

warning: can only integrate vector fields over orientable surfaces

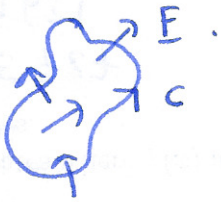
orientable   non-orientable:  Möbius band

Example find $\iint_S \underline{F} \cdot d\underline{s}$ $\underline{F} = \langle 0, 0, x \rangle$
 $S: \Phi(u, v) = (u^2, v, u^3 - v^2)$ $0 \leq u \leq 1$
 $0 \leq v \leq 1$

$\frac{\partial \Phi}{\partial u} = \langle 2u, 0, 3u^2 \rangle$ $\underline{n} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 2u & 0 & 3u^2 \\ 0 & 1 & -2v \end{vmatrix} = \langle -3u^2, 4uv, 2u \rangle$
 $\frac{\partial \Phi}{\partial v} = \langle 0, 1, -2v \rangle$

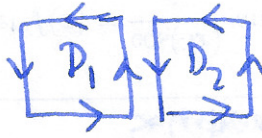
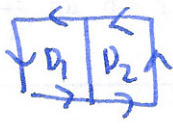
$\iint_S \underline{F} \cdot d\underline{s} = \int_0^1 \int_0^1 \underline{F}(\Phi(u, v)) \cdot \underline{n}(u, v) dv du$
 $= \int_0^1 \int_0^1 \langle 0, 0, u^2 \rangle \cdot \langle -3u^2, 4uv, 2u \rangle dv du = \int_0^1 \int_0^1 2u^3 dv du = \left[\frac{1}{2} u^4 \right]_0^1 = \frac{1}{2}$

§17.1 Green's Theorem

recall: $\oint_C \nabla f \cdot d\underline{s} = 0$  suppose $\underline{F} \neq \nabla f$?

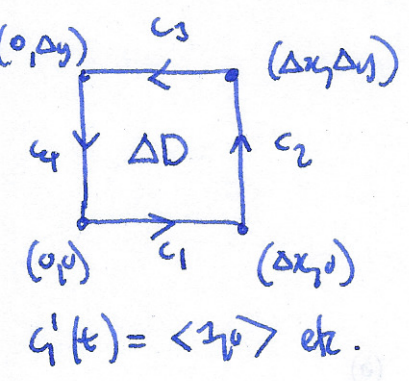
orientation convention:  counter clockwise

Thm (Green's Thm) D domain in $\mathbb{R}^2$ s.t. $\partial D = C$ simple closed curve oriented clockwise, then $\oint_C \underline{F} \cdot d\underline{s} = \iint_D \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} dA$ $\underline{F} = \langle F_1, F_2 \rangle$

intuition  note:  
 $\oint_{\partial D_1} + \oint_{\partial D_2} = \oint_{\partial(D_1 \cup D_2)}$

so suffices to check on a very small square where $\underline{F}$ is almost linear.

$$\underline{F} = \langle px+qy, rx+sy \rangle$$



$$c_1: \int_0^{\Delta x} pt + q \cdot 0 dt = \left[\frac{1}{2} pt^2 \right]_0^{\Delta x} = \frac{1}{2} p \Delta x^2$$

$$c_2: \int_0^{\Delta y} r \Delta x + st dt = \left[r \Delta x t + \frac{1}{2} st^2 \right]_0^{\Delta y} = r \Delta x \Delta y + \frac{1}{2} s \Delta y^2$$

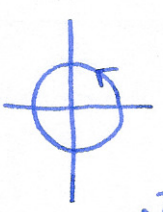
$$c_3: \int_0^{\Delta x} pt + q \Delta y dt = - \left[\frac{1}{2} pt^2 + q \Delta y t \right]_0^{\Delta x} = -\frac{1}{2} p \Delta x^2 - q \Delta x \Delta y$$

$$c_4: \int_0^{\Delta y} r \cdot 0 + st dt = -\frac{1}{2} \left[\frac{1}{2} st^2 \right]_0^{\Delta y} = -\frac{1}{2} s \Delta y^2$$

$$\oint_{\partial \Delta D} \underline{F} \cdot d\underline{s} = r \Delta x \Delta y - q \Delta x \Delta y = (r-q) \Delta A = \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \Delta A$$

$$\oint_D \underline{F} \cdot d\underline{s} = \sum_{ij} (r-q) \Delta A_{ij} = \iint_D \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA \quad \square$$

Example $\oint_C \langle xy^2, x \rangle \cdot d\underline{s}$ $C =$ unit circle oriented counterclockwise



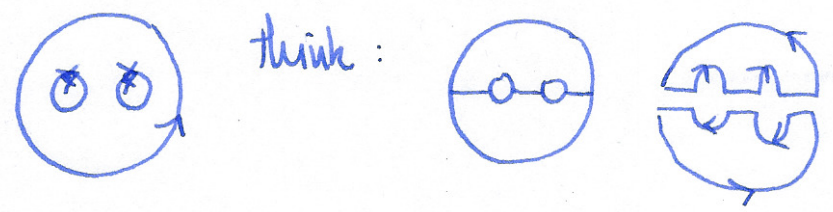
line integral $c(\theta) = (\cos \theta, \sin \theta) \quad 0 \leq \theta \leq 2\pi$
 $c'(\theta) = (-\sin \theta, \cos \theta)$

$$\int_0^{2\pi} \langle \cos \theta \sin^2 \theta, \cos \theta \rangle \cdot \langle -\sin \theta, \cos \theta \rangle d\theta = \int_0^{2\pi} -\cos \theta \sin^3 \theta + \cos^2 \theta d\theta$$

$$= \left[-\frac{1}{4} \sin^4 \theta + \frac{1}{2} \theta + \frac{1}{2} \sin 2\theta \right]_0^{2\pi} = \pi$$

double integral $\iint_D \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} dA = \iint_D \underbrace{1 - 2xy}_{0 \text{ by symmetry}} dA = \iint_D 1 dA = \text{area} = \pi$

multiple boundary components: orient components



§17.2 Stoke's Theorem (3d version of Green's Thm)

Thm $\oint_{\partial S} \underline{F} \cdot d\underline{s} = \iint_S \underbrace{\nabla \times \underline{F}}_{\text{curl}(\underline{F})} \cdot d\underline{s}$

S surface (oriented)
 ∂S boundary (induced orientation)



Remark if S is closed ($\partial S = \emptyset$) then $\oint_{\emptyset} \underline{F} \cdot d\underline{s} = 0$

$\text{curl}(\underline{F}) = \nabla \times \underline{F} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ F_1 & F_2 & F_3 \end{vmatrix} = \left\langle \frac{\partial F_3}{\partial x_2} - \frac{\partial F_2}{\partial x_3}, -\frac{\partial F_3}{\partial x_1} + \frac{\partial F_1}{\partial x_3}, \frac{\partial F_2}{\partial x_1} - \frac{\partial F_1}{\partial x_2} \right\rangle$

↑ vector!
↑ Green's Thm!

Example $\underline{F} = \underline{x} = \langle x, y, z \rangle$ $\nabla \times \underline{F} = \underline{0}$

$\underline{F} = \langle xy, e^x, \frac{y}{z} \rangle$ $\nabla \times \underline{F} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & e^x & \frac{y}{z} \end{vmatrix} = \left\langle \frac{1}{z} - 0, -0 + 0, e^x - x \right\rangle$

intuition what does $\text{curl}(\underline{F})$ measure?



fluid flow: imagine flowing along the vector field
 $\text{curl}(\underline{F}) = (\frac{1}{r})$ angular velocity of a small paddle wheel.

Example $\underline{F} = \langle y, 0, 0 \rangle$ $\nabla \times \underline{F} = \langle 0, 0, 1 \rangle$

