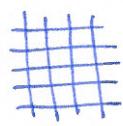


intuition

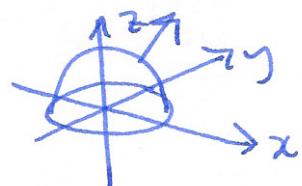
$$\oint_S \underline{F} \cdot d\underline{s} = \iiint_S \text{curl}(\underline{F}) \cdot d\underline{S}$$

divide S into small squares

same calculation as last time

$$\underline{n} = (0, 0, 1)$$

$$(\nabla \times \underline{F}) \cdot \underline{n} = (0, 0, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y}) \quad \square.$$

Example $\underline{F} = \langle -y, 2x, x+z \rangle$ $S = \text{upper hemisphere}$ 

$$\oint_S \underline{F} \cdot d\underline{s} \quad d\theta = (\cos\theta, \sin\theta, 0) \quad 0 \leq \theta \leq 2\pi$$

$$d\theta = (-\sin\theta, \cos\theta, 0)$$

$$= \int_0^{2\pi} \langle -\sin\theta, 2\cos\theta, \cos\theta \rangle \cdot \langle -\sin\theta, \cos\theta, 0 \rangle d\theta$$

$$= \int_0^{2\pi} \sin^2\theta + 2\cos^2\theta d\theta = \int_0^{2\pi} 1 + \cos^2\theta d\theta = 2\pi + \pi = 3\pi.$$

$$\iiint_S \nabla \times \underline{F} \cdot d\underline{S}$$

$$\nabla \times \underline{F} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & 2x & x+z \end{vmatrix} = \langle 0, -1, 2+1 \rangle = \langle 0, -1, 3 \rangle$$

parameterization

$$(\cos\theta \sin\phi, \sin\theta \sin\phi, \cos\phi)$$

$$0 \leq \theta \leq 2\pi$$

$$0 \leq \phi \leq \pi/2$$

$$\frac{\partial \underline{r}}{\partial \theta} = \langle -\sin\theta \sin\phi, \cos\theta \sin\phi, 0 \rangle$$

$$\frac{\partial \underline{r}}{\partial \phi} = \langle \cos\theta \cos\phi, \sin\theta \cos\phi, -\sin\phi \rangle$$

$$\underline{n} = \langle \cos\theta \sin^2\phi, \sin\theta \sin^2\phi, \sin^2\theta \sin\phi \cos\phi + \cos^2\theta \cos\phi \sin\phi \rangle$$

$$= \sin\phi \langle \cos\theta \sin\phi, \sin\theta \sin\phi, \cos\phi \rangle$$

$$\int_0^{\pi/2} \int_0^{2\pi} -\sin\theta \sin\phi + 3 \sin\phi \cos\phi \, d\phi = 3\pi.$$

recall : $\mathbf{F} = \nabla f$ then $\int_{C_1} \mathbf{F} \cdot d\mathbf{s} = \int_{C_2} \mathbf{F} \cdot d\mathbf{s} = f(Q) - f(P)$ (66)

(path independence for gradient vector fields)



Stokes Thm : $\oint_{\partial S} \mathbf{F} \cdot d\mathbf{s} = \iint_S \nabla \times \mathbf{F} \cdot d\mathbf{s}$ note: integral depends only on ∂S not S itself

i.e. surface independence for curl vector fields.



$$\oint_{\partial S} \mathbf{F} \cdot d\mathbf{s} = \iint_{S_1} \nabla \times \mathbf{F} \cdot d\mathbf{s} = \iint_{S_2} \nabla \times \mathbf{F} \cdot d\mathbf{s} \text{ if } \partial S_1 = \partial S_2 .$$

in particular, if S is closed ($\partial S = \emptyset$) then $\iint_S \nabla \times \mathbf{F} \cdot d\mathbf{s} = 0$

$S = S_1 \cup S_2$ with $\partial S_1 = -\partial S_2$ (reversed orientation).

§17.3 Divergence Thm-

recall: we have theorems of the form:

integral of a derivative on a domain = integral over oriented boundary of the domain

FTC : $\int_a^b f'(x) dx = f(b) - f(a)$ $\partial [a, b] = +b - a$

line integrals : $\int_C \nabla f \cdot d\mathbf{s} = f(Q) - f(P)$

Stoke's Thm : $\iint_S \nabla \times \mathbf{F} \cdot d\mathbf{s} = \oint_{\partial S} \mathbf{F} \cdot d\mathbf{s}$

Divergence Thm : $\iiint_W \operatorname{div}(\mathbf{F}) dV = \iint_{\partial W} \mathbf{F} \cdot d\mathbf{s}$ outward pointing normal

Def the divergence of a vector field \mathbf{F} is $\operatorname{div}(\mathbf{F}) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$ $\operatorname{div} \mathbf{F}$ scalar!

$$\underline{\text{useful properties}} : \nabla \cdot (\underline{F} + \underline{G}) = \nabla \cdot \underline{F} + \nabla \cdot \underline{G}$$

$$\nabla \cdot (c\underline{F}) = c \nabla \cdot \underline{F} \quad (c \text{ constant})$$

Example $\underline{F} = \langle x^2+y^2, xyz, e^{xyz} \rangle$

$$\nabla \cdot \underline{F} = 2x + xz + xy e^{xyz}$$

Intuition:  small ball B , so $\nabla \cdot \underline{F}$ approx constant $2B=5$

then flux across $S = \iiint_B \nabla \cdot \underline{F} dV \approx \text{div}(\underline{F}) \text{vol}(B)$

$$\text{flux} \approx \text{divergence} \times \text{vol} \quad (\text{really})$$

- $\text{div}(\underline{F}) > 0$ at a point : fluid flows out "source"

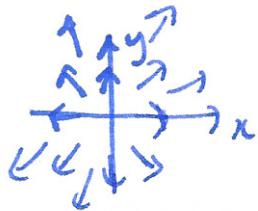


- $\text{div}(\underline{F}) < 0$: fluid flows in "sink"

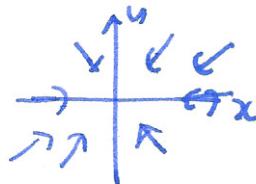


- $\text{div}(\underline{F}) = 0$: no net flow in or out "incompressible flow"

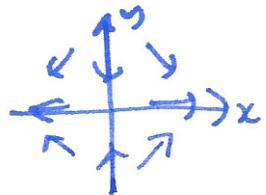
Examples (2)



$$\underline{F} = \langle 2y, x, z \rangle \quad \nabla \cdot \underline{F} = 2$$



$$\underline{F} = \langle -x, y, 0 \rangle \quad \nabla \cdot \underline{F} = -2$$



$$\underline{F} = \langle x, -y, 0 \rangle \quad \nabla \cdot \underline{F} = 0$$

Example (Verify Stoke's)

$$\underline{F} = \langle y, yz, z^2 \rangle \quad S: x^2+y^2=4 \quad 0 \leq z \leq 5$$

$$\nabla \cdot \underline{F} = 0 + z + 2z = 3z$$

$$\iiint_W 3z \, dV = 150\pi \quad (\text{cylindrical})$$