

Column space $C(A)$

Note: $C(A)$ is also the image of A .

$$= \{Ax \in \mathbb{R}^m \mid x \in \mathbb{R}^n\}. \text{ as } [c_1 \ c_2 \ \dots \ c_m] \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = c_1x_1 + c_2x_2 + \dots + c_nx_n.$$

Warning Row operations change the column space! Example $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$.

Claim: the columns of A corresponding to pivots in U are a basis for $C(A)$. so $\dim(C(A)) = \#\text{pivots} = r = \text{rank}(A) (= \dim \text{Row}(A))$.

Proof observation: $Ax=0 \Leftrightarrow Ux=0$ ($N(A)=N(U)$).

a linear dependence between the columns of A is $[c_1 \dots c_n] \quad a_1c_1 + a_2c_2 + \dots + a_nc_n = 0$

i.e. $[c_1 \dots c_n] \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix} = 0$ i.e. $Ax=0$, but then $Ux=0$, so this gives linear

dependence between columns of U and vice versa.

The pivot columns of U are a basis for $C(U)$:

\Rightarrow the corresponding columns of A are a basis for $C(A)$. □

0	1				
		1			
0	0	0	1	0	0
0	0	0	0	1	0
0	0	0	0	0	1

Left nullspace $N(A^T)$

$$\text{i.e. } y^T A = 0 \quad [y_1 \ y_2 \ \dots \ y_m] \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_m \end{bmatrix} = y_1r_1 + y_2r_2 + \dots + y_mr_m = 0$$

i.e. linear combinations of rows which give 0.

recall: $PA = LU$

$$L^{-1}P^T A = U$$

$$U = \begin{array}{|c|c|c|c|} \hline & R_1 & R_2 & R_3 \\ \hline R_1 & 1 & 0 & 0 \\ R_2 & 0 & 1 & 0 \\ R_3 & 0 & 0 & 1 \\ \hline \end{array} \text{ rows}$$

$n-r$ rows.

(bottom $n-r$ rows of $L^{-1}P$ are a basis for $N(A^T)$).

alternate method: just solve $A^T y = 0$.

(use row echelon form)

Fundamental theorem of linear algebra part I

$$\dim(C(A)) = r$$

$$\dim(N(A)) = n - r$$

$$\dim(\text{Row}(A)) = r$$

$$\dim(N(A^T)) = m - r$$

Existence of inverses

recall if A has a left inverse and a right inverse, they are equal.

fact: A has left and right inverses iff A is square $n \times n$ and $\text{rank}(A) = n$.

One sided inverses

Example $\begin{bmatrix} 2 & 0 \\ 0 & 3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1/3 \end{bmatrix} \underset{2 \times 3}{=} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1/3 \\ * & * \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

\Leftrightarrow can always solve
 $Ax = b$

not unique!

Fact $A \in \mathbb{R}^{m \times n} \quad \text{rank}(A) = r$

if $r=m$ then there is a right inverse $A^T(AA^T)^{-1}$ check!
 $r=n$ then there is a left inverse $(A^T A)^{-1} A^T$ check!

problem: when is AA^T invertible?

$$\begin{array}{lll} AA^T & m \times m & \text{rank} \leq r \\ A^T A & n \times n & \text{rank} \leq r \end{array}$$

Two sided inverses

A has a two sided inverse iff $m=n=r=\text{rank}(A)$

more equivalent conditions: columns of A span \mathbb{R}^n ; so $Ax=b$ has at least one solution for every b .

- the columns of A are independent, so $Ax=0$ has unique soln $x=0$
- the rows of A span \mathbb{R}^n
- the rows are linearly independent
- elimination gives $PA = LDU$ with n pivots.
- $\det(A) \neq 0$

$$A = \begin{bmatrix} 1 & 2 & -3 \\ 1 & 1 & 5 \\ 1 & 3 & -1 \end{bmatrix}$$

and the row echelon form of the inverse of the following matrix

§2-6 Linear transformations

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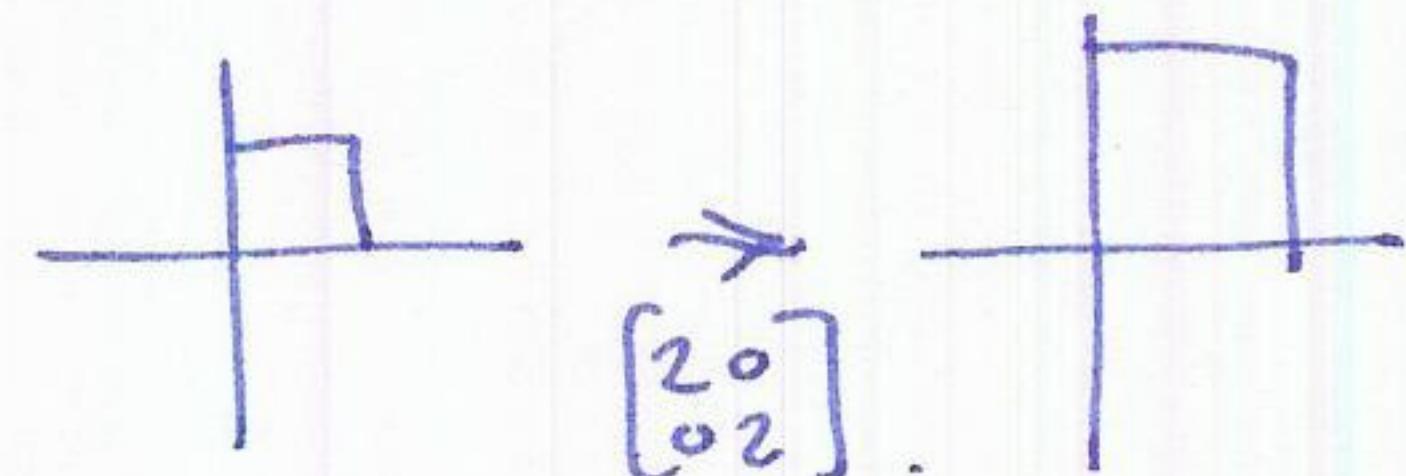
A $m \times n$ matrix $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$\underbrace{x}_{n \times 1} \mapsto \underbrace{Ax}_{m \times 1}$$

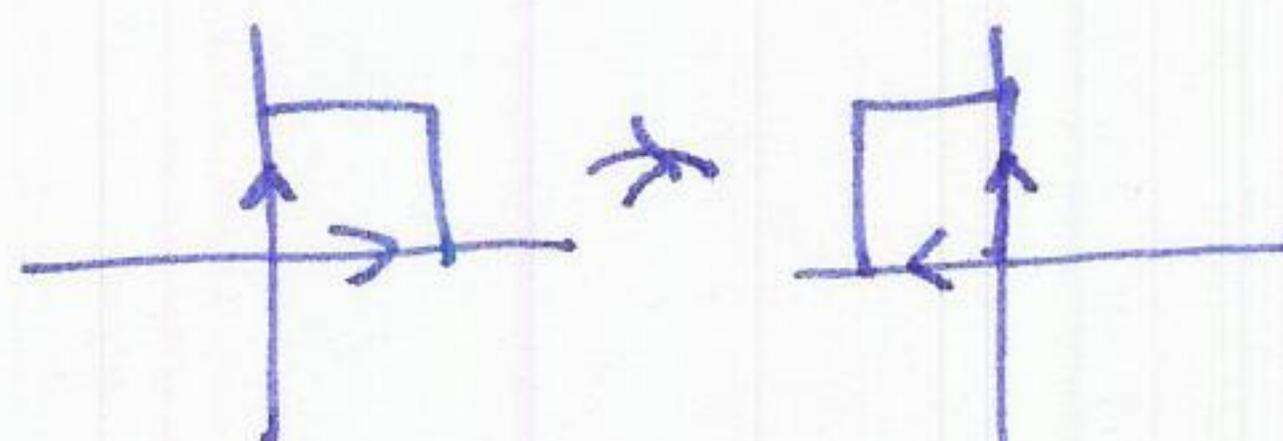
Examples

- $A = I$ $x \mapsto x$ identity.

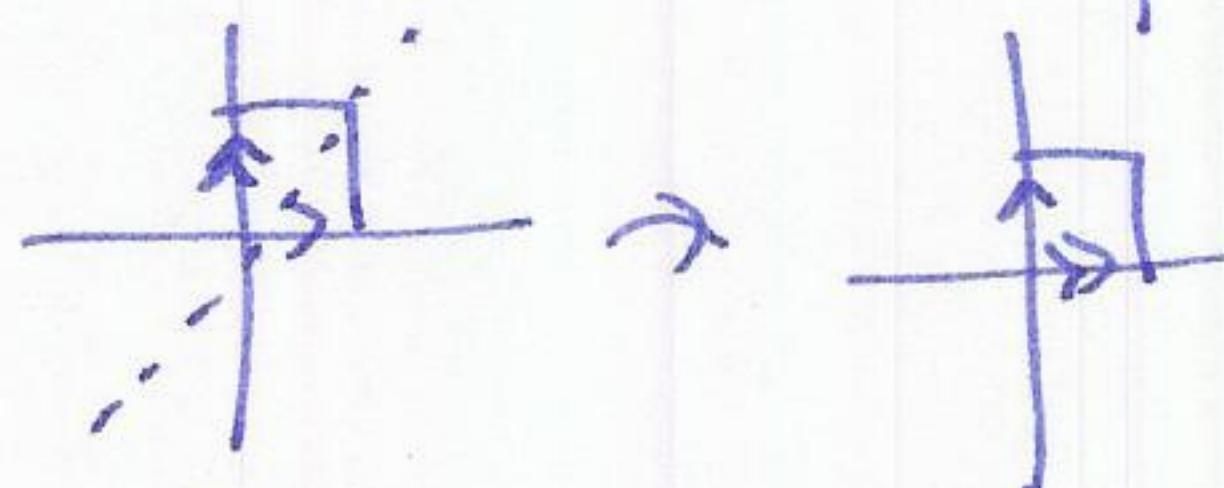
- $A = \begin{bmatrix} c & 0 \\ 0 & c \end{bmatrix} = cI$ expansion/contraction
 $c > 1$ $0 < c < 1$



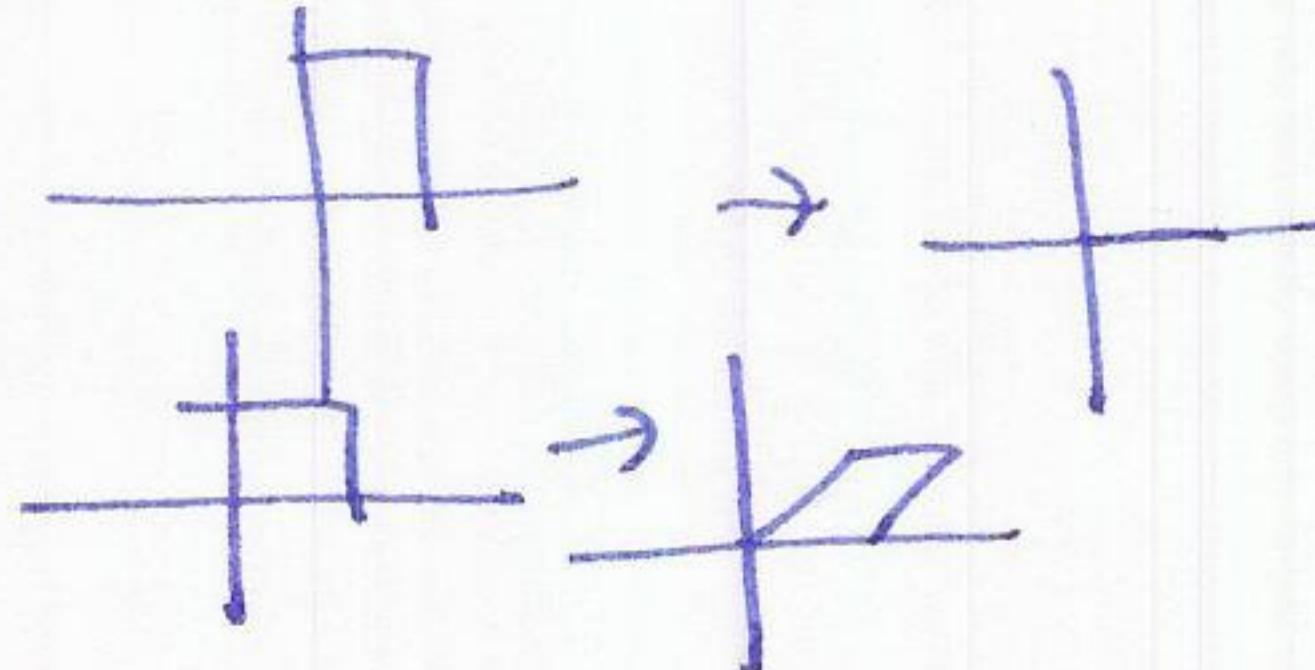
- $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ rotation $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} -y \\ x \end{bmatrix}$



- $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ reflection $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} y \\ x \end{bmatrix}$



- $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ projection $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} x \\ 0 \end{bmatrix}$



Observations $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$

- $A \cdot 0 = 0$ always sends zero vector to zero vector

- $A(cx) = c(Ax)$

- $A(x+y) = Ax+Ay$

in vectorspace.

Defn A map $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear map/transformation if

- $T(cx) = c(Tx)$

- $T(x+y) = Tx+Ty$

Examples

- $A: \mathbb{R}^m \rightarrow \mathbb{R}^n$
 $x \mapsto Ax$

Fact: every linear map can be described as a matrix.