

Defn $f(x,y)$ is differentiable at (a,b) if

- $\frac{\partial f}{\partial x}(a,b)$ and $\frac{\partial f}{\partial y}(a,b)$ exist
- $f(x,y)$ is locally linear at (a,b)

in this case the tangent plane is $z = L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$

Thm If $f_x(x,y), f_y(x,y)$ exist and are continuous close to (a,b) .
Then $f(x,y)$ is differentiable at (a,b) .

Bad example is $z = x^2 + y^2$ differentiable at $(0,0)$.

$$z = \sqrt{x^2+y^2}$$

$$\frac{\partial f}{\partial x} = \frac{1}{2}(x^2+y^2)^{-1/2} \cdot 2x = \frac{x}{\sqrt{x^2+y^2}} = \frac{r \cos \theta}{r} = \cos \theta \quad \left. \begin{array}{l} \text{net } c \\ \text{at } (0,0) \end{array} \right\}$$

$$\frac{\partial f}{\partial y} = \frac{1}{2}(x^2+y^2)^{-1/2} \cdot 2y = \frac{y}{\sqrt{x^2+y^2}} = \frac{r \sin \theta}{r} = \sin \theta$$

§ 14.5 Gradient

2d: $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ $f(x,y)$

the gradient of f is $\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right\rangle$

$$\nabla f(a,b) = \left\langle \frac{\partial f}{\partial x}(a,b), \frac{\partial f}{\partial y}(a,b) \right\rangle$$

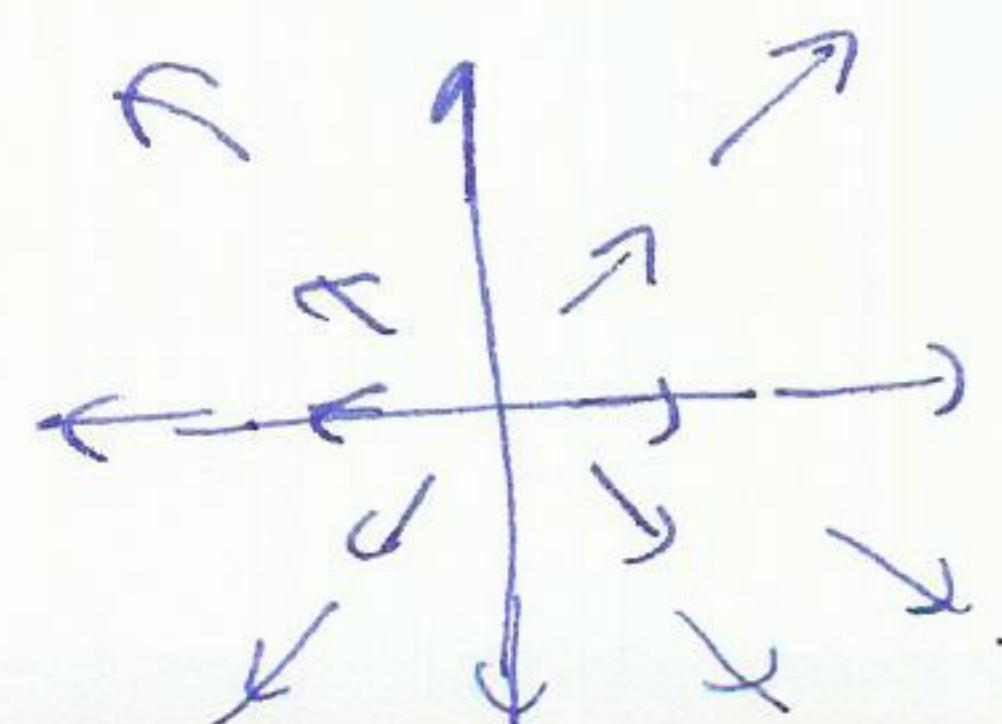
3d: $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ $f(x,y,z)$ $\nabla f(a,b,c) = \left\langle \frac{\partial f}{\partial x}(a,b,c), \frac{\partial f}{\partial y}(a,b,c), \frac{\partial f}{\partial z}(a,b,c) \right\rangle$

Rule: $\nabla f: \text{point} \rightarrow \text{vector}$
 $\begin{matrix} \mathbb{R}^2 & \rightarrow & \mathbb{R}^2 \\ \mathbb{R}^3 & \rightarrow & \mathbb{R}^3 \end{matrix} \quad]$

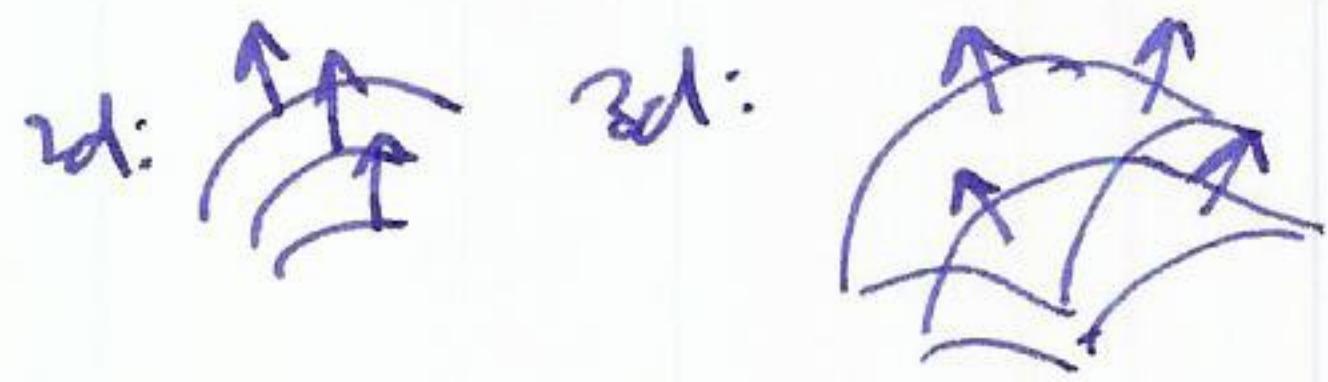
key facts:

- the gradient vector points in the direction of fastest rate of change
- $\|\nabla f\| =$ fastest rate of change

Example $f(x,y) = x^2 + y^2$ $\nabla f = \langle 2x, 2y \rangle$



observation: the gradient vector is perpendicular to the level sets / contours. (53)



Directional derivatives useful properties

$$1) \quad \nabla(f+g) = \nabla f + \nabla g$$

$$2) \quad \nabla(cf) = c\nabla f$$

$$3) \text{ product rule } \nabla(fg) = f\nabla g + g\nabla f$$

4) chain rule: if $F(t)$ is differentiable then

$$\nabla(F(f(x,y,z))) = F'(f(x,y,z)) \nabla f$$

check this makes sense

$$F \circ f: \mathbb{R}^3 \xrightarrow{f} \mathbb{R} \xrightarrow{F} \mathbb{R}$$

$$\begin{aligned} \nabla(F(f(x))) &= \left\langle \frac{\partial}{\partial x}(F(f(x))), \frac{\partial}{\partial y}(F(f(x))), \frac{\partial}{\partial z}(F(f(x))) \right\rangle \\ \stackrel{f(x)}{=} \stackrel{f(x,y,z)}{=} & \left\langle F'(f(x)) \cdot \frac{\partial f}{\partial x}, F'(f(x)) \cdot \frac{\partial f}{\partial y}, F'(f(x)) \cdot \frac{\partial f}{\partial z} \right\rangle \\ &= F'(f(x)) \nabla f \end{aligned}$$

Chain rule for paths

$$f: \mathbb{R}^3 \rightarrow \mathbb{R} \quad \text{path} \quad \underline{s}: \mathbb{R} \rightarrow \mathbb{R}^3 \quad t \mapsto (x(t), y(t), z(t))$$

$$\text{composition: } \underbrace{c_f}_{\mathbb{R} \xrightarrow{c} \mathbb{R}^3 \xrightarrow{f} \mathbb{R}}$$

$$\text{Thm: } \frac{d}{dt} f(\underline{s}(t)) = \nabla f(\underline{s}(t)) \cdot \underline{s}'(t)$$

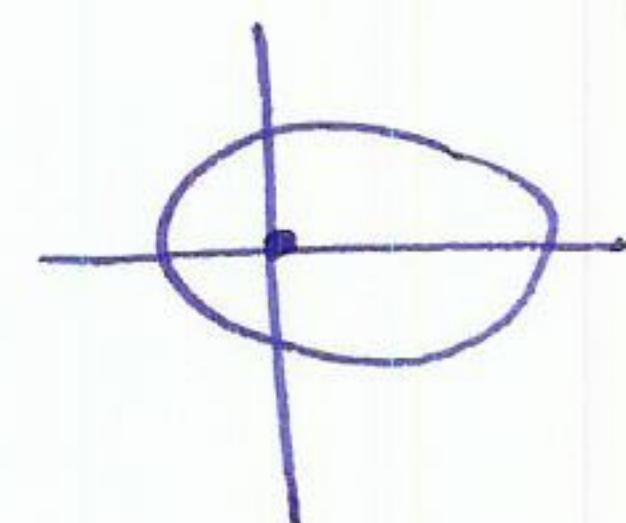
$$\text{Proof in } \mathbb{R}^2: \frac{d}{dt}(f(\underline{s}(t))) = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right\rangle \cdot \langle \underline{s}'(t), \underline{s}'(t) \rangle = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

Example temperature T varies with location like $T(x, y, z) = \frac{1}{x^2 + y^2 + z^2}$ (54)

if we move an ellipse $\frac{(x-3)^2}{25} + \frac{y^2}{16} = 1$ (foci at $(0,0), (6,0)$)

parameterize ellipse: $\underline{c}(t) = (5\cos t + 3, 4\sin t, 0)$

$$\text{then } T(\underline{c}(t)) = \frac{1}{(5\cos t + 3)^2 + (4\sin t)^2 + 0^2}$$



$$\frac{d}{dt}(T(\underline{c}(t))) = \nabla T \cdot \underline{c}'(t) = \left\langle \frac{\partial T}{\partial x}, \frac{\partial T}{\partial y}, \frac{\partial T}{\partial z} \right\rangle \cdot \left\langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right\rangle$$

$$= \left\langle -(x^2 + y^2 + z^2)^{-2} \cdot 2x, -(x^2 + y^2 + z^2)^{-2} \cdot 2y, -(x^2 + y^2 + z^2)^{-2} \cdot 2z \right\rangle \cdot \langle -5\sin t, 4\cos t, 0 \rangle$$

$$= -\frac{2}{(x^2 + y^2 + z^2)^2} \langle x, y, z \rangle \cdot \langle -5\sin t, 4\cos t, 0 \rangle$$

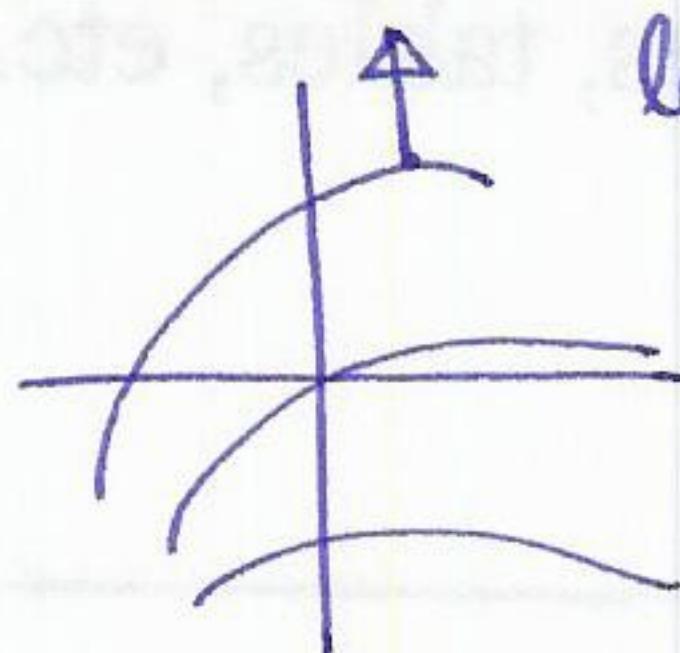
$$= -\frac{2}{(5\cos t + 3)^2 + (4\sin t)^2} \langle 5\cos t + 3, 4\sin t, 0 \rangle \cdot \langle -5\sin t, 4\cos t, 0 \rangle$$

$$= -2[(5\cos t + 3)(-5\sin t) + (4\sin t)(4\cos t)] / [(5\cos t + 3)^2 + (4\sin t)^2]$$

Directional derivatives

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

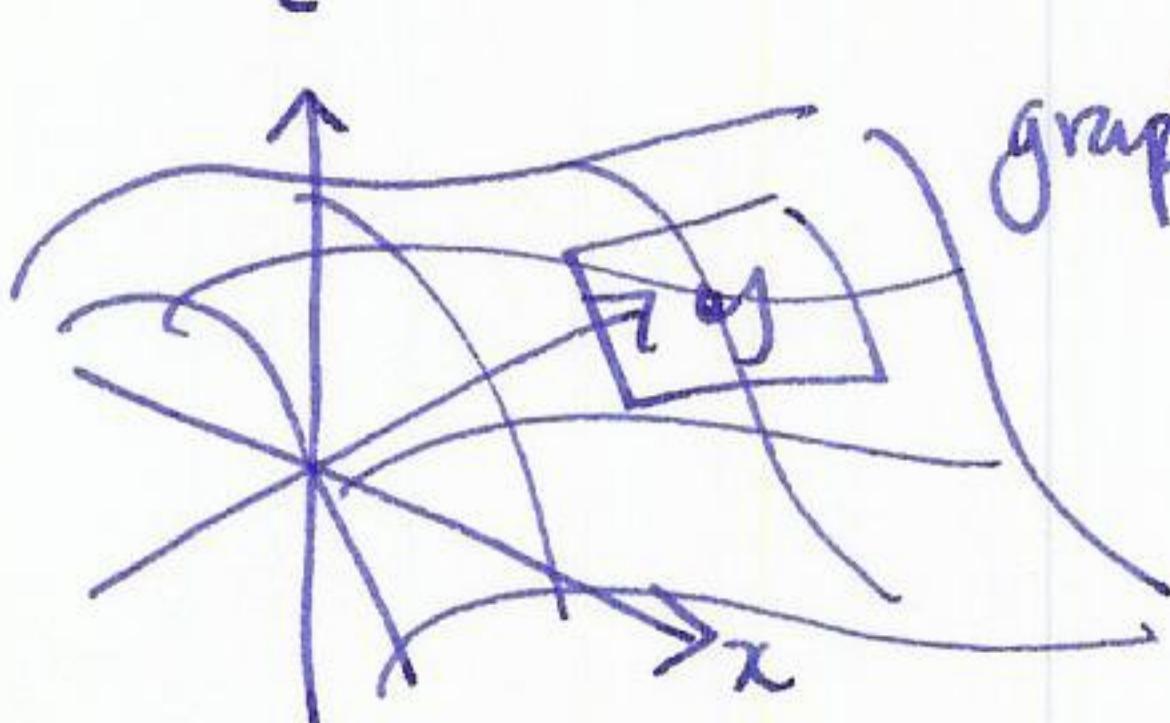
$$f(x, y)$$



level sets $\nabla f \perp$ (level sets).

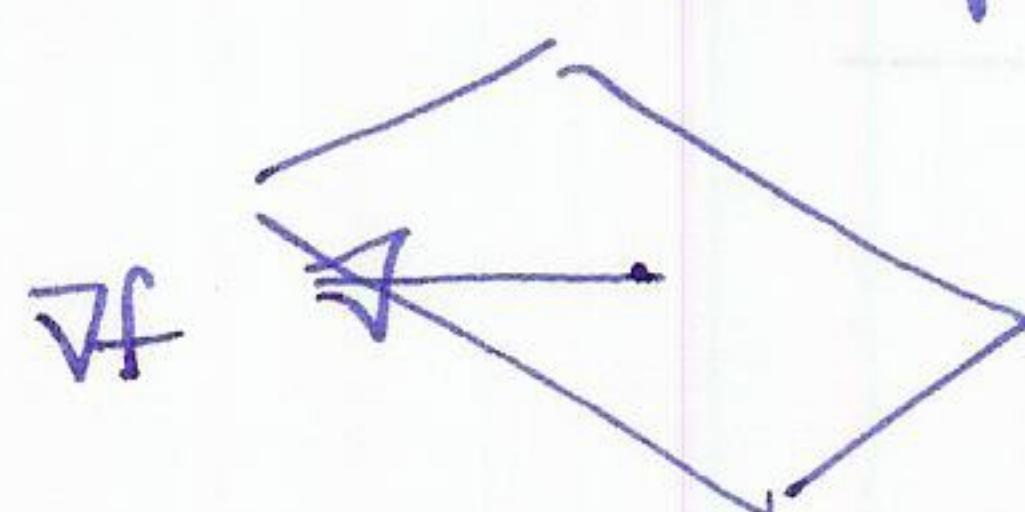
rate of change in direction $\nabla f = \|\nabla f\|$

rate of change in \perp direction tangent to
level set is 0.



graph $z = f(x, y)$

tangent plane at a point

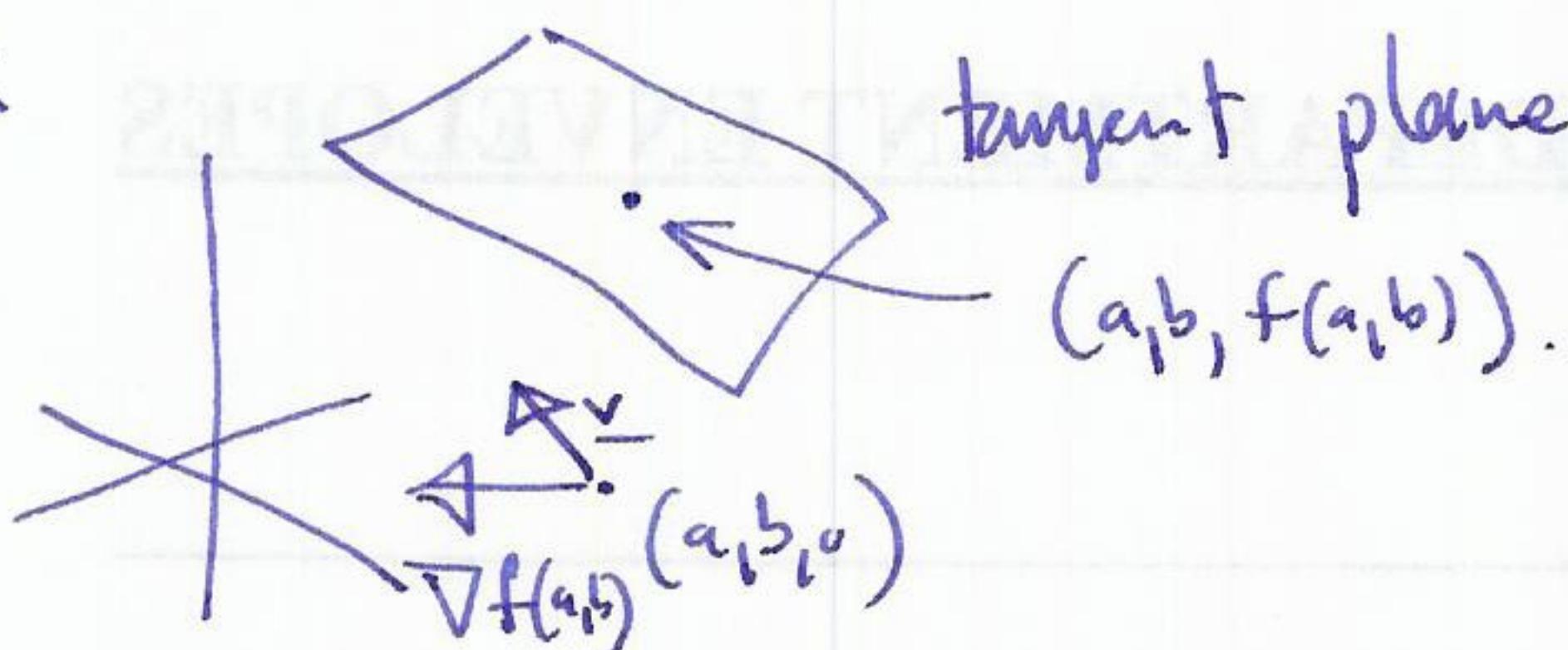


what about rate of change in some other direction \underline{v} (unit vector $\|\underline{v}\|=1$) (55)

Then the directional derivative $D_{\underline{v}} f$ is equal to

$$D_{\underline{v}} f(a,b) = \nabla f(a,b) \cdot \underline{v}$$

sketch:



tangent plane has equation

$(a, b, f(a, b))$.

$$z = \frac{\partial f}{\partial x}(a,b)(x-a) + \frac{\partial f}{\partial y}(a,b)(y-b)$$

so if $\underline{v} = \langle v_1, v_2 \rangle$ then rate of change is $\frac{\partial f}{\partial x}(a,b) \cdot v_1 + \frac{\partial f}{\partial y}(a,b) v_2$
 $= \nabla f \cdot \underline{v}$.

Useful properties

- if \underline{v} is not a unit vector define $D_{\underline{v}} f(a,b) = \nabla f \cdot \underline{v}$
- $D_{\lambda \underline{v}} f(a,b) = \lambda \nabla f \cdot \underline{v}$
- so if \underline{v} is not a unit vector the directional derivative in direction \underline{v} is $\frac{1}{\|\underline{v}\|} \nabla f \cdot \underline{v}$

Applications

Finding normal vectors : sphere $x^2+y^2+z^2=r^2$

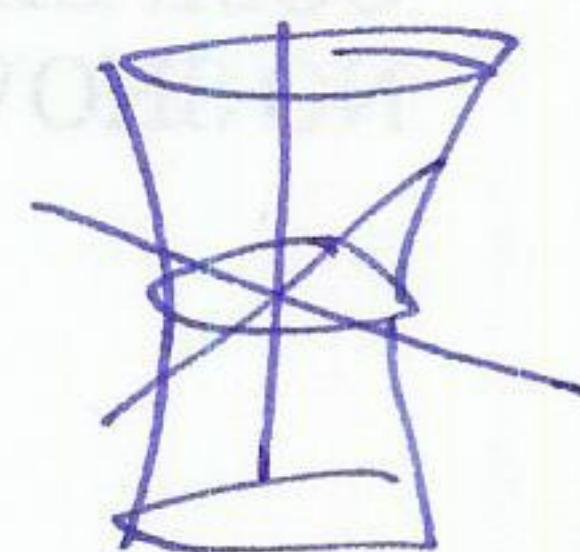


consider $f(x,y,z) = x^2+y^2+z^2$

then $\nabla f(x,y,z) = \langle 2x, 2y, 2z \rangle$ is normal vector.

Finding a tangent plane : hyperboloid $x^2+y^2=z^2+1$

find normal vectors : consider $f(x,y,z) = x^2+y^2-z^2=1$



then $\nabla f = \langle 2x, 2y, -2z \rangle$

so normal vector at $(1,1,1)$ is $\langle 2, 2, -2 \rangle$

so tangent plane is $\underline{n} \cdot (\underline{x} - \underline{p}) = 0$

$$\langle 2, 2, -2 \rangle \cdot (\langle x, y, z \rangle - \langle 1, 1, 1 \rangle) = 0$$

$$2x + 2y - 2z = 2.$$

§ 14.6 Chain rule

recall : $\mathbb{R} \xrightarrow{g} \mathbb{R} \xrightarrow{f} \mathbb{R}$

$$(f(g(x)))' = f'(g(x)) \cdot g'(x)$$

$\mathbb{R}^a \xrightarrow{f} \mathbb{R}^b$ looks like $f(x_1, x_2, \dots, x_n) = (f_1(x_1, \dots, x_n), f_2(x_1, \dots, x_n), \dots, f_b(x_1, \dots, x_n))$

(x_1, x_2, \dots, x_n)

Example $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $f(x_1) = (x_1^2 + y^2, x_1^2 - y^2)$

the derivative at a point is a linear map $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$Df = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial y} \end{bmatrix}$$

General chain rule :

$f: \mathbb{R}^a \xrightarrow{g} \mathbb{R}^b \xrightarrow{f} \mathbb{R}^c$

$$D(g \circ f)(x) = Df(g(x)) \cdot Dg(x) \quad \text{matrix multiplication!}$$

$$\left[\frac{\partial f_i}{\partial x_j} \right]_{a \times b} \left[\frac{\partial g_j}{\partial x_k} \right]_{b \times c}$$

is an $a \times c$ matrix!

Example ① $\mathbb{R} \xrightarrow{g} \mathbb{R}^2 \xrightarrow{f} \mathbb{R}$

$$Dg = \begin{pmatrix} g_1(t) \\ g_2(t) \end{pmatrix} \quad Df = \nabla f$$

$$g(t) = (g_1(t), g_2(t))$$

$$g'(t) = (g_1'(t), g_2'(t))$$

$$\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right\rangle$$

$$\begin{aligned}
 D(f(g(x))) &= Df(g(t)) \cdot Dg(t) \\
 &= \nabla f \cdot g'(t) = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right\rangle \cdot \left\langle \frac{dg_1}{dt}, \frac{dg_2}{dt} \right\rangle \\
 &= \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}.
 \end{aligned}$$

② $\mathbb{R}^2 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{f} \mathbb{R}^2$

$$g(x_1, x_2) = (g_1(x_1, x_2), g_2(x_1, x_2)).$$

$$D(f(g(x))) = Df(g(x)) \cdot Dg(x).$$

$$Dg = \begin{bmatrix} \frac{\partial g_1}{\partial x_1} & \frac{\partial g_1}{\partial x_2} \\ \frac{\partial g_2}{\partial x_1} & \frac{\partial g_2}{\partial x_2} \end{bmatrix}.$$

$$Df = \begin{bmatrix} \frac{\partial f_1}{\partial y_1} & \frac{\partial f_1}{\partial y_2} \\ \frac{\partial f_2}{\partial y_1} & \frac{\partial f_2}{\partial y_2} \end{bmatrix}.$$

$$Df(g(x)) \cdot Dg = \begin{bmatrix} \frac{\partial f_1}{\partial y_1} & \frac{\partial f_1}{\partial y_2} \\ \frac{\partial f_2}{\partial y_1} & \frac{\partial f_2}{\partial y_2} \end{bmatrix} \begin{bmatrix} \frac{\partial g_1}{\partial x_1} & \frac{\partial g_1}{\partial x_2} \\ \frac{\partial g_2}{\partial x_1} & \frac{\partial g_2}{\partial x_2} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial y_1} \frac{\partial g_1}{\partial x_1} + \frac{\partial f_1}{\partial y_2} \frac{\partial g_2}{\partial x_1} & \dots \\ \dots & \dots \end{bmatrix}$$