

$$T: V \rightarrow W$$

column vector notation

choose a basis B_V $v_1, \dots, v_n$ for V
 B_W $w_1, \dots, w_m$ for W

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}_{B_V} = x_1 v_1 + x_2 v_2 + \dots + x_n v_n$$

$$\begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}$$

then $T(v_i) \in W$, so $T(v_1) = a_{11} w_1 + a_{21} w_2 + \dots + a_{m1} w_m$
 $T(v_2) = a_{12} w_1 + a_{22} w_2 + \dots + a_{m2} w_m$
 $\vdots$
 $T(v_n) = a_{1n} w_1 + a_{2n} w_2 + \dots + a_{mn} w_m$

let $v \in V$ be a vector. Then $v = x_1 v_1 + x_2 v_2 + \dots + x_n v_n = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$
 $T(v) = T(x_1 v_1 + \dots + x_n v_n)$
 $= T(x_1 v_1) + \dots + T(x_n v_n)$
 $= x_1 T(v_1) + \dots + x_n T(v_n)$
 $= x_1 \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} + x_2 \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix} + \dots + x_n \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$

so let A be the matrix $\begin{bmatrix} a_{ij} \end{bmatrix} \sim (A)_{ij} = a_{ij}$

then $T(v) = Ax \sim T: V \rightarrow W$
 $v \mapsto T(v)$

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}_{B_V} \mapsto \underbrace{\begin{bmatrix} A \end{bmatrix}}_{m \times n} \underbrace{\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}}_{n \times 1} \leftarrow \text{in basis } B_W$$

claim knowing values of T on a basis determines T .

Proof $v \in V$, then $v = x_1 v_1 + x_2 v_2 + \dots + x_n v_n$ uniquely.

so $T(v) = x_1 T(v_1) + \dots + x_n T(v_n) \quad \square$

Example $P_n =$ degree n polynomials.

P_n standard basis $\{t^n, t^{n-1}, \dots, t_1\}$

integration (with additive constant 0)

$$P^n \rightarrow P^{n+1}$$

$$p(t) \mapsto \int p(t) dt + C$$

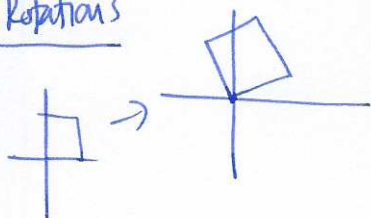
special case $I: P^2 \rightarrow P^3$:

$$I = \begin{bmatrix} 1/3 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$a_n t^n + a_{n-1} t^{n-1} + \dots + a_1 t + a_0 \mapsto \frac{a_n t^{n+1}}{n+1} + \frac{a_{n-1} t^n}{n} + \dots + \frac{a_1 t^2}{2} + a_0 t$$

$$a_2 t^2 + a_1 t + a_0 \mapsto \frac{a_2 t^3}{3} + \frac{a_1 t^2}{2} + a_0 t + C$$

Rotations



$$R_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

note $R_\phi \circ R_\theta$ should be $R_{\phi+\theta}$ check:

$$\begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} \cos \phi \cos \theta - \sin \phi \sin \theta & -\cos \phi \sin \theta - \sin \phi \cos \theta \\ \sin \phi \cos \theta + \cos \phi \sin \theta & -\sin \phi \sin \theta + \cos \phi \cos \theta \end{bmatrix}$$

trig addition formulae:

$$= \begin{bmatrix} \cos(\phi+\theta) & -\sin(\phi+\theta) \\ \sin(\phi+\theta) & \cos(\phi+\theta) \end{bmatrix}$$

General fact

$$U \xrightarrow{S} V \xrightarrow{T} W \quad \text{linear maps}$$

$$u \mapsto s(u) \mapsto t(s(u))$$

pick bases

$$\{u_1, \dots, u_n\} \quad \{v_1, \dots, v_m\} \quad \{w_1, \dots, w_n\}$$

then

$$S \leftrightarrow A_{m \times n} \quad T \leftrightarrow B_{n \times m}$$

$$x \mapsto s(x) \mapsto t(s(x))$$

$$l \times 1 \quad \underbrace{A_{m \times n} \quad l \times 1}_{m \times 1} \mapsto \underbrace{B_{n \times m} \quad l \times 1}_{n \times 1}$$

Fact composition of linear functions corresponds to matrix multiplication.