

Linear Algebra ^{Sample} Midterm 3 Solutions

①

a) choose $\underline{w}_1 = \underline{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$.

choose $\underline{w}_2 = \underline{v}_2 - \lambda \underline{v}_1$ where $\lambda = \frac{\underline{w}_1 \cdot \underline{v}_2}{\|\underline{v}_1\| \cdot \|\underline{v}_2\|} = \frac{3}{6} = \frac{1}{2}$

$$\underline{w}_2 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1/2 \\ -1/2 \\ 0 \end{bmatrix}$$

choose $\underline{w}_3 = \underline{v}_3 - \lambda_1 \underline{w}_1 - \lambda_2 \underline{w}_2$

where $\lambda_1 = \frac{\underline{v}_3 \cdot \underline{w}_1}{\underline{w}_1 \cdot \underline{w}_1} = \frac{1}{6}$ $\lambda_2 = \frac{\underline{v}_3 \cdot \underline{w}_2}{\underline{w}_2 \cdot \underline{w}_2} = \frac{-1/2}{1/2} = -1$

so $\underline{w}_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{6} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + \begin{bmatrix} -1/2 \\ -1/2 \\ 0 \end{bmatrix} = \begin{bmatrix} -2/3 \\ 2/3 \\ 2/3 \end{bmatrix}$

b) normalize : $\left\{ \begin{bmatrix} 1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix}, \begin{bmatrix} -1/\sqrt{2} \\ -1/\sqrt{2} \\ 0 \end{bmatrix}, \begin{bmatrix} -1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix} \right\}$.

Q2 a) find \underline{v} s.t. $\underline{v} \cdot \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix} = 0$ and $\underline{v} \cdot \begin{bmatrix} 2 \\ 4 \\ -2 \end{bmatrix} = 0$

i.e. solve $\begin{bmatrix} -1 & 1 & 2 & | & 0 \\ 2 & 4 & -2 & | & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & -1 & 2 & | & 0 \\ 0 & 6 & 2 & | & 0 \end{bmatrix}$

$\rightsquigarrow \begin{bmatrix} 1 & 0 & 7/3 & | & 0 \\ 0 & 1 & 1/3 & | & 0 \end{bmatrix}$ $\underline{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ then $z = t$
 $y = -1/3 t$
 $x = -7/3 t$

so solns are: $t \begin{bmatrix} 7 \\ 1 \\ -3 \end{bmatrix}$

so $\left\{ \begin{bmatrix} 7 \\ 1 \\ -3 \end{bmatrix} \right\}$ is a basis for V^\perp .

b) $A = P^{-1} D P$ D upper triangular $A^2 \underline{v} = \lambda \underline{v} = A^T \underline{v}$
 $A^2 = P^{-1} D^2 P$ if \underline{v} eigenvector.
 $A^T = P^T D^T P^{-1}$ D^T lower triangular.

$\Rightarrow D^2 = (P P^T) D^T (P P^T)^{-1}$ similar so if eigenvalues

for A $\{\lambda_1, \dots, \lambda_n\}$ then $\{\lambda_1^2, \dots, \lambda_n^2\}$ also eigenvalues.

\Rightarrow all eigenvalues roots of unity.

Q3
 a) $A = \begin{bmatrix} 3 & 1 \\ -5 & -3 \end{bmatrix}$ $\det(A - \lambda I) = (3 - \lambda)(-3 - \lambda) + 5$

$\lambda^2 - 4 = 0$ $\lambda = \pm 2$

b) $\begin{bmatrix} 1 & 1 & | & 0 \\ -5 & -5 & | & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is eigenvector corresponding to +2.

$\begin{bmatrix} 5 & 1 & | & 0 \\ -5 & 1 & | & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 \\ -5 \end{bmatrix}$ is eigenvector corresponding to -2.

so $\begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix} = P^{-1}AP$ where $P = \begin{bmatrix} 1 & 1 \\ -1 & -5 \end{bmatrix}$

c) $D^k = \begin{bmatrix} 2^k & 0 \\ 0 & (-2)^k \end{bmatrix}$

$A^k = P D^k P^{-1} = \begin{bmatrix} 1 & 1 \\ -1 & -5 \end{bmatrix} \begin{bmatrix} 2^k & 0 \\ 0 & (-2)^k \end{bmatrix} \begin{bmatrix} -5 & -1 \\ 1 & 1 \end{bmatrix} \cdot \frac{1}{4}$

$= -\frac{1}{4} \begin{bmatrix} 2^k & (-2)^k \\ -2^k & -5(-2)^k \end{bmatrix} \begin{bmatrix} -5 & -1 \\ 1 & 1 \end{bmatrix} = -\frac{1}{4} \begin{bmatrix} -5 \cdot 2^k + (-2)^k & -2^k + (-2)^k \\ +5 \cdot 2^k - 5(-2)^k & 2^k - 5(-2)^k \end{bmatrix}$

d) 2^k and $(-2)^k$

Q4

a) row reduce :

$$\begin{bmatrix} 1 & 0 & -2/3 & 1/3 & 0 \\ 0 & 1 & 7/3 & 1/3 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$\text{rank}(A) = 2$ (row rank = rank).

$\text{nullity}(A) = 3$ (rank nullity formula: $\text{rank}(A) + \text{nullity}(A) = \# \text{cols}$)
 $2 + \text{nullity}(A) = 5$.

b) orthogonal complement of null space = row space

has basis $\left\{ \begin{bmatrix} 1 \\ 0 \\ -2/3 \\ 1/3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 7/3 \\ 1/3 \\ 3 \end{bmatrix} \right\}$.

Q5 a) $\{1, t, t^2, t^3, t^4\}$.

b) yes. suppose $c_1(t^4+1) + c_2(t^3+t) + c_3(t^2) = 0$

$$c_1 t^4 + c_2 t^3 + c_3 t^2 + c_2 t + c_1 = 0 \text{ polynomial.}$$

\Rightarrow all $c_i = 0$.

c) which inner product? how about silly inner product $p \cdot q = \sum p_i q_i$

where $p = p_0 + p_1 t + \dots + p_4 t^4$ etc.

then want p s.t. $p \cdot 1 = 0, p \cdot t = 0, p \cdot t^2 = 0, p \cdot t^3 = 0$.

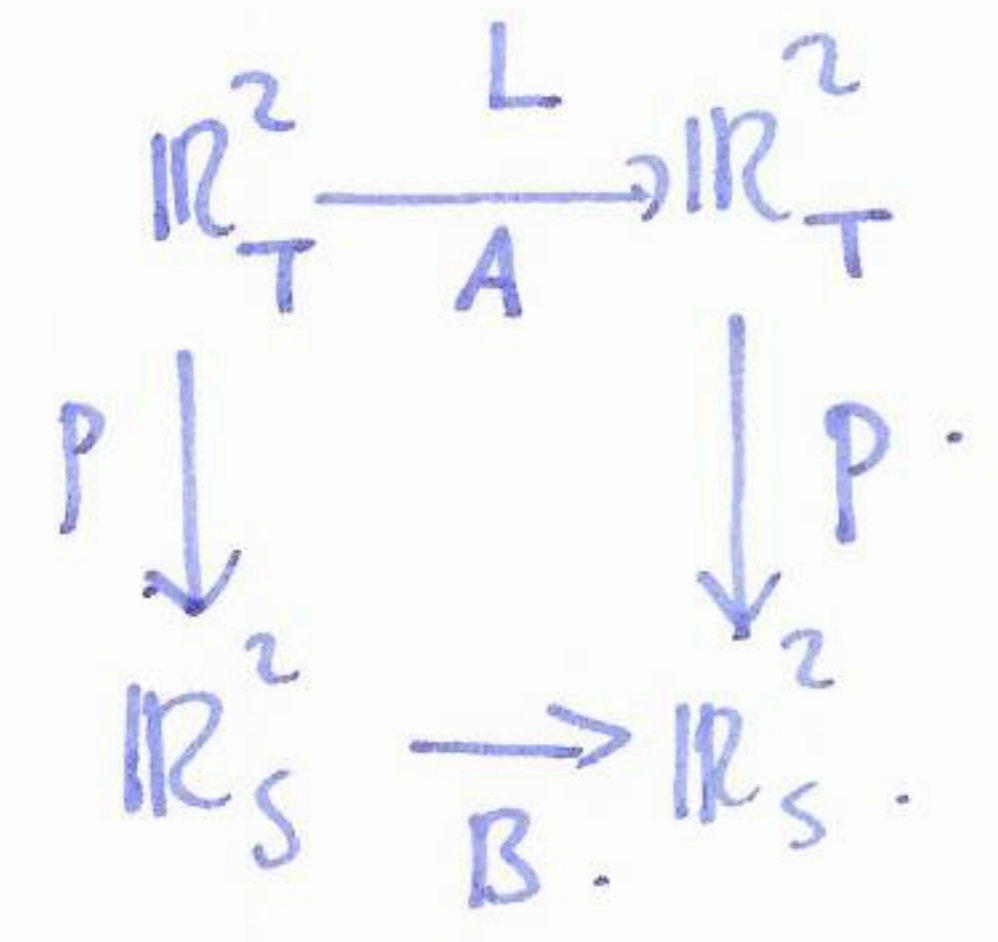
i.e. $p_0 = 0, p_1 = 0, p_2 = 0, p_3 = 0$

so orthogonal complement has basis $\{t^4\}$.

Q6 $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad L(x, y) = (x - 2y, x + 2y)$

a) $A = \begin{bmatrix} 1 & -2 \\ 1 & 2 \end{bmatrix}$

b) $P_{T \leftarrow S} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} = P$



~~B~~ $B = P \begin{bmatrix} 1 & -2 \\ 1 & 2 \end{bmatrix} P^{-1}$

$$= \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -2 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & -2 \\ 4 & 4 \end{bmatrix}$$

c) $\text{rank}(A) = \text{rank}(\text{ref}(A)) = \text{rank} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 2$

$\text{rank}(A) + \text{nullity}(A) = 2 \Rightarrow \text{nullity} = 0.$

$\dim(\text{Im}(L)) = \dim(\mathbb{R}^2) - \dim(\text{Ker}(L))$
 (2) (1) basis, γραμ. τις προκύπτει απευθείας

Q7

a)

$$\begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

b)

$$(\cos\theta - \lambda)(\cos\theta - \lambda) + \sin^2\theta = 0$$

$$\lambda^2 - 2\lambda \cos\theta + \cos^2\theta + \sin^2\theta = 0$$

$$\lambda^2 - 2\lambda \cos\theta + 1 = 0$$

$$\lambda = \frac{2\cos\theta \pm \sqrt{4\cos^2\theta - 4}}{2} = \cos\theta \pm i\sin\theta$$

$\lambda = \cos\theta + i\sin\theta$:

$$\begin{bmatrix} -i\sin\theta & -\sin\theta \\ \sin\theta & -i\cos\theta \end{bmatrix}$$

eigenvector

$$\begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$\lambda = \cos\theta - i\sin\theta$:

$$\begin{bmatrix} i\sin\theta & -\sin\theta \\ \sin\theta & i\cos\theta \end{bmatrix}$$

eigenvector

$$\begin{bmatrix} 1 \\ i \end{bmatrix}$$

(5) (10 marks) If $\lambda(x) = \frac{x+1}{x-2}$ and $\lambda^{-1}(x) = \dots$

Q8

a) $\det(A - \lambda I_3)$ is a cubic polynomial, always has at least one real root.

b) every rotation in \mathbb{R}^3 preserves a direction (axis).

c)

$$\begin{bmatrix} \cos\theta & -\sin\theta & 0 & 0 \\ \sin\theta & \cos\theta & 0 & 0 \\ 0 & 0 & \cos\theta & -\sin\theta \\ 0 & 0 & \sin\theta & \cos\theta \end{bmatrix}$$

d) rotations in \mathbb{R}^4 don't need to fix a direction.