

let S be a set (e.g. $\mathbb{R}^2$)

a transformation of S is a function $S \rightarrow S$

a collection G of transformations forms a group if

- if $f, g \in G$ then $f \circ g \in G$
- if $f \in G$ then f has an inverse f^{-1} which is also in G .

observation $\Rightarrow id_S \in G$ as $ff^{-1} = id$.

Klein's view of geometry: study the transformation groups and their invariants.

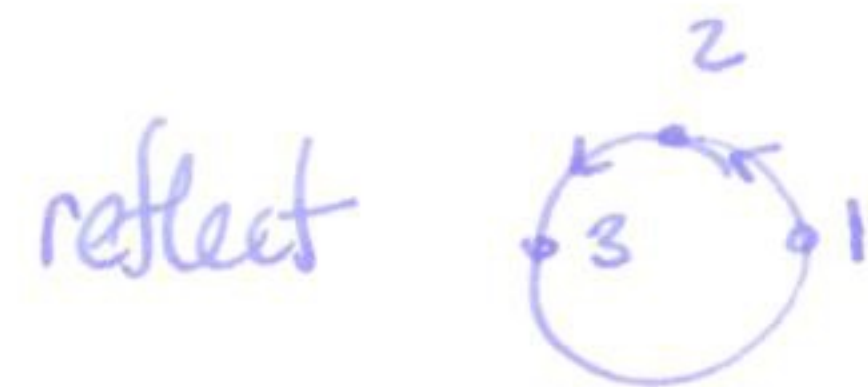
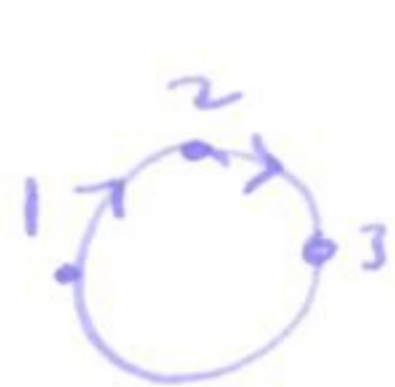
Example $\mathbb{R}^2$, $G =$ isometries of $\mathbb{R}^2$

invariants: distance, straight lines $\mapsto$ straight lines
circles $\mapsto$ circles.

perpendicular lines $\mapsto$ perpendicular lines
angles are preserved.

non-invariants: vertical lines.

clockwise order on the circle



Oriented Euclidean geometry $Isom^+(\mathbb{R}^2) \subset Isom(\mathbb{R}^2)$

all isometries which are a product of an even number of reflections.
(i.e. rotations + translations)

claim $Isom^+(\mathbb{R}^2)$ is a group.

check: • f, g products of an even number of reflections, then so is fg .

• if $f = r_1 \dots r_{2m}$ product of an even number of reflections
then $f^{-1} = r_{2m} \dots r_1$ also product of an even number of reflections.

claim $\text{Isom}^+(\mathbb{R}^2)$ preserves clockwise order.

proof: a single reflection reverses clockwise order, so we preserve it, so an even number of reflections preserve it. $\square$.

§4.1 Vectors

Examples $\mathbb{R}, \mathbb{R}^2, \mathbb{R}^3, \mathbb{R}^n, \dots$

rules for vectors:

$$\underline{u} + \underline{v} = \underline{v} + \underline{u}$$

$$\underline{u} + (\underline{v} + \underline{w}) = (\underline{u} + \underline{v}) + \underline{w}$$

$$\underline{u} + \underline{0} = \underline{u}$$

$$\underline{u} + (-\underline{u}) = \underline{0}$$

$$1\underline{u} = \underline{u}$$

$$a(\underline{u} + \underline{v}) = a\underline{u} + a\underline{v}$$

$$(a+b)\underline{u} = a\underline{u} + b\underline{u}$$

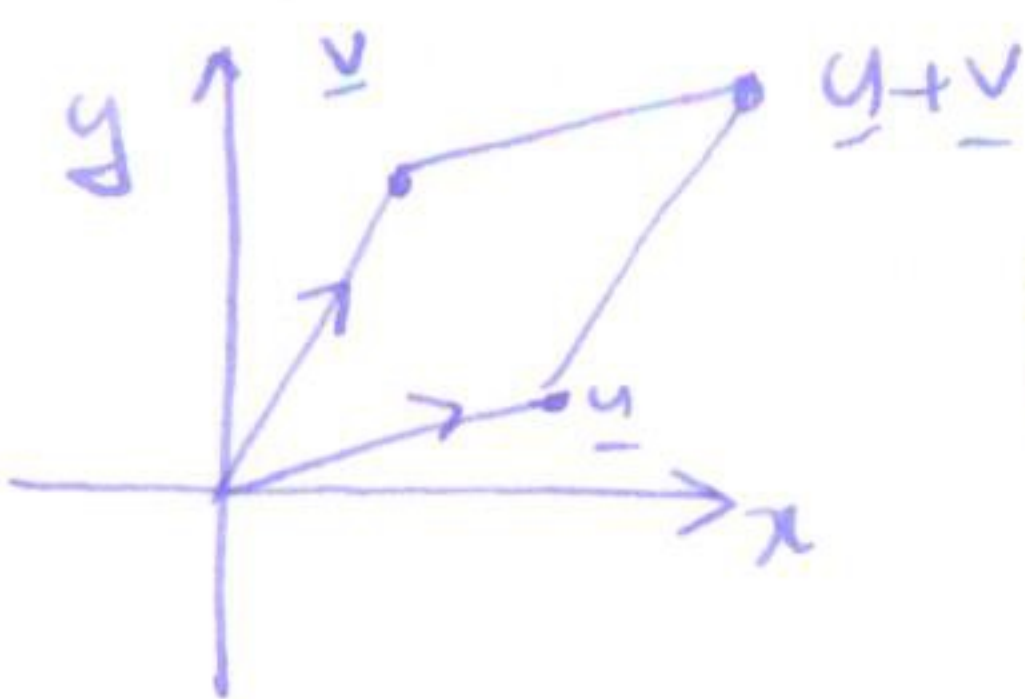
$$a(b\underline{u}) = (ab)\underline{u}$$

rules hold for $\underline{u}, \underline{v} \in \mathbb{R}^2$.

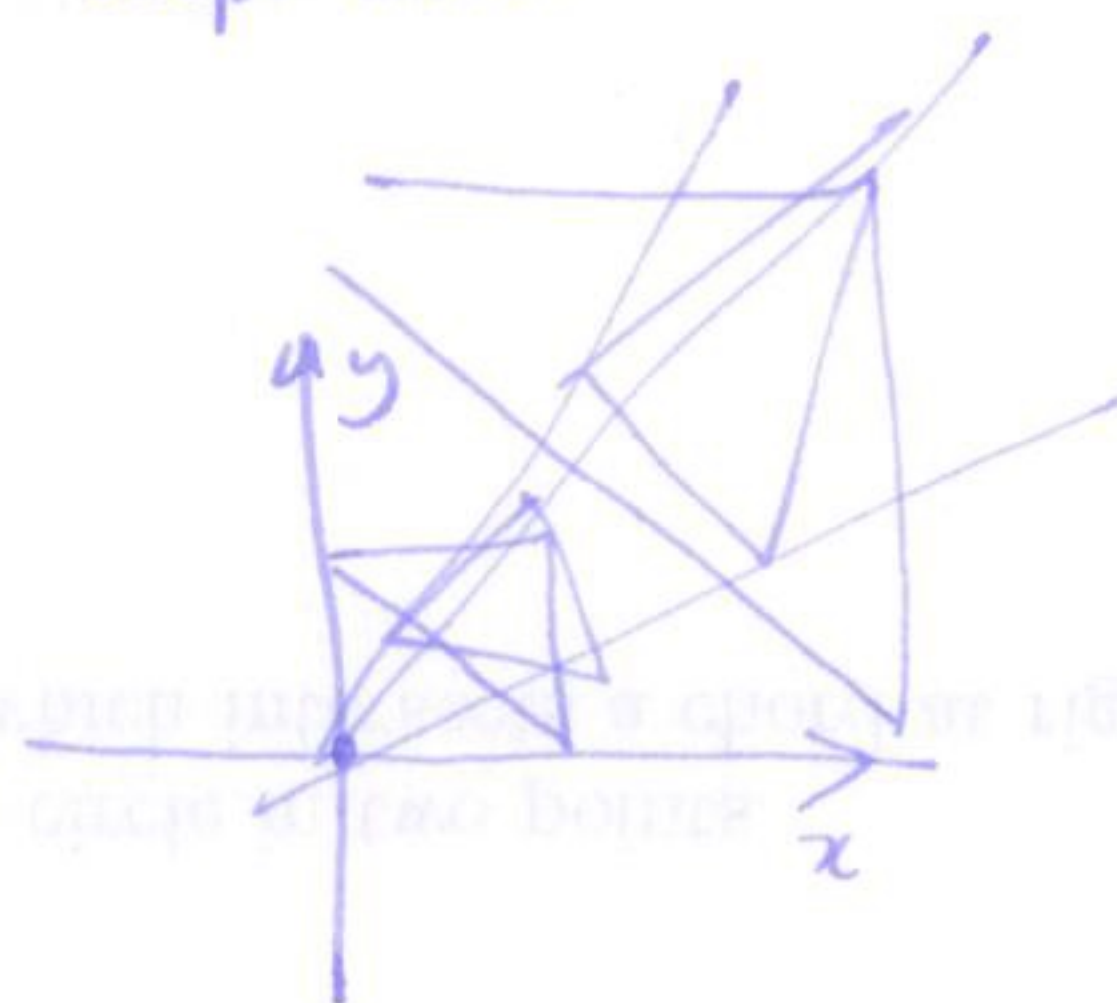
$\underline{u}, \underline{v} \in \mathbb{R}^2$ if we define $(x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$

and $a(x_1, y_1) = (ax_1, ay_1)$

geometrically: sum



parallelogram rule for vector sum.



$(x, y) \mapsto (ax, ay)$

scalar multiplication: scaling by a

Defⁿ A (real) vector space V is a set with operations of addition and scalar multiplication s.t.

- if $\underline{u}, \underline{v} \in V$ then $\underline{u} + \underline{v} \in V$ and $a\underline{u} \in V$
- there is a zero vector $\underline{0}$ s.t. $\underline{u} + \underline{0} = \underline{u}$ for all $\underline{u} \in V$

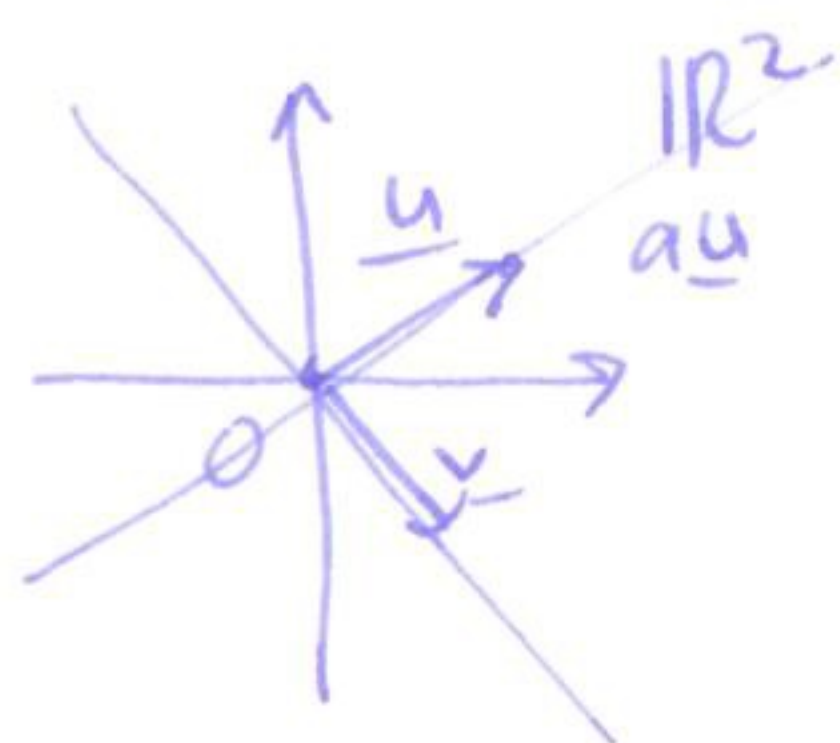
- addition and scalar multiplication have the eight properties listed above. (32)

examples $\mathbb{R}^3$: $(x_1, y_1, z_1) + (x_2, y_2, z_2) = (x_1 + x_2, y_1 + y_2, z_1 + z_2)$

$$a(x_1, y_1, z_1) = (ax_1, ay_1, az_1).$$

$\mathbb{R}^n$ similarly...

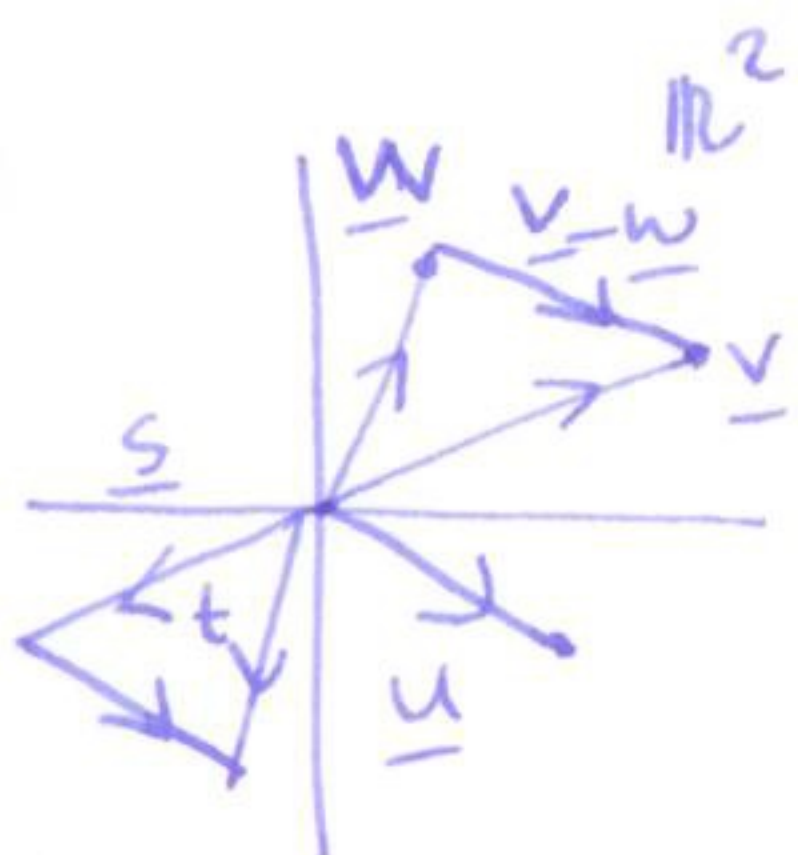
§4.2 Direction and linear independence



given a non-zero vector $\underline{u}$, the vectors $a\underline{u}$, $a \in \mathbb{R}$ gives the line through $\underline{0}$ and $\underline{u}$.

two vectors $\underline{u}, \underline{v}$ point in different directions if neither is a multiple of the other.

we say $\underline{u}, \underline{v}$ are linearly independent if there are no real numbers a, b s.t. $a\underline{u} + b\underline{v} = \underline{0}$.



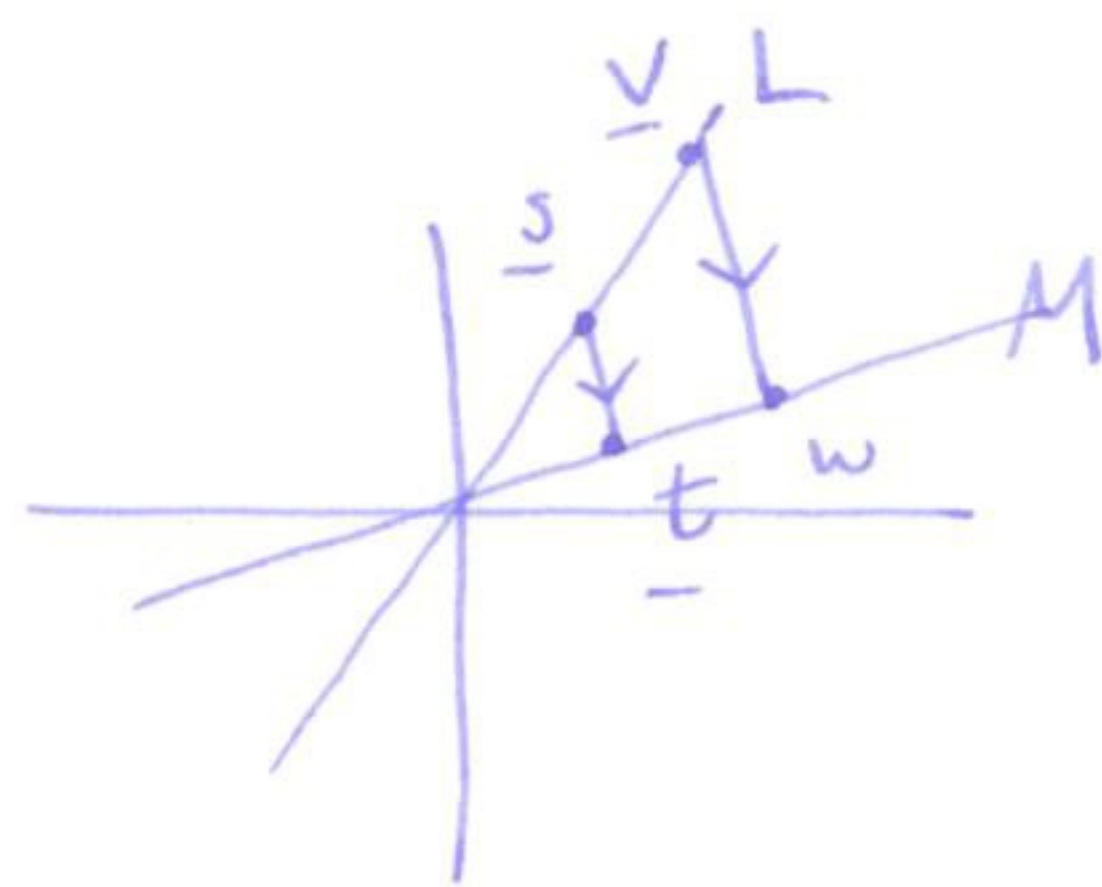
$\underline{v} - \underline{w}$ is the relative direction from $\underline{w}$ to $\underline{v}$.

two relative directions are parallel if $\underline{v} - \underline{w} = a(\underline{s} - \underline{t})$.

Thales Theorem (vector version)

if $\underline{s}, \underline{v}$ lie on a line L through $\underline{0}$ and $\underline{t}, \underline{w}$ lie on a different line M through $\underline{0}$, and $\underline{w} - \underline{v}$ is parallel to $\underline{t} - \underline{s}$, then

$\underline{v} = a\underline{s}$ and $\underline{w} = a\underline{t}$ for some number a .



Proof parallel: $\underline{w} - \underline{v} = a(\underline{t} - \underline{s})$

$\underline{s}, \underline{v}$ on same line: $\underline{v} = b\underline{s}$

$\underline{t}, \underline{w}$ on same line: $\underline{w} = c\underline{t}$