

$$x = A^{-1}b = \frac{1}{\det(A)} C^T b. \quad b \text{ in } j\text{-th-column} \quad (57)$$

Cramer's rule $x = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} \quad x_i = \frac{\det B_j}{\det A} \quad B_j = \begin{bmatrix} a_{11} & a_{12} & \dots & \overset{b_i}{\check{b}} & a_{1n} \\ \vdots & & & & \vdots \\ a_{m1} & a_{m2} & \dots & b_m & a_{mn} \end{bmatrix}$

Proof expand along row j. \square .

Note: solutions vary continuously with coeffs in A

problem: errors become large if $\det(A)$ close to zero.

Eigenvalues and eigenvectors

Example $A: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$

Q: what about $A = \begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix}$? ?
how do we understand this geometrically?

Note: $\begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} f_1$
 $\begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} f_2$ $\rightarrow 2f_1 + f_2$,

Observation $F = \{f_1, f_2\} = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^2 , so we can write any vector $x = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ then $Ax = c_1 A \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 A \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

i.e. $x = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}_F \quad [Ax]_F = \begin{bmatrix} 2c_1 \\ c_2 \end{bmatrix} \quad \therefore A_F = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$

Defn An eigenvector for A is a vector v such that $Av = \lambda v$
 λ is called the eigenvalue for v ($v \neq 0$, but $\lambda = 0$ is ok)

Example $\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ eigenvectors $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \end{bmatrix}$
 eigenvalues $2 \quad 1$

$\begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix}$ eigenvector $\begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ ? \end{bmatrix}$
 eigenvalues $2 \quad 1$

How to find eigenvectors and eigenvalues

$$Av = \lambda v = \lambda Iv \Leftrightarrow Av - \lambda I v = 0 \Leftrightarrow \underbrace{(A - \lambda I)}_{n \times n \text{ matrix}} v = 0$$

v lies in nullspace / kernel of $A - \lambda I$

recall: $\dim(\text{null}(A - \lambda I)) > 0 \Leftrightarrow \det(A - \lambda I) = 0$

Defn $\det(A - \lambda I)$ is called the characteristic equation for A .

to find eigenvalues, solve $\det(A - \lambda I) = 0$

example $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 0 \\ 0 & 1-\lambda \end{vmatrix} = (2-\lambda)(1-\lambda) = 0$
 $\lambda = 2, 1$

$$A = \begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} 3-\lambda & -1 \\ 2 & -\lambda \end{vmatrix} = (3-\lambda)(-\lambda) + 2 = \lambda^2 - 3\lambda + 2 = (\lambda-2)(\lambda-1) = 0$$

Note: A $n \times n$, $\det(A - \lambda I)$ is degree n polynomial, $\lambda = 2, 1$.
 so n solutions (counting with multiplicity)

Once you've found the eigenvalues, you can find the eigenvectors.

example $\begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix} \quad \lambda = 1$: solve $(A - I)x = 0$ row
 $\begin{bmatrix} 3-1 & -1 \\ 2 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & -1 \\ 2 & -1 \end{bmatrix} \xrightarrow{\text{R2}} \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix}$
 $2x_1 - t = 0 \quad x_1 = t/2 \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = t \begin{bmatrix} 1/2 \\ 1 \end{bmatrix} = t \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ↑ free var t

$\lambda = 2$: solve $(A - 2I)x = 0$ $\begin{bmatrix} 2-2 & -1 \\ 2 & 0-2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 2 & -2 \end{bmatrix}$ row
R2 $\xrightarrow{\text{R2}} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$
 $x_1 - t = 0 \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ↑ free var t

summary $A = \begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix}$ has eigenvalues $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 2 \end{bmatrix}$
 with eigenvectors $\begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

Observation: if v is an eigenvector, so is any multiple of v $A(cv) = cAv$ (59)
 $= \lambda c v = \lambda(v)$

• $\dim(\text{null}(A - \lambda I))$ may be > 1

Example $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ eigenvalues 1, 2 $\lambda=1$ has eigenvectors $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$
 $\lambda=2$ has eigenvectors $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

Special case upper triangular matrices

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} \quad A - \lambda I = \begin{bmatrix} 1-\lambda & 2 & 3 \\ 0 & 4-\lambda & 5 \\ 0 & 0 & 6-\lambda \end{bmatrix} \quad \det(A - \lambda I) = (1-\lambda)(4-\lambda)(6-\lambda)$$

so eigenvalues are diagonal elements.

useful facts • $\det(A) = \text{product of eigenvalues } \lambda_1 \lambda_2 \dots \lambda_n$

• $\text{trace}(A) = a_{11} + a_{22} + \dots + a_{nn} = \lambda_1 + \lambda_2 + \dots + \lambda_n$ sum of eigenvalues.

warning: row operations do not preserve eigenvalues!

Example $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \leftarrow \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$

$$\chi_A = \lambda^2 \quad \chi_A = \lambda(\lambda-1) \quad \leftarrow \text{different!}$$

Example $\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \quad \begin{vmatrix} 2-\lambda & 1 \\ 1 & 1-\lambda \end{vmatrix} = (2-\lambda)(1-\lambda) - 1 = \lambda^2 - 3\lambda + 1$

$$\lambda = \frac{3 \pm \sqrt{9-4}}{2} = \frac{3 \pm \sqrt{5}}{2}$$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0 \quad \lambda = \pm i$$

find eigenvectors: $\begin{bmatrix} -i & 1 \\ 1 & -i \end{bmatrix} \rightarrow \begin{bmatrix} -i & -1 \\ 0 & 0 \end{bmatrix} \quad v = t \begin{bmatrix} 1 \\ -i \end{bmatrix}$ check
 $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -i \end{bmatrix} = \begin{bmatrix} i \\ -1 \end{bmatrix} = i \begin{bmatrix} 1 \\ -i \end{bmatrix}$

Diagonalization
Example $\begin{bmatrix} 5 & 3 \\ -6 & -4 \end{bmatrix}$ has eigenvalues 2, -1
with eigenvectors $\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.

$$\begin{array}{ccc} \mathbb{R}^2 & \xrightarrow{A_E} & \mathbb{R}^2 \\ E & \xrightarrow{\begin{bmatrix} 5 & 3 \\ -6 & 4 \end{bmatrix}} & E \\ S \uparrow & & \uparrow S \\ \mathbb{R}^2 & \xrightarrow{A_F} & \mathbb{R}^2 \\ F & & F \end{array}$$

$$E = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \quad F = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \end{bmatrix} \right\}$$

Q: what is matrix for A wrt basis F ?

$$\underline{A}: \quad A \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad \text{so } A_F = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}$$

$$A \begin{bmatrix} -1 \\ 2 \end{bmatrix} = -1 \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\text{let } S \text{ be the change of basis matrix from } F \text{ to } E, \text{ so } S = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$$

i.e. S is the matrix of eigenvectors (if there are enough eigenvectors!)

$$\text{then } A_F = S^{-1} A_E S \text{ check: } \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5 & 3 \\ -6 & 4 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \leftarrow \text{diagonal matrix of eigenvalues!}$$

In general suppose A has n linearly independent eigenvectors v_1, \dots, v_n with eigenvalues $\lambda_1, \dots, \lambda_n$. Let $S = [v_1 \ v_2 \ \dots \ v_n]$

$$\text{then } S^{-1} A S = \boxed{\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}}$$

equivalently $A = S \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} S^{-1}$

Remarks (1) if all eigenvalues $\lambda_1, \dots, \lambda_n$ are distinct, then their eigenvectors v_1, \dots, v_n are independent.

(2) S is not unique.

(3) not all matrices have n independent eigenvectors.

problem: repeated eigenvalues.

$$\underline{\text{Example}} \quad \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad \lambda_1 = \lambda_2 = 0 \quad \det(A - \lambda I) = \begin{vmatrix} -\lambda & 1 \\ 0 & \lambda \end{vmatrix} = \lambda^2 = 0.$$

$$\text{but } \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow x_2 = 0, \text{ so solutions are } t \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

only 1 eigenvector

Defn the algebraic multiplicity of an eigenvalue is the pwr of $(\lambda - \lambda_i)$ in $\det(A - \lambda_i I) = 0$

the geometric multiplicity is $\dim(\text{null}(A - \lambda_i I))$

note: geometric multiplicity \leq algebraic multiplicity

\Leftrightarrow not diagonalizable.

Example $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ not diagonalizable. $D = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ but $s D s^{-1} = 0$
 $\Rightarrow A = 0$.

Example $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ not diagonalizable. $\lambda_1 = \lambda_2 = 1$ $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$D = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, but then $s D s^{-1} = I \neq A$

Lemma Eigenvectors corresponding to distinct eigenvalues are independent

Proof (2x2 case) Let v_1 have eigenvalue λ_1 $A v_1 = \lambda_1 v_1$
 v_2 have eigenvalue λ_2 $A v_2 = \lambda_2 v_2$

suppose (1) $c_1 v_1 + c_2 v_2 = 0$, then $A(c_1 v_1 + c_2 v_2) = 0$

$$(1) (AV \in S) (\exists V \in B)(AV = 0) \Rightarrow c_1 A v_1 + c_2 A v_2 = 0$$

$$(P) (\exists V \in B)(\forall v \in V)(v \in S)$$

$$(2) (AV \in S) (\exists V \in B)(\forall v \in V)(v \in S) \Rightarrow \lambda_1 c_1 v_1 + \lambda_2 c_2 v_2 = 0 \quad (2)$$

$$\lambda_1(1) - (2) : \lambda_1 c_2 - \lambda_2 c_2 v_2 = \underbrace{(\lambda_1 - \lambda_2)}_{\neq 0} c_2 v_2 = 0 \Rightarrow c_2 = 0$$

$$(2) - \lambda_2(1) : c_1(\lambda_1 - \lambda_2) v_1 = 0 \Rightarrow c_1 = 0 \Rightarrow \text{linearly indep. } \square.$$

examples (1) projection matrix: $A = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$ eigenvalues $(\frac{1}{2} - \lambda)^2 - \frac{1}{4} = 0$

eigenvalues: $\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \end{bmatrix}$

$$\lambda^2 - \lambda = 0$$

$$\lambda(\lambda - 1) = 0 \Rightarrow \lambda = 0, 1$$

(2) rotation: $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ $\det(A - \lambda I) = (-\lambda)^2 + 1 = 0 \Rightarrow \lambda = \pm i$

eigenvectors $\begin{bmatrix} 1 \\ i \end{bmatrix}, \begin{bmatrix} 1 \\ -i \end{bmatrix}$ check $s^{-1} A s = D$!