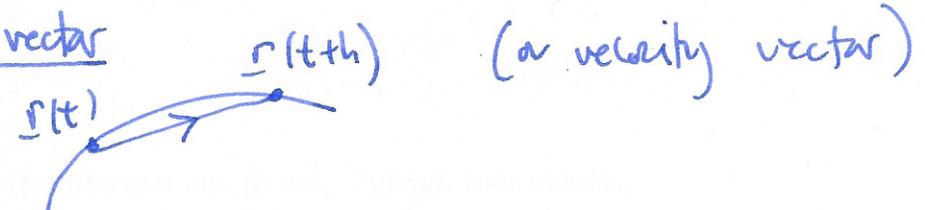


simple example in  $\mathbb{R}^2$ :  $\underline{r}_1(t) \cdot \underline{r}_2(t) = \langle x_1(t), y_1(t) \rangle \cdot \langle x_2(t), y_2(t) \rangle$

$$\begin{aligned}
 (\underline{r}_1(t) \cdot \underline{r}_2(t))' &= (x_1 x_2 + y_1 y_2)' = x_1' x_2 + x_1 x_2' + y_1' y_2 + y_1 y_2' \\
 &= x_1' x_2 + y_1' y_2 + x_1 x_2' + y_1 y_2' = \langle x_1', y_1' \rangle \cdot \langle x_2, y_2 \rangle + \langle x_1, y_1 \rangle \cdot \langle x_2', y_2' \rangle \\
 &= \underline{r}_1'(t) \cdot \underline{r}_2(t) + \underline{r}_1(t) \cdot \underline{r}_2'(t). \quad \square.
 \end{aligned}$$

The derivative is the tangent vector

$$r'(t) = \lim_{h \rightarrow 0} \frac{\underline{r}(t+h) - \underline{r}(t)}{h}$$



tangent line: is given by  $\underline{L}(t) = \underline{r}(t_0) + t \underline{r}'(t_0)$

Example find tangent line to helix  $\underline{r}(t) = \langle \cos t, \sin t, t \rangle$  at  $t=1$ .

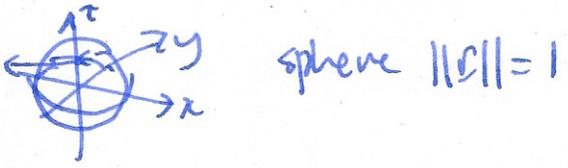
Example show  $\underline{r}(t)$  and  $\underline{r}'(t)$  are orthogonal if  $\underline{r}(t)$  has unit length.

unit length  $\|\underline{r}'(t)\| = 1$   
 $\underline{r}(t) \cdot \underline{r}(t) = 1$

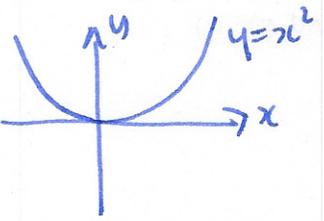
$$\text{so } (\underline{r}(t) \cdot \underline{r}(t))' = \underline{r}'(t) \cdot \underline{r}(t) + \underline{r}(t) \cdot \underline{r}'(t) = 2 \underline{r}'(t) \cdot \underline{r}(t) = 0$$

$$\Rightarrow \underline{r}(t) \perp \underline{r}'(t)$$

geometric interpretation:



Example



$$\begin{aligned}
 \underline{r}(t) &= \langle t, t^2 \rangle \\
 \underline{r}'(t) &= \langle 1, 2t \rangle \quad \text{note } \|\underline{r}'(t)\| \neq 0 \quad \text{in this parameterization}
 \end{aligned}$$

Q:  $\underline{r}(t) = \langle t^3, t^6 \rangle$ ?

Integration

Def: define integration componentwise, i.e.  $\underline{r}(t) = \langle x(t), y(t), z(t) \rangle$

$$\int_a^b \underline{r}(t) dt = \left\langle \int_a^b x(t) dt, \int_a^b y(t) dt, \int_a^b z(t) dt \right\rangle$$

the integral exists if each of the components is integrable.

Example  $\int_0^1 \langle t, e^{2t}, \frac{1}{4x^2} \rangle dt = \langle \int_0^1 t dt, \int_0^1 e^{2t} dt, \int_0^1 \frac{1}{4x^2} dt \rangle$

$\langle [\frac{1}{2}t^2]_0^1, [\frac{1}{2}e^{2t}]_0^1, [\tan^{-1}(x)]_0^1 \rangle = \langle \frac{1}{2}, \frac{1}{2}e^2 - \frac{1}{2}, \tan^{-1}(1) \rangle$

Antiderivatives

Defn An anti-derivative of  $\underline{r}(t)$  is a function  $\underline{R}(t)$  st.  $\underline{R}'(t) = \underline{r}(t)$

Thm 4 Let  $\underline{R}_1(t)$  and  $\underline{R}_2(t)$  be antiderivatives of  $\underline{r}(t)$ , i.e.  $\underline{R}_1'(t) = \underline{R}_2'(t) = \underline{r}(t)$ .

Then  $\underline{R}_1(t) = \underline{R}_2(t) + \underline{c}$   $\underline{c}$  constant vector.

General antiderivative  $\int \underline{r}(t) dt = \underline{R}(t) + \underline{c}$

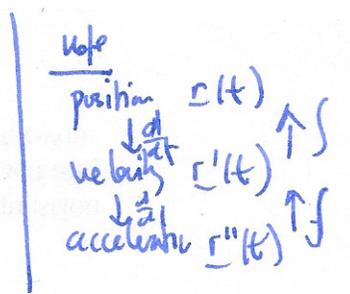
Fundamental theorem of calculus (vector valued version)

$\underline{r}(t)$  continuous on  $[a,b]$  and  $\underline{R}(t)$  an antiderivative of  $\underline{r}(t)$

then  $\int_a^b \underline{r}(t) dt = \underline{R}(b) - \underline{R}(a)$ .

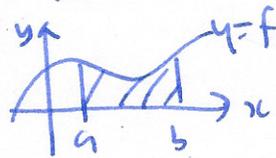
Example A particle moves with velocity  $\underline{r}(t) = \langle t, \sin t \rangle$ . If it starts at  $\langle 1, 1 \rangle$  at  $t=0$ , where is it at  $t=4$ ?

$\int_0^4 \underline{r}(t) dt = \underline{R}(4) - \underline{R}(0)$   $\underline{R}(t) = \langle \frac{1}{2}t^2, -\cos t \rangle$   
 $= \langle 8, -\cos 4 \rangle - \langle 0, -1 \rangle = \langle 8, 1 - \cos 4 \rangle$

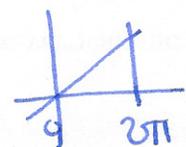
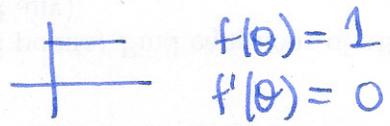
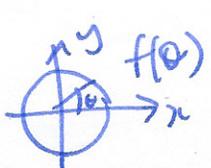


Warning/Motivation

$f: \mathbb{R} \rightarrow \mathbb{R}$   
 $y=f(x)$  has integral  $F(x) = \int_a^x f(x) dx = \text{area under curve}$ .



note this doesn't work for  $f: S^1 \rightarrow \mathbb{R}$  circle



$\int f(\theta) d\theta = 0? = F(\theta)$   
not periodic  $F(0) = 0$   
 $F(2\pi) = 2\pi \neq 0$