

Warning  $AB \neq BA$  in general

$$AB=0 \Rightarrow A \text{ or } B=0$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

Special matrices

0 zero matrix ( $m \times n$ )

I identity matrix ( $n \times n$ )

$$\begin{bmatrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{bmatrix}$$

Transpose

$$[A^t]_{ij} = [A]_{ji} \quad \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}^t = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^t = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Defn. A linear map  $L: \mathbb{R}^m \rightarrow \mathbb{R}^n$  satisfies  $L(a+b) = L(a) + L(b)$   
 $L(c a) = c L(a)$ .

Fact A linear map may be written as a matrix.

choose a basis  $\{e_1, \dots, e_m\}$  for  $\mathbb{R}^m$

$\{f_1, \dots, f_n\}$  for  $\mathbb{R}^n$

then

$$L(e_1) = a_{11}f_1 + a_{21}f_2 + \dots + a_{n1}f_n$$

$$L(e_2) = a_{12}f_1 + a_{22}f_2 + \dots + a_{n2}f_n$$

$$L(e_m) = a_{1m}f_1 + a_{2m}f_2 + \dots + a_{nm}f_n$$

composition

$$\mathbb{R}^m \xrightarrow{S} \mathbb{R}^n \xrightarrow{T} \mathbb{R}^p$$

$$\underline{x} \mapsto S\underline{x} \mapsto T\underline{x}$$

$\underline{v} \in \mathbb{R}^m$ , then  $\underline{v} = v_1e_1 + v_2e_2 + \dots + v_m e_m$

$$\underline{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix} \text{ in basis } \{e_1, \dots, e_m\}.$$

$$L(\underline{v}) = v_1 L(e_1) + v_2 L(e_2) + \dots + v_m L(e_m)$$

$$= v_1 (a_{11}f_1 + \dots + a_{n1}f_n) + \dots + v_m (a_{1m}f_1 + \dots + a_{nm}f_n)$$

$$= (a_{11}v_1 + a_{21}v_2 + \dots + a_{1m}v_m) f_1 + \dots + (a_{11}v_1 + a_{12}v_2 + \dots + a_{nm}v_n) f_n$$

$$L(\underline{v}) = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & & & \\ \vdots & & & \\ a_{n1} & \dots & \dots & a_{nm} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix} \text{ in basis } \{f_1, \dots, f_n\}.$$

$$\text{wrt } e_i \mapsto \begin{bmatrix} a_{1i} \\ \vdots \\ a_{ni} \end{bmatrix} \text{ first col.}$$

$$e_i \mapsto \begin{bmatrix} a_{1i} \\ \vdots \\ a_{ni} \end{bmatrix} \text{ i-th col}$$

## Geometric action of linear maps

Examples  $A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \quad \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Which transformations are linear?

- reflection in x-axis
- translation by  $(1, 1)$ .
- rotation by  $\theta$  degrees.
- projection to y-axis.

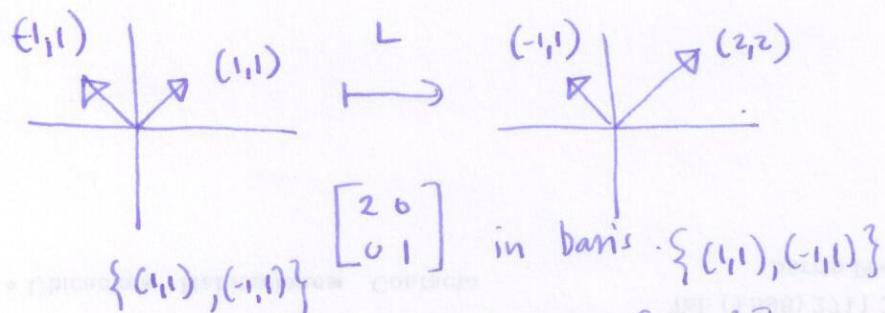
## Determinants for $2 \times 2$ matrices

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc \quad \text{geometric interpretation: change of volume.}$$

Inverses for  $2 \times 2$  matrices  $A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$  as long as  $\det(A) \neq 0$ .

## Change of basis is a linear map

Example:



Q: what is  $L$  wrt to the standard basis  $\{e_1, e_2\}$ ?

$$\begin{array}{ccc} \begin{array}{c} (1,1) \\ (-1,1) \end{array} & \xrightarrow{\quad L \quad} & \begin{array}{c} (1,1) \\ (2,1) \end{array} \\ \{e_1, e_2\} & \xrightarrow{\quad L \quad} & \{e_1, e_2\} \end{array}$$

$$v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = v_1(1,1) + v_2(-1,1) = (v_1 - v_2, v_1 + v_2) = \begin{bmatrix} v_1 - v_2 \\ v_1 + v_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \xrightarrow{\quad L \quad} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \quad \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \xrightarrow{\quad L \quad} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

so change of basis matrix is  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$

$$\begin{array}{ccc} \mathbb{R}_F^2 & \xrightarrow{\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}} & \mathbb{R}_F^2 \\ \xrightarrow{A_F} & & \end{array} \quad \text{so } A_E = T A_F T^{-1}$$

$$\begin{array}{ccc} T & \downarrow & T \\ \mathbb{R}_E^2 & \xrightarrow{A_E} & \mathbb{R}_E^2 \end{array}$$

$$= \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$