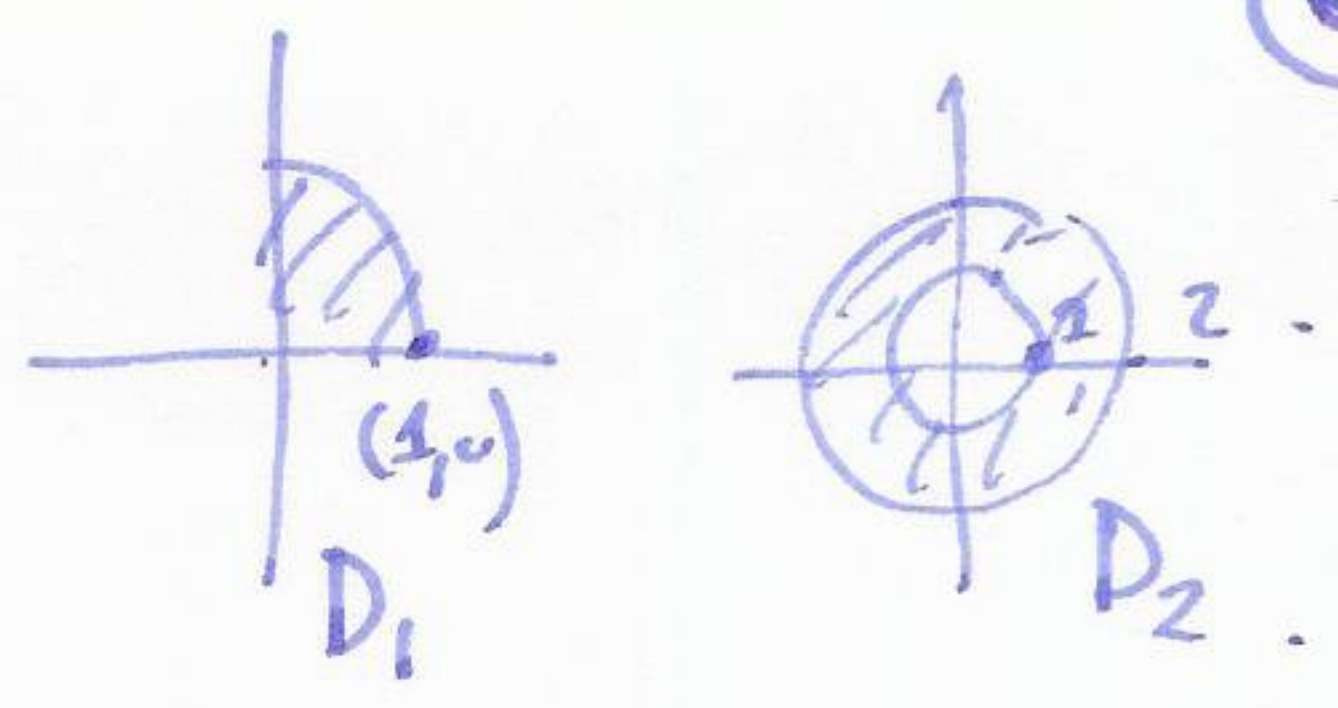


§14.3 Polar coordinates

double integrals over regions $\iint_D f(x,y) dA$
 some regions hard to describe in cartesian
 coordinates, but easy to describe in polars.

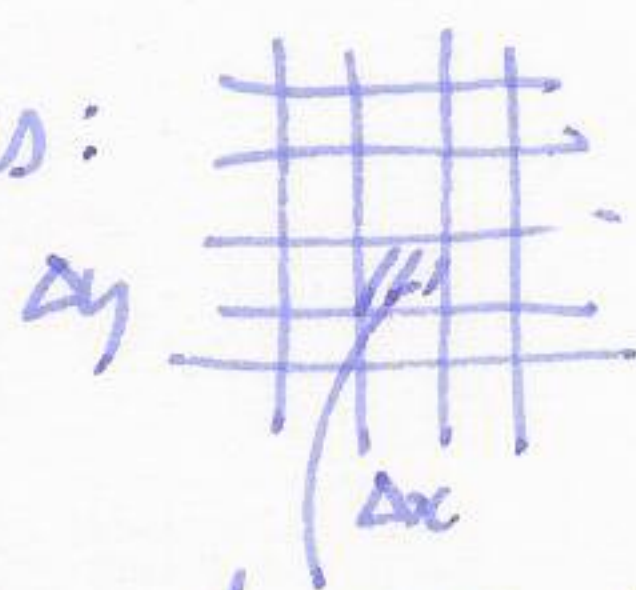


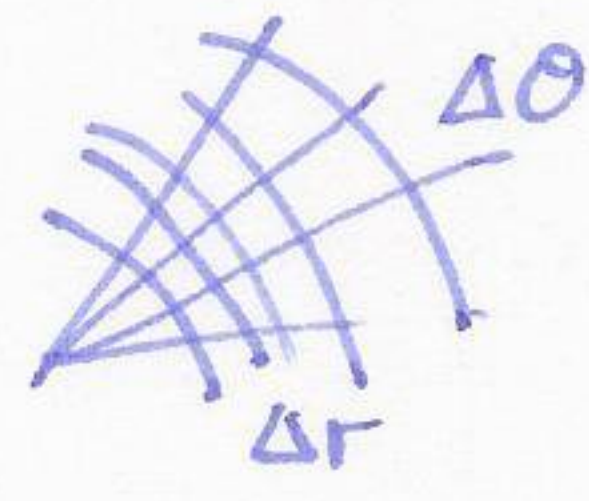
$D_1 : 0 \leq \theta \leq \pi/4 \quad 0 \leq r \leq 1$

$D_2 : 0 \leq \theta < 2\pi \quad 1 \leq r \leq 2$

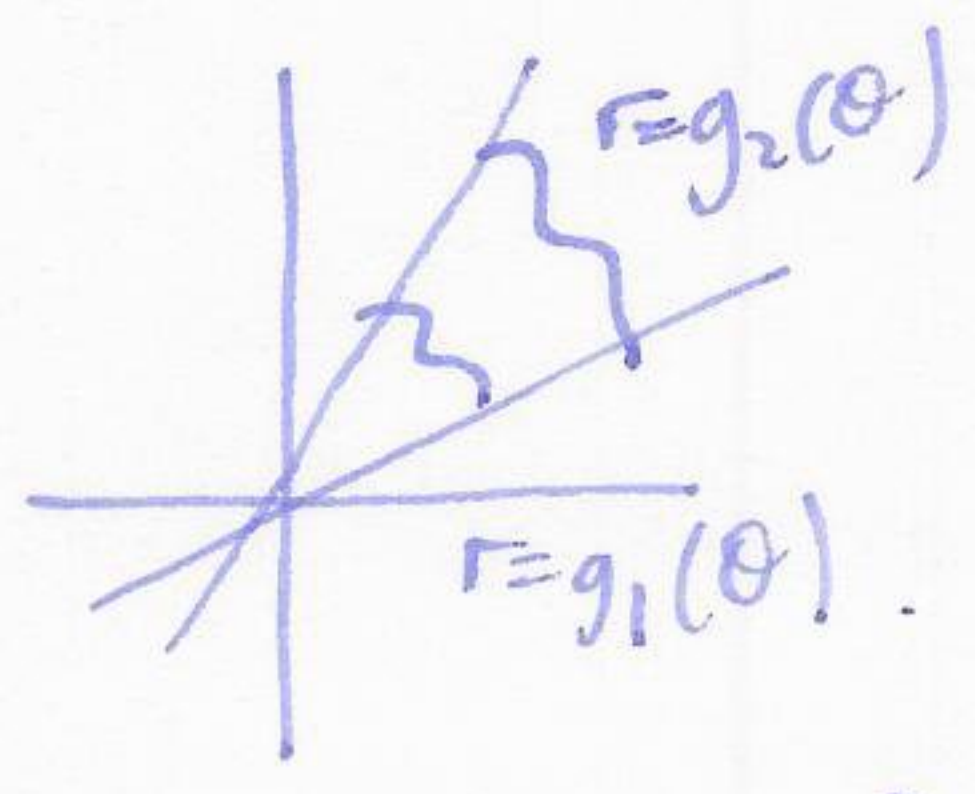
Useful fact : in polar coords $\iint_D f(x,y) dA = \iint_D f(x(r,\theta), y(r,\theta)) r dr d\theta$

$dA = r dr d\theta$ do not forget the r .

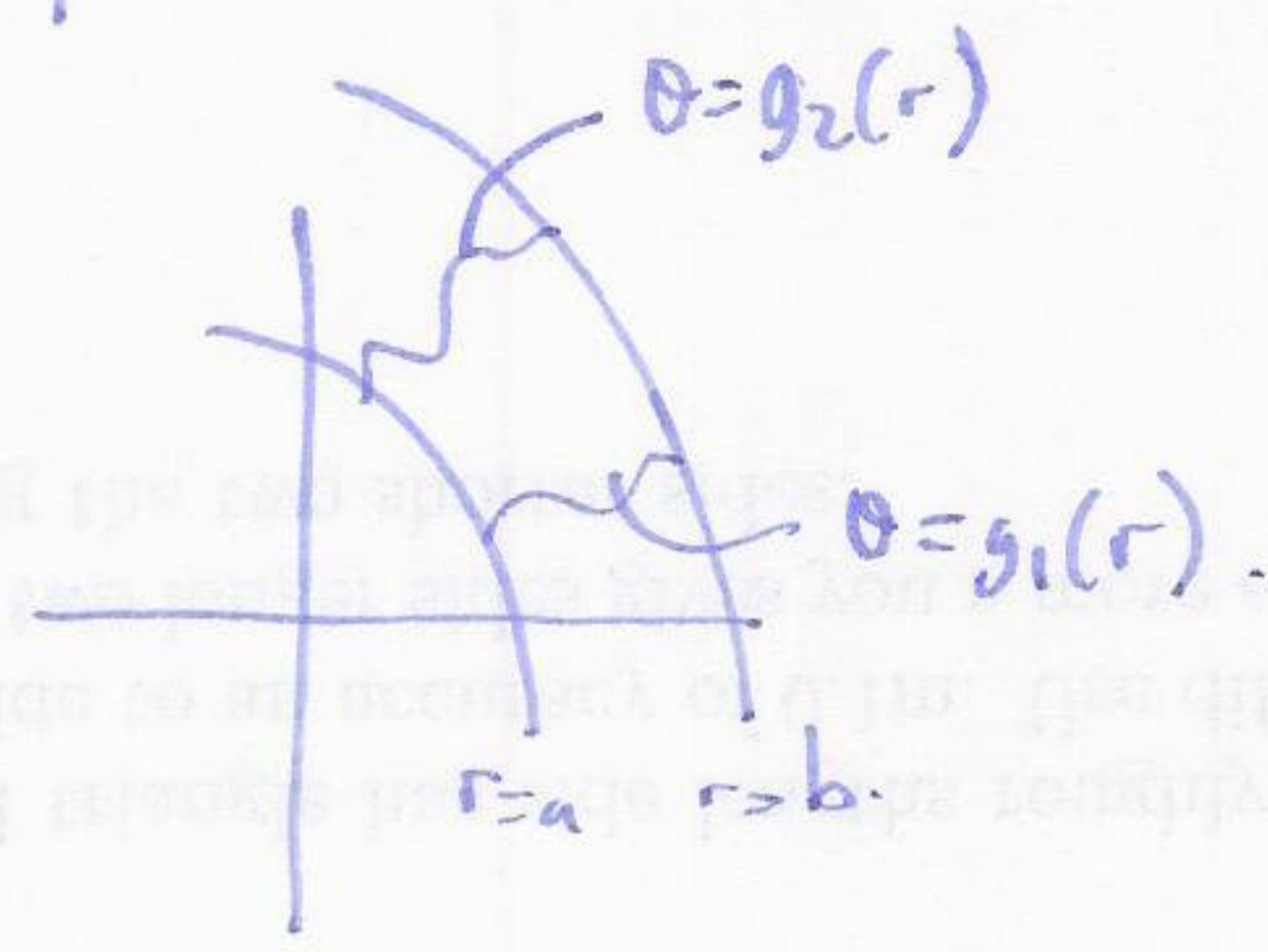
idea : cartesian: 
 each square of size $\Delta x \times \Delta y$

polars : 
 regions of different size
 size approximately $r \Delta r \Delta \theta$.

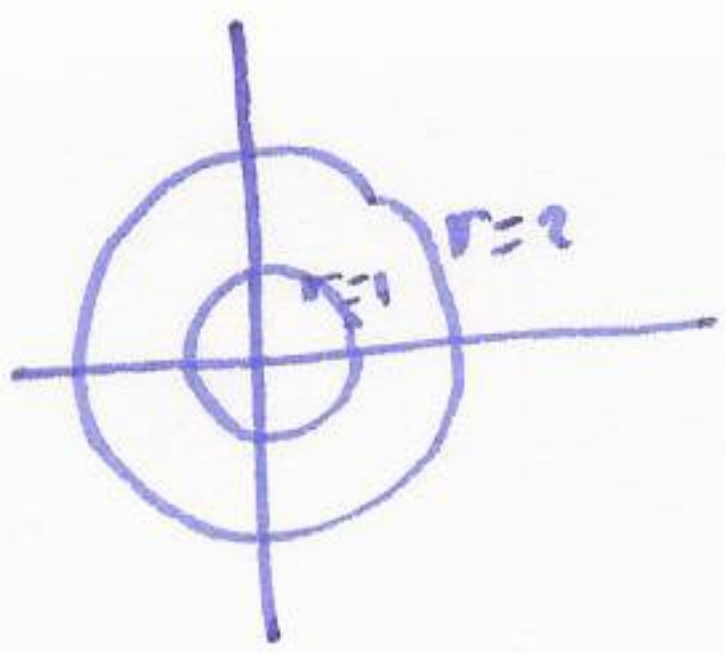
$\int_a^b \int_{g_1(\theta)}^{g_2(\theta)} r dr d\theta$



$\int_a^b \int_{g_1(r)}^{g_2(r)} r d\theta dr$



area $r \Delta \theta$
 $(r + \Delta r) \Delta \theta - r \Delta \theta = \Delta r \Delta \theta$
 $= r \Delta r \Delta \theta$

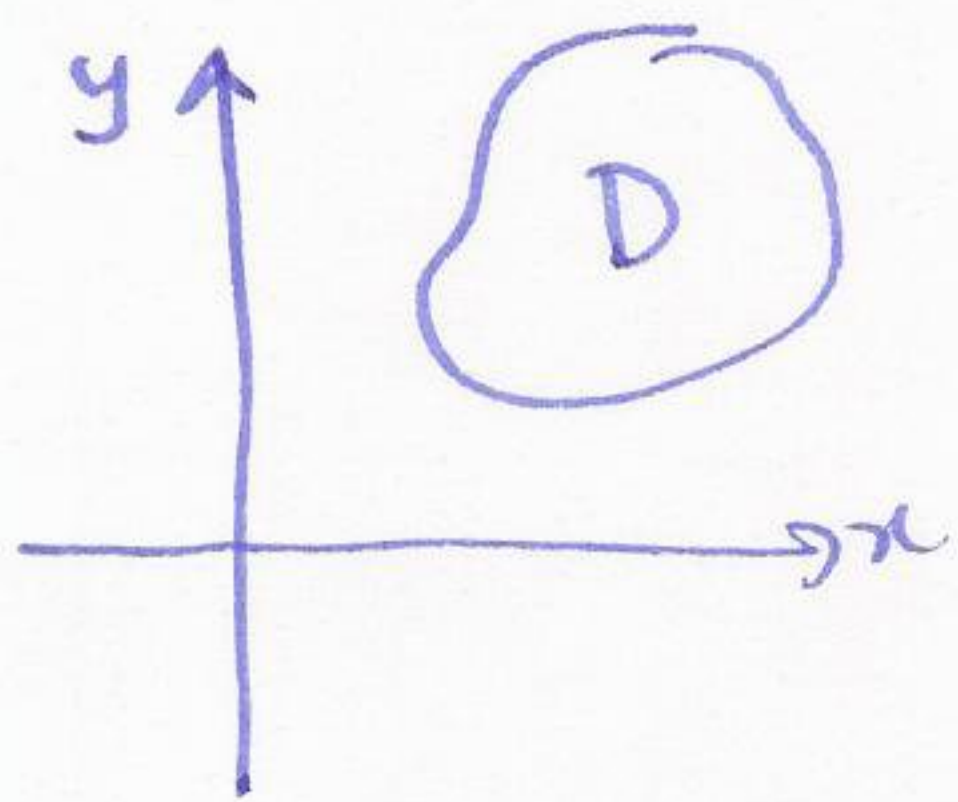
Example

$$\iint_D x^2 + y^2 dA$$

$$\int_0^{2\pi} \int_1^2 r^2 r dr d\theta$$

$$\left[\frac{1}{4} r^4 \right]_1^2 = \frac{1}{4} (16 - 1)$$

$$\int_0^{2\pi} \frac{15}{4} d\theta = \frac{15\pi}{2}$$

§14.4 Centers of mass

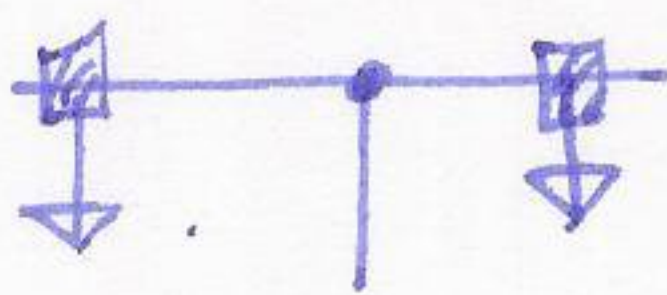
$\rho(x, y)$ = density of region D.



$$\text{mass } m = \iint_D \rho(x, y) dA$$

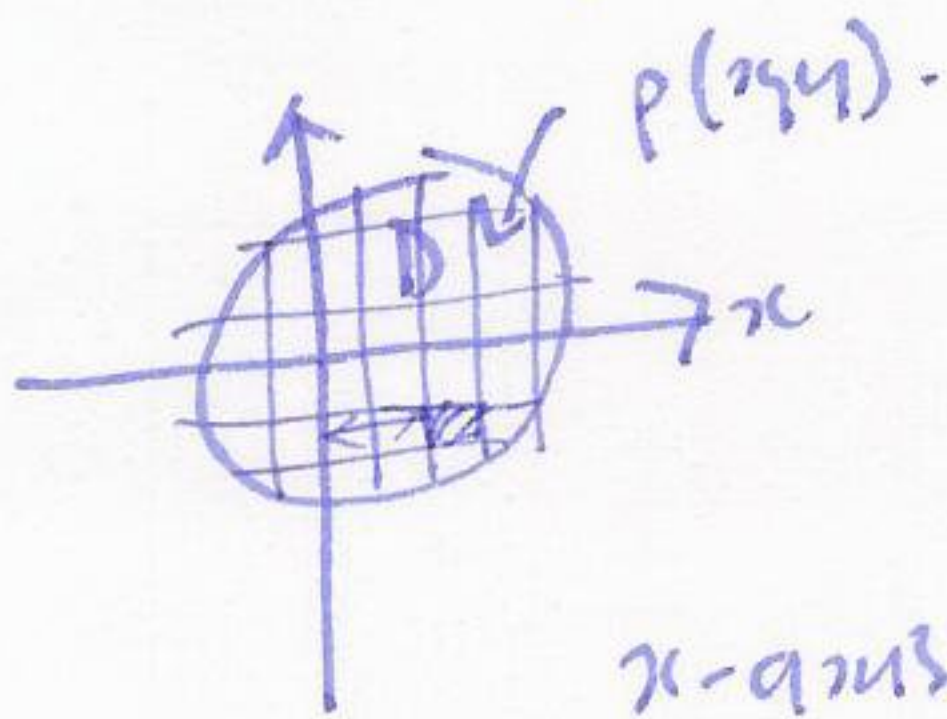
moment, turning force

1d:



turning force = force $\times$ distance

2d



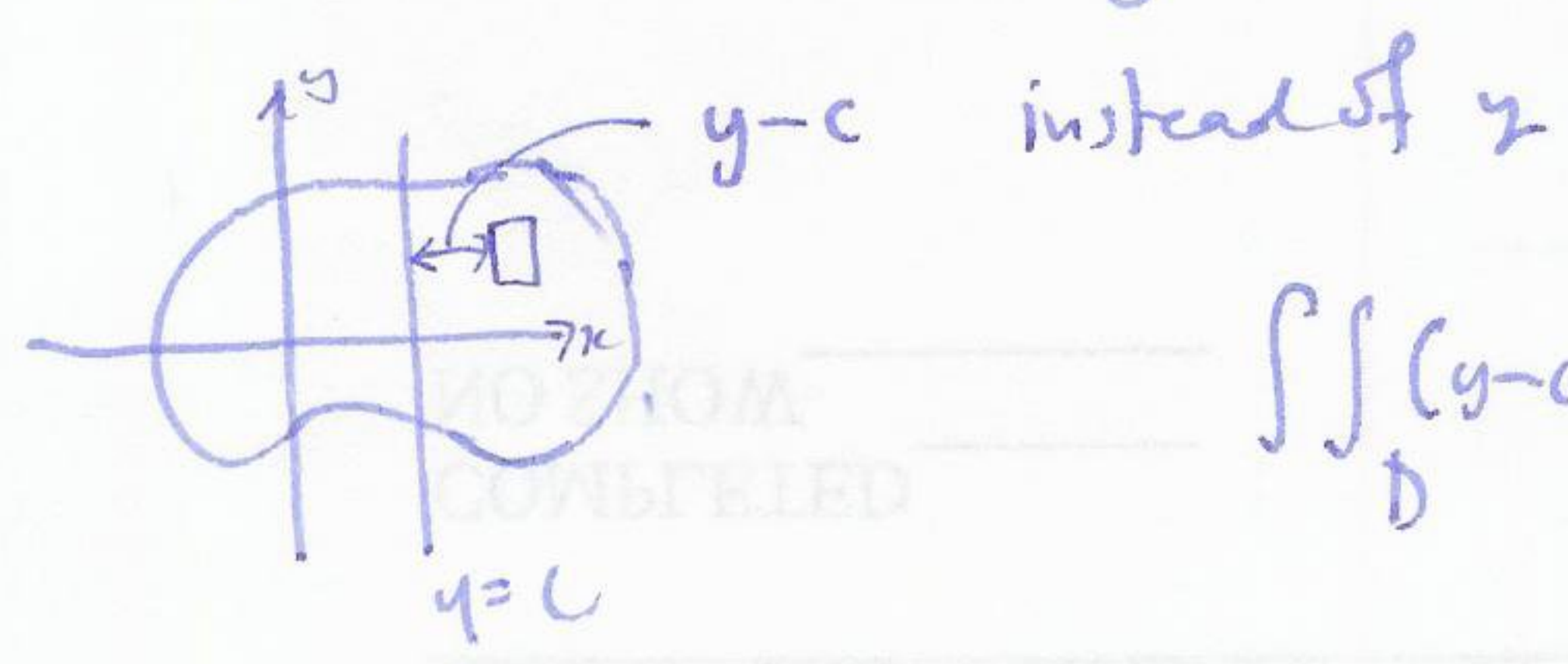
turning force/moment about x-axis

x-axis: $M_x = \iint_D y \rho(x, y) dA$

y-axis: $M_y = \iint_D x \rho(x, y) dA$

center of mass: $(\bar{x}, \bar{y}) = \left(\frac{M_y}{m}, \frac{M_x}{m} \right)$ m = total mass.

moment about x-axis $\leftrightarrow y=0$. what about moment about $y=c$?



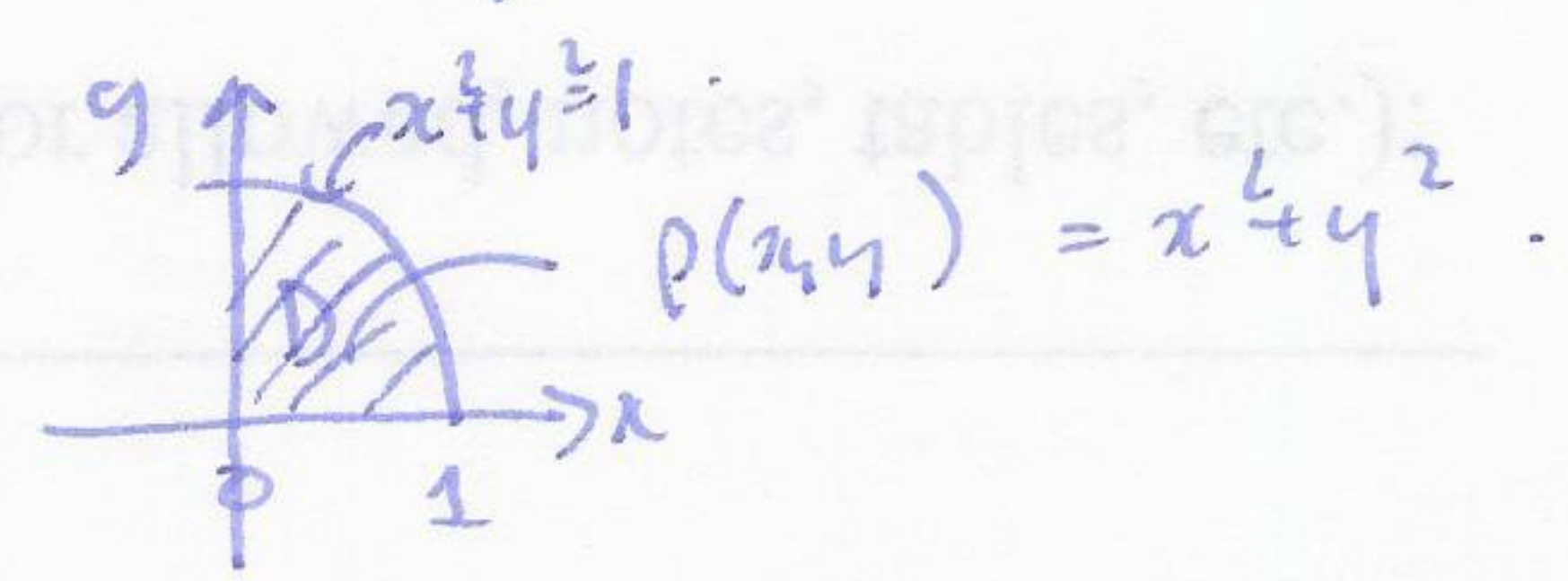
$$\iint_D (y-c) \rho dA = \iint_D y \rho dA - \iint_D c \rho dA$$

$$= M_x - cM = 0$$

↑ balanced.

$$\Rightarrow c = \frac{M_x}{M}$$

Example find center of mass of



$$M = \iint_D (x^2+y^2) dA \quad M_x = \iint_D y(x^2+y^2) dA \quad M_y = \iint_D x(x^2+y^2) dA$$

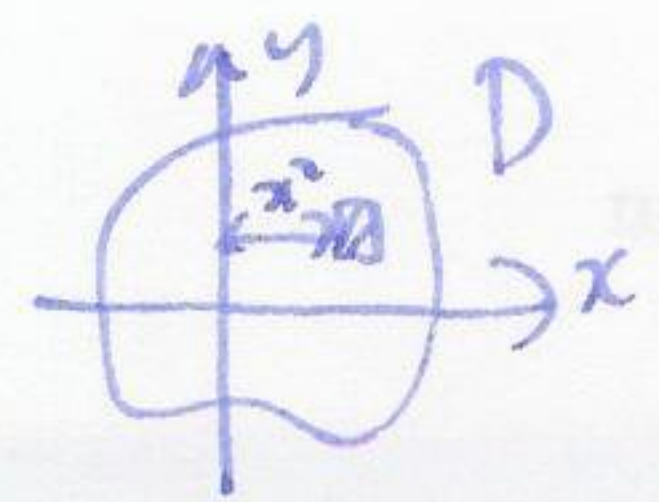
$$M = \int_0^1 \int_0^{\sqrt{1-x^2}} (x^2+y^2) dy dx = \int_0^{\pi/2} \int_0^1 r^2 \cdot r dr d\theta = \frac{\pi}{2} \left[\frac{1}{4} r^4 \right]_0^1 = \frac{\pi}{8}$$

$$M_x = \int_0^{\pi/2} \int_0^1 r \sin \theta \cdot r^2 \cdot r dr d\theta = \int_0^{\pi/2} \int_0^1 r^4 dr d\theta = \left[\frac{1}{5} r^5 \right]_0^1 = \frac{1}{5}$$

$$\frac{1}{5} \int_0^{\pi/2} \sin \theta d\theta = \frac{1}{5} [-\cos \theta]_0^{\pi/2} = \frac{1}{5} (-0 + 1) = \frac{1}{5} \cdot \left(\frac{8}{5\pi} \mid \frac{8}{5\pi} \right)$$

Moment of inertia / angular momentum.

1d angular momentum = $d^2 \times \text{force}$.



$$I_y = \iint_D x^2 \rho dA \quad I_x = \iint_D y^2 \rho dA$$