

Examplesoverdamped

has solution

$$y'' + 6y' + 5y = 6\sqrt{5} \cos(\sqrt{5}t)$$

$$y(0) = y'(0) = 0$$

$$y(t) = \frac{\sqrt{5}}{4} (-e^{-t} + e^{-5t}) + \sin(\sqrt{5}t)$$

critically damped

$$y'' + 2y' + y = 2\cos(t)$$

$$y(0) = y'(0) = 0$$

$$y(t) = -te^{-t} + \sin(t)$$

underdamped

$$y'' + 2y' + y = 2\sqrt{2} \cos(\sqrt{2}t)$$

$$y(0) = y'(0) = 0$$

$$y(t) = -\sqrt{2} e^{-t} \sin(t) + \sin(\sqrt{2}t)$$

Resonance (spoke $\omega = 0$)

$$y'' + \frac{k}{m} y = \frac{A}{m} \cos(\omega t)$$

 $(\omega_0 \neq \omega)$

general solution: $y(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t) + \frac{A}{m(\omega_0^2 - \omega^2)} \cos(\omega t) \quad (*)$

$$\omega_0 = \sqrt{\frac{k}{m}} \leftarrow \text{called natural frequency.}$$

$$\omega \leftarrow \text{called input frequency.}$$

suppose $\omega_0 = \omega$ (resonant case). $(*)$ not a solution. to $y'' + \frac{k}{m} y = \frac{A}{m} \cos(\omega t)$

$$y_h(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t)$$

try: $y_p(t) = at \cos(\omega_0 t) + bt \sin(\omega_0 t)$

$$y_p'(t) = a \cos(\omega_0 t) - at \sin(\omega_0 t) \omega_0 + b \sin(\omega_0 t) + bt \cos(\omega_0 t) \omega_0$$

$$y_p''(t) = -a \omega_0 \sin(\omega_0 t) - a \omega_0 \sin(\omega_0 t) - a \omega_0^2 t \cos(\omega_0 t) + b \cos(\omega_0 t) \omega_0 + b \cos(\omega_0 t) \omega_0 - b \omega_0^2 t \sin(\omega_0 t).$$

plug in $(*)$:

$$= -2a \omega_0 \sin(\omega_0 t) - a \omega_0^2 t \cos(\omega_0 t) + 2b \omega_0 \cos(\omega_0 t) - b \omega_0^2 t \sin(\omega_0 t)$$

$$y'' + \frac{k}{m}y = \frac{A}{m} \cos(\omega_0 t) \quad \omega_0 = \sqrt{\frac{k}{m}}$$

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$$\cos(\omega_0 t) \left[-a\omega_0^2 t + 2b\omega_0 + \frac{k}{m}at \right] + \sin(\omega_0 t) \left[-2a\omega_0 - b\omega_0^2 t + \frac{k}{m}bt \right] = \frac{A}{m} \cos(\omega_0 t)$$

$$2b\omega_0 \cos(\omega_0 t) - 2a\omega_0 \sin(\omega_0 t) = \frac{A}{m} \cos(\omega_0 t)$$

for all t : $a=0$, $2b\omega_0 = \frac{A}{m}$, $b = \frac{A}{2m\omega_0}$

so $y_p(t) = \frac{A}{2m\omega_0} t \sin(\omega_0 t)$

general solution: $y(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t) + \frac{A}{2m\omega_0} t \sin(\omega_0 t)$

slc $\rightarrow \infty$ as $t \rightarrow \infty$!

Beats ($c=0$, no damping) $\omega \neq \omega_0$ $y'' + \omega^2 y = \frac{A}{m} \cos(\omega_0 t)$, $y(0)=0$, $y'(0)=0$

use: addition formulae:

$$\begin{aligned} \cos(A+B) &= \cos A \cos B - \sin A \sin B \\ \cos(A-B) &= \cos A \cos B + \sin A \sin B \end{aligned}$$

$$y(t) = \frac{A}{m(\omega_0^2 - \omega^2)} (\cos(\omega t) - \cos(\omega_0 t))$$

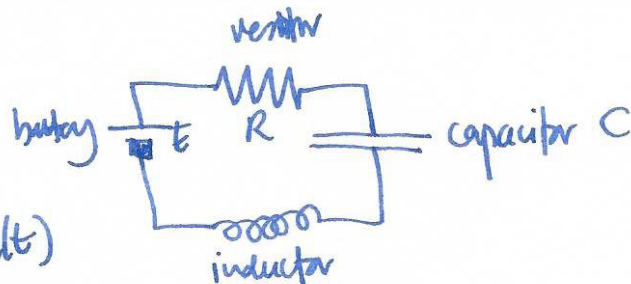
$$= \frac{2A}{m(\omega_0^2 - \omega^2)} \sin\left(\frac{1}{2}(\omega_0 + \omega)t\right) \sin\left(\frac{1}{2}(\omega_0 - \omega)t\right)$$



Electrical circuits

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voltage



$$E(t) = Li'(t) + Ri(t) + \frac{1}{C}q(t)$$

$$i(t) = q'(t) \leadsto q'' + \frac{R}{L}q' + \frac{1}{LC}q = \frac{1}{L}E \leftarrow \text{exactly same as spring equation!}$$

analogy:

displacement function	$y(t) \leftrightarrow$	charge $q(t)$
velocity	$y'(t) \leftrightarrow$	current $i(t)$
driving force	$f(t) \leftrightarrow$	electromotive force $E(t)$
mass	$m \leftrightarrow$	inductance L
damping constant	$c \leftrightarrow$	resistance R
spring modulus	$k \leftrightarrow$	$1/\text{capacitance}$

Higher order differential equations

Reduction to first order: $y'' + 2y' + y = 0$ (*) try $y = e^{\lambda x}$, $y' = \lambda e^{\lambda x}$, $y'' = \lambda^2 e^{\lambda x}$
 $e^{\lambda x}(\lambda^2 + 2\lambda + 1) = 0$ etc...

alternatively: set $\begin{cases} z_1 = y \\ z_2 = y' = z_1' \\ y'' = z_2' \end{cases}$ (*) becomes $z_2' + 2z_2 + z_1 = 0$.

equivalent to $\begin{cases} z_1' = z_2 \\ z_2' = -z_1 - 2z_2 \end{cases}$ 2d first order d.e.!

set $\underline{z} = \begin{bmatrix} z_1 \\ z_2 \end{bmatrix}$ $\underline{z}' = A\underline{z}$ where $A = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix}$

look for solution: $\underline{z} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} e^{\lambda x}$ $\underline{z}' = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \lambda e^{\lambda x}$

$$\underline{z}' = A\underline{z} : \lambda \underline{c} e^{\lambda x} = A \underline{c} e^{\lambda x} \Rightarrow A \underline{c} = \lambda \underline{c}$$

$\underline{c}$ eigenvector, λ eigenvalue of A .

Example

$$y''' + 2y'' - y' - 2y = 0 \quad (*)$$

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$$z_1 = y$$

$$z_1' = z_2$$

$$z_2' = y' = z_1'$$

$$z_2' = z_3$$

$$z_3' = z_2 - 2z_3$$

$$z_3' = 2z_1 + z_2 - 2z_3$$

$$\underline{z}' = A \underline{z}$$

in general: $\underline{z}' = A(\underline{z}) \underline{z}$

§6.1 Vectors

scalar/number

magnitude $\forall \pi \in \mathbb{R}$
s.t.

vector

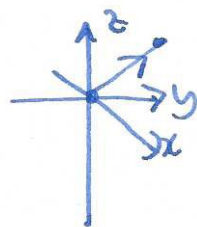
magnitude and direction



$$2d \in \mathbb{R}^2$$

$$3d \in \mathbb{R}^3$$

$$nd \in \mathbb{R}^n$$



$\underline{v}, \underline{w}$

$$\langle x, y, z \rangle \in \mathbb{R}^3$$

scalar multiplication

$$2\underline{v}$$

vector same direction

twice as long

$$\underline{v} = \langle v_1, v_2, v_3 \rangle$$

$$-\frac{1}{2}\underline{v}$$

opposite

half as long

$$3\underline{v} = \langle 3v_1, 3v_2, 3v_3 \rangle$$

warning

$3 + \underline{v}$ doesn't make sense!

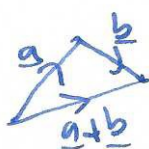
length



$$\|\underline{v}\| = \sqrt{v_1^2 + v_2^2 + v_3^2}$$

check: $\|\lambda \underline{v}\| = |\lambda| \|\underline{v}\|$

vector addition



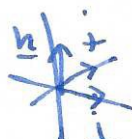
$$\underline{a} = \langle a_1, a_2, a_3 \rangle \quad \underline{b} = \langle b_1, b_2, b_3 \rangle$$

$$\underline{a} + \underline{b} = \langle a_1 + b_1, a_2 + b_2, a_3 + b_3 \rangle$$

triangle inequality

$$\|\underline{a} + \underline{b}\| \leq \|\underline{a}\| + \|\underline{b}\|$$

special vectors



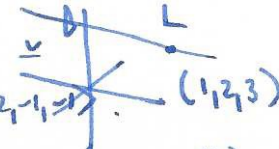
$$\underline{v} = \langle v_1, v_2, v_3 \rangle = v_1 \underline{i} + v_2 \underline{j} + v_3 \underline{k}$$

equations of lines



$$\underline{r}(t) = \underline{a} + t\underline{v}$$

Example

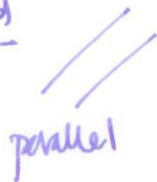


$$\underline{r}(t) = \langle 3, 1, 2 \rangle$$

$$\underline{r}(t) = \langle 1, 2, 3 \rangle + t \langle 2, -1, -1 \rangle$$

same!

2d



parallel



intersect

3d



parallel



intersect



skew.

3d

§6.2 Dot product

Defn (geometric)
(algebraic)

$$\underline{a} \cdot \underline{b} = \|\underline{a}\| \|\underline{b}\| \cos \theta$$

$$\underline{a} \cdot \underline{b} = a_1 b_1 + a_2 b_2 + a_3 b_3.$$

so can find θ :

$$\cos \theta = \frac{\underline{a} \cdot \underline{b}}{\|\underline{a}\| \|\underline{b}\|}$$

Useful properties

$$\underline{a} \cdot \underline{b} = \underline{b} \cdot \underline{a}$$

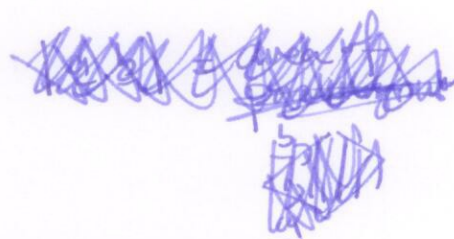
$$(\underline{a} + \underline{b}) \cdot \underline{c} = \underline{a} \cdot \underline{c} + \underline{b} \cdot \underline{c}$$

$$\lambda(\underline{a} \cdot \underline{b}) = (\lambda \underline{a}) \cdot \underline{b} = \underline{a} \cdot (\lambda \underline{b})$$

$$\underline{a} \cdot \underline{a} = \|\underline{a}\|^2$$

$$\underline{a} \cdot \underline{a} = 0 \Rightarrow \underline{a} = \underline{0}$$

$$\|\alpha \underline{a} + \beta \underline{b}\|^2 = \alpha^2 \|\underline{a}\|^2 + 2\alpha\beta \underline{a} \cdot \underline{b} + \beta^2 \|\underline{b}\|^2 \quad (*)$$



Cauchy-Schwarz

$$|\underline{a} \cdot \underline{b}| \leq \|\underline{a}\| \|\underline{b}\|$$

warning:

0 number $\underline{0}$ vector $\langle 0, 0, 0 \rangle$

$\underline{a} \cdot \underline{b} \cdot \underline{c}$ doesn't make sense! but $(\underline{a} \cdot \underline{b}) \cdot \underline{c}$ does.

*proof:

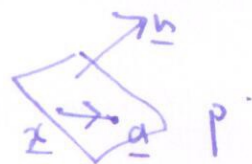
$$\|\alpha \underline{a} + \beta \underline{b}\|^2 = (\alpha \underline{a} + \beta \underline{b}) \cdot (\alpha \underline{a} + \beta \underline{b})$$

$$= \alpha^2 \underline{a} \cdot \underline{a} + 2\alpha\beta \underline{a} \cdot \underline{b} + \beta^2 \underline{b} \cdot \underline{b}$$

$$= \alpha^2 \|\underline{a}\|^2 + 2\alpha\beta \underline{a} \cdot \underline{b} + \beta^2 \|\underline{b}\|^2. \quad \square.$$

Defn Two vectors are orthogonal or perpendicular if $\underline{a} \cdot \underline{b} = 0$

Equations of planes



$$(\underline{x} - \underline{a}) \cdot \underline{n} = 0$$

$$\underline{n} = \langle a, b, c \rangle$$

$$\underline{a} = \langle x_0, y_0, z_0 \rangle.$$

$$\underline{x} = \langle x, y, z \rangle.$$

$$(\langle x, y, z \rangle - \langle x_0, y_0, z_0 \rangle) \cdot \langle a, b, c \rangle = 0$$

$$ax + by + cz = d.$$