

$$(A - 4I) \underline{v}_2 = \underline{v}_1$$

$$\begin{bmatrix} -3 & 3 \\ -3 & 3 \end{bmatrix} \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \left[\begin{array}{cc|c} -3 & 3 & 1 \\ -3 & 3 & 1 \end{array} \right] = \left[\begin{array}{cc|c} x_1 & x_2 & \\ -3 & 3 & 1 \\ 0 & 0 & 0 \end{array} \right] \quad \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} s.$$

homogeneous solution: $\begin{bmatrix} 1 \\ 1 \end{bmatrix} s$

particular solution: $\begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$

$$x_2 = s \\ -3x_1 + 3x_2 = 1 \\ x_1 = s - 1/3. \quad \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} s$$

so $\underline{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} s + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$ just need one, can choose $s=0$, $\underline{v}_2 = \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$.

so 2nd solution is $\begin{bmatrix} 1 \\ 1 \end{bmatrix} t e^{4t} + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix} e^{4t}$

general soln: $c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{4t} + c_2 \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} t e^{4t} + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix} e^{4t} \right)$.

Example $\dot{\mathbf{X}} = A\mathbf{X}$ $A = \begin{bmatrix} -2 & -1 & -5 \\ 25 & 7 & 0 \\ 0 & 1 & 3 \end{bmatrix}$ eigenvalues: $-2, -2, -2$
eigenvector: $\begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix}$.

so one solution is $\begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix} e^{-2t}$ know other solutions contain $t e^{-2t}, t^2 e^{-2t}$.

method: look for second solution of the form $\underline{X}_2 = \underline{v}_1 t e^{-2t} + \underline{v}_2 e^{-2t}$

third $\underline{X}_3 = \frac{1}{2} \underline{v}_1 t^2 e^{-2t} + \underline{v}_2 t e^{-2t} + \underline{v}_3 e^{-2t}$.

plug in \underline{X}_2 : $\dot{\underline{X}}_2 = A\underline{X}_2$

$$\underline{v}_1 \left(e^{-2t} - 2t e^{-2t} \right) + \underline{v}_2 (-2e^{-2t}) = \underbrace{A\underline{v}_1}_{-2\underline{v}_1} t e^{-2t} + A\underline{v}_2 e^{-2t}$$

$$\underline{v}_1 - 2\underline{v}_2 = A\underline{v}_2$$

$$(A+2I)\underline{v}_2 = \underline{v}_1$$

$$\left[\begin{array}{ccc|c} 0 & -1 & -5 & -1 \\ 25 & -5 & 0 & -5 \\ 0 & 1 & 5 & 1 \end{array} \right] \quad \text{homogeneous solution } \begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix}$$

$$\text{particular solution } \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\rightsquigarrow \left[\begin{array}{ccc|c} 5 & -1 & 0 & -1 \\ 0 & 1 & 5 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad \text{general solution } \begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \text{choose } s=0.$$

choose free variable $s=0$

$$x_2 + 0 = 1 \Rightarrow x_2 = 1$$

$$5x_1 - \underline{x_2} + \underline{0x_3} = -1 \quad \Rightarrow x_1 = 0.$$

$$\underline{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{so 2nd solution is } \begin{bmatrix} v_1 \\ -s \\ 1 \end{bmatrix} t e^{-2t} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} e^{-2t}$$

$$\text{now look for } X_3 = \frac{1}{2} \underline{v}_1 t^2 e^{-2t} + \underline{v}_2 t e^{-2t} + \underline{v}_3 e^{-2t}$$

$$\text{plug in to: } \underline{X} = A\underline{X}$$

$$\begin{aligned} & \cancel{\frac{1}{2} \underline{v}_1 (2t e^{-2t} + t^2 \cdot -2e^{-2t})} + \underline{v}_2 (e^{-2t} + t \cdot -2e^{-2t}) + \underline{v}_3 (-2e^{-2t}) \\ &= \underbrace{\frac{1}{2} A \underline{v}_1}_{-2\underline{v}_1} t^2 e^{-2t} + \underbrace{A \underline{v}_2 t e^{-2t}}_{\underline{v}_1 - 2\underline{v}_2} + A \underline{v}_3 e^{-2t} \end{aligned}$$

$$\text{leaves: } e^{-2t} \left[\underline{v}_2 - 2\underline{v}_3 = A \underline{v}_3 \right]$$

$$(A + 2I) \underline{v}_3 = \underline{v}_2$$

$$\left[\begin{array}{ccc|c} 0 & -1 & -5 & 0 \\ 25 & -5 & 0 & 1 \\ 0 & 1 & 5 & 0 \end{array} \right]$$

$$\text{homogeneous solution: } \begin{bmatrix} -1 \\ 5 \\ 1 \end{bmatrix}$$

$$\text{particular solution } \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\therefore \begin{aligned} X_3 &= \frac{1}{2} \begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix} t^2 e^{-2t} \\ &+ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} t e^{-2t} \\ &+ \begin{bmatrix} 425 \\ 0 \\ 0 \end{bmatrix} e^{-2t} \end{aligned}$$

§10.3 Non-homogeneous case

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$$\dot{x} = Ax + g$$

§10.3.1 Variation of parameters.

$$\dot{x} = Ax + g$$

solve $\dot{x} = Ax$, let solution be $\Omega(t) \cdot C$.
fundamental matrix of solutions.

look for a solution $\Psi(t) = \Omega(t) u(t)$
 \uparrow $n \times 1$ vector.

$$\dot{\Psi} = \Omega' u + \Omega u'$$

plug in:

$$\underbrace{\Omega' u + \Omega u'}_{\text{cancel}} = \underbrace{A \Omega u + g}_{A \Omega u + g}$$

$$\begin{aligned}\Omega u' &= 0 & \Omega \text{ invertible as columns}\\ u' &= \Omega^{-1} g & \text{linearly independent!}\end{aligned}$$

$$u(t) = \int \Omega^{-1}(t) g(t) dt$$

general solution: $x(t) = \Omega(t) \cdot C + \Omega(t) u(t)$

Example $\dot{x} = \begin{bmatrix} 1 & -10 \\ -1 & 4 \end{bmatrix} x + \begin{bmatrix} t \\ 1 \end{bmatrix}$ eigenvalues $-1 \quad 6$
eigenvectors $\begin{bmatrix} 5 \\ 1 \end{bmatrix} \quad \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

fundamental matrix $\Omega(t) = \begin{bmatrix} 5e^{-t} & -2e^{+6t} \\ e^{-t} & e^{+6t} \end{bmatrix}$

$$\begin{aligned}u(t) &= \int \Omega^{-1}(t) g(t) dt & \Omega^{-1}(t) &= \frac{1}{5e^{5t} + 2e^{6t}} \begin{bmatrix} e^{6t} & 2e^{6t} \\ -e^{-t} & 5e^{-t} \end{bmatrix} \\ &= \frac{1}{7} \begin{bmatrix} e^t & 2e^t \\ -e^{-6t} & 5e^{-6t} \end{bmatrix}\end{aligned}$$

$$\begin{aligned}
 u(t) &= \int \Sigma^{-1}(t) g(t) dt = \int \frac{1}{7} \begin{bmatrix} e^t & 2e^t \\ -e^{-6t} & 5e^{-6t} \end{bmatrix} \begin{bmatrix} t \\ 1 \end{bmatrix} dt \\
 &= \frac{1}{7} \int \begin{bmatrix} te^t + 2e^t \\ -te^{-6t} + 5e^{-6t} \end{bmatrix} dt = \frac{1}{7} \left[\begin{bmatrix} te^t - \int e^t dt + 2e^t \\ -t - \frac{1}{6}e^{-6t} + \frac{1}{6} \int e^{-6t} dt - \frac{5}{6}e^{-6t} \end{bmatrix} \right] \\
 &= \frac{1}{7} \begin{bmatrix} e^t(t+1) \\ e^{-6t}\left(\frac{t}{6} + \frac{1}{36} - \frac{5}{6}\right) \end{bmatrix} = \frac{1}{7} \begin{bmatrix} e^t(t+1) \\ e^{-6t}\left(-\frac{29}{36}\right) \end{bmatrix}
 \end{aligned}$$

general solution: $\underline{u}(t) \cdot C + \underline{x}_p(t)$

$$\begin{aligned}
 &= \begin{bmatrix} 5e^{-t} & -2e^{+6t} \\ e^{-t} & e^{+6t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} + \frac{1}{7} \begin{bmatrix} e^t(t+1) \\ e^{-6t}\left(-\frac{29}{36}\right) \end{bmatrix} \cdot \begin{bmatrix} 5e^{-t} & -2e^{+6t} \\ e^{-t} & e^{+6t} \end{bmatrix} \frac{1}{7} \begin{bmatrix} e^t(t+1) \\ e^{-6t}\left(-\frac{29}{36}\right) \end{bmatrix} \\
 &\quad + \frac{1}{3} \begin{bmatrix} 17/6 + (49/7)t \\ 1/12 + t/2 \end{bmatrix}.
 \end{aligned}$$

§ 10.2.2 Diagonalization

want to solve $\dot{\underline{X}} = A\underline{X} + \underline{G}$ where $A = PDP^{-1}$

change coordinates: set $\underline{X} = P\underline{Z}$

example $\dot{\underline{X}} = \begin{bmatrix} 3 & 3 \\ 1 & 5 \end{bmatrix} \underline{X} + \begin{bmatrix} 8 \\ 4e^{3t} \end{bmatrix}$ eigenvalues 2, 6
eigenvectors $\begin{bmatrix} -3 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

so $P = \begin{bmatrix} -3 & 1 \\ 1 & 1 \end{bmatrix}$ and $P^{-1}AP = \begin{bmatrix} 2 & 0 \\ 0 & 6 \end{bmatrix}$

set $\underline{X} = P\underline{Z}$ plug in: $\dot{\underline{X}} = P\underline{Z}'$

$$\underline{P}\underline{Z}' = A\underline{P}\underline{Z} + \underline{G}$$

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multiply by P^{-1} : $\bar{P}^{-1}P\bar{z}' = \bar{P}^{-1}APz + \bar{P}^{-1}G$

$$\bar{z}' = Dz + \bar{P}^{-1}G$$

$$\bar{P}^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & 3 \end{bmatrix} \frac{1}{4}$$

i.e. $\begin{bmatrix} z'_1 \\ z'_2 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 6 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + \frac{1}{4} \begin{bmatrix} -1 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 8 \\ 4e^{3t} \end{bmatrix}$

two independent linear first order equations:

$$z'_1 = 2z_1 - 2 + e^{3t}$$

$$z'_2 = 6z_2 + 2 + 3e^{3t}$$

solve: $z_1 = 9e^{2t} + e^{3t} + 1$

$$z_2 = c_2 e^{6t} - e^{3t} - \frac{1}{3}$$

then $X(t) = P\bar{z}(t) = \begin{bmatrix} -3 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} -3 & 1 \\ 1 & 1 \end{bmatrix} \left(\begin{bmatrix} 9e^{2t} \\ c_2 e^{6t} \end{bmatrix} + \begin{bmatrix} e^{3t} + 1 \\ -e^{3t} - \frac{1}{3} \end{bmatrix} \right)$

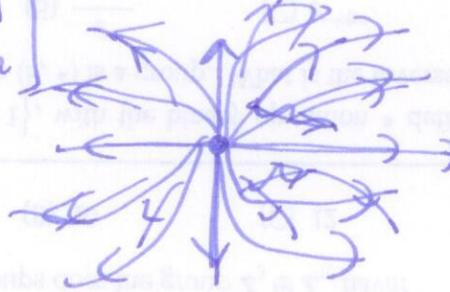
$$= \begin{bmatrix} -3e^{2t} & e^{6t} \\ e^{2t} & e^{6t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} + \begin{bmatrix} -4e^{3t} - 10/3 \\ 2 \end{bmatrix}$$

10.6 Phase portraits

local pictures for solution of $X' = AX$ A constant matrix.

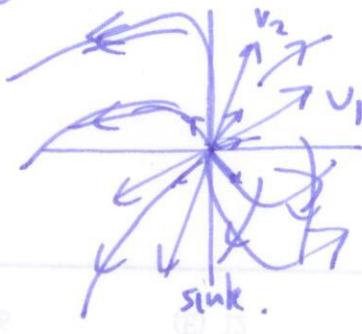
special case $\overset{A}{\cancel{A}} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \quad \lambda_1 = 3 \quad \lambda_2 = 2$

solutions $\begin{bmatrix} e^{3t} & 0 \\ 0 & e^{2t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$

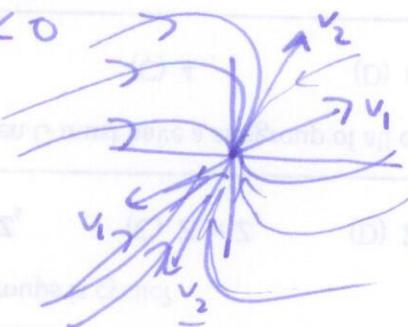


Now space A has positive real eigenvalues $\lambda_1 > \lambda_2 > 0$
 eigenvectors v_1, v_2

$x' = AX$ has general solution $c_1 v_1 e^{\lambda_1 t} + c_2 v_2 e^{\lambda_2 t}$



negative eigenvalues $\lambda_1 < \lambda_2 < 0$
 as above; arrows reversed.

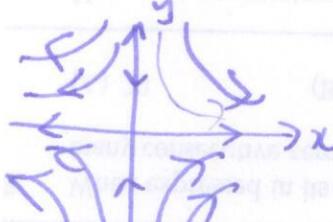


sink.

real eigenvalues opposite sign

$$\lambda_1 < 0 < \lambda_2$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

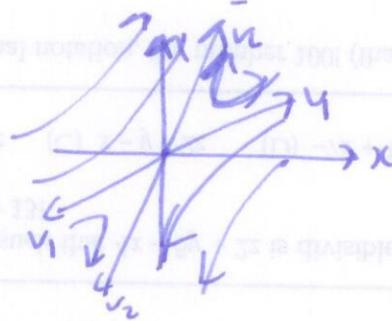


$$\text{st} \begin{bmatrix} c_1 e^t \\ c_2 e^{-t} \end{bmatrix}$$

$$\lambda_1 < 0 < \lambda_2$$

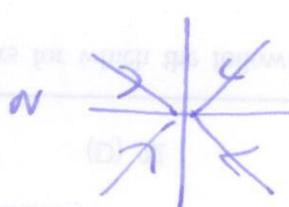
$$v_1 \quad v_2$$

saddle



real eigenvalues equal

① two eigenvectors $\lambda > 0$



$$\lambda > 0$$

$$\lambda < 0$$

② only one eigenvector

$x' = AX$ has general solution $x = c_1 v_1 e^{\lambda t} + (c_2 v_2 + c_3 u) e^{\lambda t}$

$$= c_1 (v_1 t + v_2) e^{\lambda t} + c_3 u e^{\lambda t}$$

