

Math 338 Linear Algebra Spring 22 Midterm 2a

Name: Solutions

- I will count your best 8 of the following 10 questions.
- You may use a calculator without symbolic algebra capabilities, and a 3×5 index card of notes.

1	20	
2	10	
3	10	
4	10	
5	10	
6	10	
7	10	
8	10	
9	10	
10	10	
	80	

Midterm 2	
Overall	

(1) Consider the matrix A with LU factorization: $A = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} \textcircled{1} & -1 & 0 & 1 \\ 0 & 0 & \textcircled{1} & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

s t
 \downarrow \downarrow

- (a) The matrix A determines a map $x \mapsto Ax$ from \mathbb{R}^a to \mathbb{R}^b . What are a and b ?
- (b) Find all solutions to the equation $Ax = 0$.

a) $a = 4$ $b = 3$.

b) $x_4 = t$
 $x_3 + x_4 = 0$

$x_3 = -t$

$x_2 = s$

$x_1 - x_2 + x_4 = 0$

$x_1 = s - t$

$\left\{ \begin{bmatrix} s-t \\ s \\ -t \\ t \end{bmatrix} \right\} = \left\{ s \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ -1 \\ 1 \end{bmatrix} \right\}.$

(2) Consider the equation $Ax = b$, where $A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & -1 & 3 \\ 3 & -2 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 1 \\ 0 \\ c \end{bmatrix}$. Find all possible solutions for all values of c .

$$\begin{bmatrix} 1 & -1 & 2 & 1 \\ 1 & -1 & 3 & 0 \\ 3 & -2 & 4 & c \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 2 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 1 & -2 & c-3 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -1 & 2 & 1 \\ 0 & 1 & -2 & c-3 \\ 0 & 0 & 1 & -1 \end{bmatrix} \quad \text{unique solution for all values of } c$$

$$x_3 = -1$$

$$x_2 - 2x_3 = c - 3$$

$$x_2 = c - 5$$

$$x_1 - x_2 + 2x_3 = 1$$

$$x_1 - c + 5 - 2 = 1$$

$$x_1 = -2 + c$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2+c \\ -5+c \\ -1 \end{bmatrix}$$

(3) Let S be the following set of vectors.

$$S = \left\{ \begin{bmatrix} 3 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix} \right\}.$$

- (a) Find a subset of S which is a basis for the span of S .
 (b) Do the vectors in S span \mathbb{R}^3 ?

$$\begin{bmatrix} 3 & 1 & 2 & 1 \\ 2 & 1 & 1 & 0 \\ 3 & -1 & 3 & 4 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 3 & 1 & 2 & 1 \\ & & & \\ & & & \\ & & & \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 2 & 1 \\ 1 & 2 & 1 & 0 \\ -1 & 3 & 3 & 4 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 3 & 2 & 1 \\ 0 & -1 & -1 & -1 \\ 0 & 6 & 5 & 5 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 3 & 2 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

a) $\left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} \right\}$

b) yes.

- (4) (a) Write down a basis for \mathbb{R}^4 .
(b) Write down a spanning set for \mathbb{R}^4 which is not a basis.
(c) Write down a linearly independent set in \mathbb{R}^4 which is not a basis.

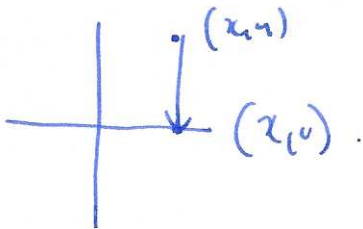
a) $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$

b) $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}.$

c) $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}.$

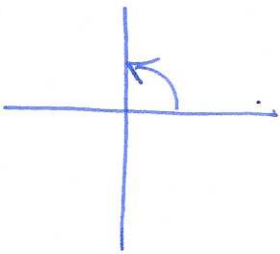
- (5) (a) Write down a 2×2 matrix giving projection onto the x -axis.
 (b) Write down a 2×2 matrix corresponding to a rotation by $\pi/2$.
 (c) Use your answers to (a) and (b) to write down a product of matrices which gives projection onto the y -axis.

a)



$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ 0 \end{bmatrix}.$$

b)



$$R_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad \theta = \frac{\pi}{2} \quad R = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

c)

$$R A R^{-1} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}.$$

(6) Use the Gram-Schmidt algorithm to find an orthonormal basis for \mathbb{R}^3 , starting

with the basis $\left\{ \underset{v_1}{\begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}}, \underset{v_2}{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}, \underset{v_3}{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}} \right\}.$

$$q_1 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$q'_2 = v_2 - (q_1 \cdot v_2) q_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - (1) \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$q_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

$$q'_3 = v_3 - (q_1 \cdot v_3) q_1 - (q_2 \cdot v_3) q_2$$

$$= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - 3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{2}} 3 \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} - \frac{3}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1/2 \\ 0 \end{bmatrix}$$

$$q_3 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}.$$

(7) Let $v = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$ be a vector in \mathbb{R}^3 .

(a) Show that the set of all vectors perpendicular to v is a vector subspace of \mathbb{R}^3 .

(b) Find a basis for this vector subspace.

a) addition: if $x \cdot v = 0$ and $y \cdot v = 0$ then $(x+y) \cdot v = x \cdot v + y \cdot v = 0$ ✓
 scalar multiplication: if $x \cdot v = 0$ then $(kx) \cdot v = k(x \cdot v) = k \cdot 0 = 0$ ✓.

$$b) \begin{bmatrix} 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

\uparrow \uparrow
 s t

$$x_1 + s - t = 0 \quad x_1 = -s + t$$

$$x_2 = s$$

$$x_3 = t$$

$$\left\{ \begin{bmatrix} -s+t \\ s \\ t \end{bmatrix} \right\} = \left\{ s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

basis for null space / kernel is $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$.

(8) Let $A = \begin{bmatrix} 4 & -3 \\ 6 & -5 \end{bmatrix}$.

- (a) Find the eigenvalues for A .
 (b) Find the eigenvectors for A .

$$\begin{aligned} \text{a) } \begin{vmatrix} 4-\lambda & -3 \\ 6 & -5-\lambda \end{vmatrix} &= -(4-\lambda)(5+\lambda) + 18 \\ &= \lambda^2 + \lambda - 20 + 18 = \lambda^2 + \lambda - 2 \\ &= (\lambda+2)(\lambda-1) \end{aligned}$$

$$\lambda = -2, 1$$

$$\text{b) } \lambda = -2: \begin{bmatrix} 6 & -3 \\ 6 & -3 \end{bmatrix} \sim \begin{bmatrix} 6 & -3 \\ 0 & 0 \end{bmatrix} \quad v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\lambda = 1: \begin{bmatrix} 3 & -3 \\ 6 & -6 \end{bmatrix} \sim \begin{bmatrix} 3 & -3 \\ 0 & 0 \end{bmatrix} \quad v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

$$\begin{array}{ccc}
 \mathbb{R}^2 & \xrightarrow{A} & \mathbb{R}^2 \\
 S \downarrow & & \downarrow S \\
 \mathbb{R}^2 & \xrightarrow{D} & \mathbb{R}^2
 \end{array}$$

- (9) Let $A = \begin{bmatrix} 4 & -3 \\ 6 & -5 \end{bmatrix}$. Use your answer to the previous question to write down a matrix S , and a diagonal matrix D such that $A = S^{-1}DS$. Verify that this is correct.

$$D = \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix} \quad S^{-1} = \begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix} \quad S = -\begin{bmatrix} 1 & -1 \\ -2 & 1 \end{bmatrix}$$

$$S^{-1}DS =$$

$$\begin{bmatrix} 1 & -1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} -2 & -2 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 4 & -3 \\ 6 & -5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 2 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 4 & -3 \\ 6 & -5 \end{bmatrix} \checkmark$$

(10) Let P_3 be the vector space of cubic polynomials.

(a) Write down a basis for P_3 .

(b) Show that the map $T: P_3 \rightarrow P_3$ given by $f(x) \mapsto xf'(x)$ is a linear map.

(c) Write down a matrix for T with respect to the basis in (a).

a) $\{\cancel{t^3}, \cancel{t^2}, \cancel{t}, 1\} \quad \{x^3, x^2, x, 1\}$

b) $\cancel{at^3 + bt^2}$ sums: $f(x) + g(x) \mapsto x(f'(x) + g'(x))$
 $= x f'(x) + x g'(x)$
 $= T(f) + T(g) \quad \checkmark$

constant multiples: $T(kf(x)) = x(kf(x))' = xkf'(x) = k(xf'(x)) = kT(x) \quad \checkmark$

c) $T(ax^3 + bx^2 + cx + d) = x(a \cdot 3x^2 + b \cdot 2x + c) = 3ax^3 + 2bx^2 + cx$

$$\begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 3a \\ 2b \\ c \\ 0 \end{bmatrix}$$