n-dim subsets without boundary"} / \text{"n-dim subsets which}}{\text{bound } (n+1)\text{-dim subsets"}}$
 = "closed sets" / "boundaries".

example :

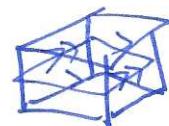


$$\uparrow f_0 \in H_1(X)$$



$$\uparrow = 0 \text{ in } H_1(X)$$

$$T = \sigma^1 x_0 \sigma^1 x_1 \cdot \begin{array}{c} \nearrow \\ \downarrow \\ \nwarrow \end{array}$$



§2 Homology : simplicial homology

Defn(s) An n-simplex is the smallest convex set in \mathbb{R}^m containing $n+1$ points v_0, v_1, \dots, v_n which ~~are in general~~ do not lie in an k -dim subspace for $k < n$. (equivalently, the vectors $v_1 - v_0, v_2 - v_0, \dots, v_n - v_0$ are linearly independent). The points v_i are the vertices of the simplex, which we shall denote $[v_0, v_1, \dots, v_n]$. For the purposes of defining homology groups, we will need to keep track of the order of the vertices, so this is an ordered list. examples $[v_0]$, $[v_0, v_1] \xrightarrow{v_0 \rightarrow v_1} [v_1]$, $v_0 \xrightarrow{v_0 \rightarrow v_1 \rightarrow v_2} [v_0, v_1, v_2]$, $[v_0, v_1, v_2, v_3]$

The standard n-simplex is $\Delta^n = \{ (t_0, t_1, \dots, t_n) \in \mathbb{R}^{n+1} \mid \sum_{i=0}^{n+1} t_i = 1 \}$.
 vertices are $[e_0, e_1, \dots, e_n]$ ei standard basis vectors. and $t_i \geq 0$

Examples :

$$[e_0] \quad \begin{array}{c} \bullet \\ \circ \end{array}$$

$$[e_0, e_1] \quad \begin{array}{c} \bullet \\ \nearrow \\ \circ \end{array}$$

$$[e_0, e_1, e_2] \quad \begin{array}{c} \bullet \\ \nearrow \\ \circ \end{array}$$

Remark all n-dimensional simplices are homeomorphic.

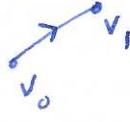
There is a ^{canonical} map from the standard n -simplex to any n -simplex given by ③

$$(t_0, t_1, \dots, t_n) \mapsto t_0 v_0 + t_1 v_1 + \dots + t_n v_n$$

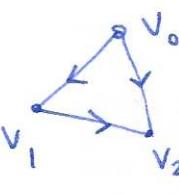
The coefficients t_i are called barycentric coordinates on $[v_0, v_1, \dots, v_n]$.

A face of an n -simplex is the k -simplex corresponding to a subset of $\{v_0, v_1, \dots, v_n\}$. We include the full n -simplex as a face.

convention: we will always give the vertices of a face the order arising from the original simplex.

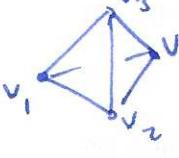
examples $[v_0, v_1]$  faces $[v_0], [v_1], [v_0, v_1]$.

$[v_1, v_0]$ 

$[v_0, v_1, v_2]$  faces $[v_0], [v_1], [v_2]$

$[v_0, v_1] [v_1, v_2] [v_0, v_3]$

$[v_0, v_1, v_2]$

$[v_0, v_1, v_2, v_3]$  faces $[v_0], [v_1], [v_2], [v_3]$

$[v_0, v_1] [v_0, v_2] [v_0, v_3] [v_1, v_2] [v_1, v_3] [v_2, v_3]$

$[v_0, v_1, v_2] [v_0, v_1, v_3] [v_0, v_2, v_3] [v_1, v_2, v_3]$

$[v_0, v_1, v_2, v_3]$

etc.

quotient of

Defn Δ -complex: a collection of disjoint simplices obtained by identifying a ^{some} collection of their faces by the canonical linear homeomorphisms between them.

More formally: let Δ_α^n be a collection of disjoint simplices.

let F_β be a collection of sets of faces of the Δ_α^n , where each set consist of simplices of the same dimension.

$X =$

take $\coprod \Delta_\alpha^n / \sim$ where \sim : if $f_i = (f_1, f_2, \dots, f_k) \in F_\beta$ then and