

General case $w = f(x_1, \dots, x_n)$ & $x_1(t_1, \dots, t_m)$
 \vdots
 $x_n(t_1, \dots, t_m)$

$$\frac{\partial w}{\partial t_j} = \frac{\partial w}{\partial x_1} \frac{\partial x_1}{\partial t_j} + \frac{\partial w}{\partial x_2} \frac{\partial x_2}{\partial t_j} + \dots + \frac{\partial w}{\partial x_n} \frac{\partial x_n}{\partial t_j}$$

matrix notation:

$$\frac{\partial w}{\partial t_j} = \sum_i \frac{\partial w}{\partial x_i} \frac{\partial x_i}{\partial t_j}$$

$$\frac{\partial w}{\partial t_m} = \frac{\partial w}{\partial x_1} \frac{\partial x_1}{\partial t_m} + \dots + \frac{\partial w}{\partial x_n} \frac{\partial x_n}{\partial t_m}$$

example $f(xyz, t) = xyz$ $x = \text{scost}$
 $y = \text{ssint}$
 $z = t$

$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial s}$$

$$= yz \text{cost} + xz \text{ssint} + yz \cdot 0 = st \text{ssint cost} + st \text{cost ssint}$$

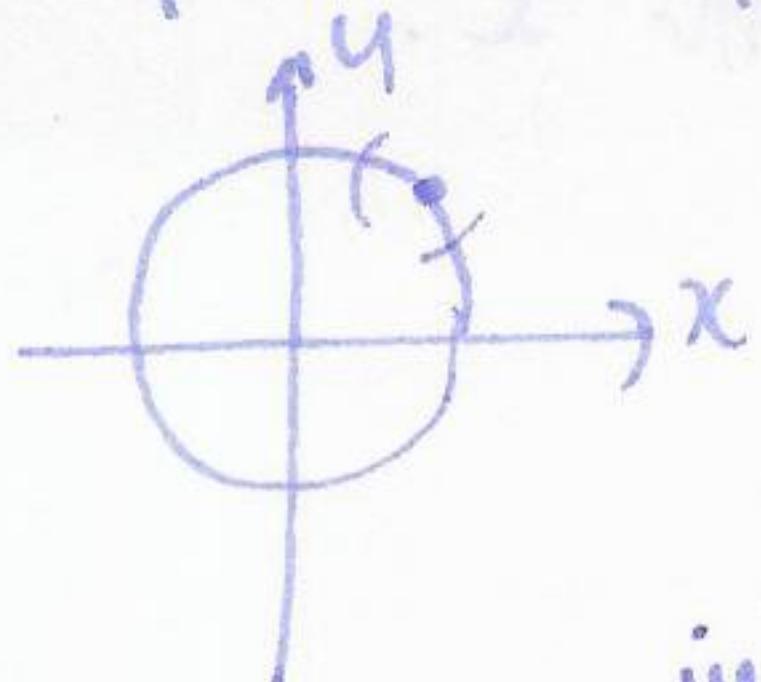
$$= 2st \text{ssint cost}$$

Implicit partial differentiation

we know how to differentiate function how can we differentiate equations?

Example $x^2 + y^2 = 1$. ← equation, but implicitly defines a function

really near most points (x, y) .



$w = F(x, y) = 0$ (where $F = x^2 + y^2 - 1$ in this example).

imagine y is a function of x . $y = f(x)$.

$$w = F(x, f(x)) = 0$$

apply chain rule:

$$\frac{dw}{dx} = \frac{\partial F}{\partial x} \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx}$$

"! "!

so $F_x + F_y \frac{dy}{dx} = 0$ i.e. $\frac{dy}{dx} = - \frac{F_x}{F_y}$ ($F_y \neq 0$).

Example $F(x, y) = x^2 + y^2 - 1$.

$$\frac{dy}{dx} = - \frac{2x}{2y} = - \frac{x}{y}.$$

3 vars $F(x, y, z) = 0$ suppose this defines $z(x, y)$.

i.e. $w = F(x, y, z(x, y))$

$$\frac{\partial w}{\partial x} = F_x \underbrace{\frac{\partial x}{\partial x}}_1 + F_y \underbrace{\frac{\partial y}{\partial x}}_0 + F_z \underbrace{\frac{\partial z}{\partial x}}_? \quad \text{so} \quad \frac{\partial z}{\partial x} = - \frac{F_x}{F_z} \quad (F_z \neq 0)$$

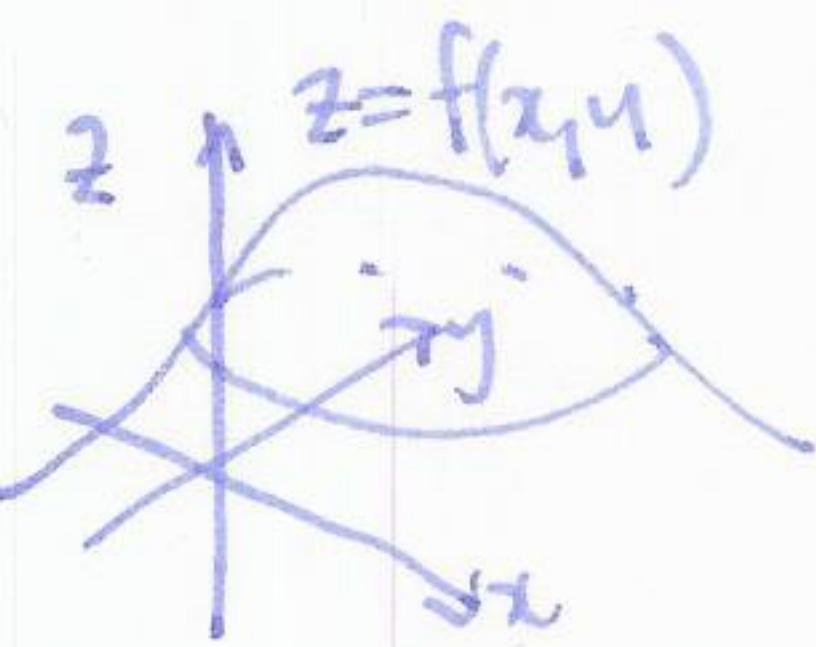
similarly $\frac{\partial z}{\partial y} = - \frac{F_y}{F_z}$.

Example $x^2 + y^2 + z^2 = 1$



$$\frac{\partial z}{\partial x} = - \frac{2x}{2z} \quad \frac{\partial z}{\partial y} = - \frac{2y}{2z}$$

§13.6 Gradient / directional derivatives



$\frac{\partial f}{\partial x}$ = rate of change in x-direction.

$\frac{\partial f}{\partial y}$ = rate of change in y-direction.

Q: what about rate of change in some other direction?

specify direction with unit vector $\underline{v} = \langle \cos\theta, \sin\theta \rangle$.

assume $f(x,y)$ differentiable, so tangent plane is good approximation.

(53)



$\frac{\partial f}{\partial x}$ = slope of tangent plane in x -direction

$\frac{\partial f}{\partial y}$ = slope of tangent plane in y -direction

so. equation for tangent plane is $z = f(x_0, y_0) + f_x(x_0, y_0)(x-x_0) + f_y(x_0, y_0)(y-y_0)$.

so what's the slope in direction \underline{v} ? plug in $x = x_0 + \cos\theta$
 $y = y_0 + \sin\theta$.

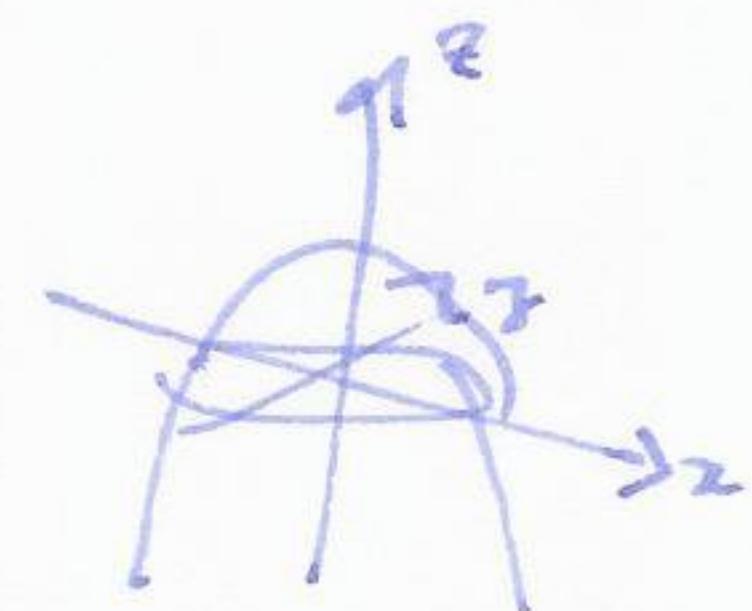
get: $\Delta z = f_x(x_0, y_0) \cos\theta + f_y(x_0, y_0) \sin\theta$.

Defn: The directional derivative is

$$D_{\underline{v}} f(x_0, y_0) = f_x(x_0, y_0) \cos\theta + f_y(x_0, y_0) \sin\theta \quad \textcircled{*}$$

Example $f(x,y) = 1 - x^2 - y^2$.

direction $\theta = \frac{\pi}{4}, \langle \cos\frac{\pi}{4}, \sin\frac{\pi}{4} \rangle$.



$$D_{\underline{v}} f(x_0, y_0) = -2x \cos\frac{\pi}{4} - 2y \sin\frac{\pi}{4}$$

Observation $\textcircled{*}$ looks like a dot product.

$$D_{\underline{v}} f(x_0, y_0) = \langle f_x(x_0, y_0), f_y(x_0, y_0) \rangle \cdot \underbrace{\langle \cos\theta, \sin\theta \rangle}_{\underline{v}}$$

Defn: The gradient vector is $\underline{\nabla} f = \langle f_x, f_y \rangle$.

$$D_{\underline{v}} f = \underline{\nabla} f \cdot \underline{v}$$

Important properties

- the gradient vector points in the direction of greatest increase.
- the length of the gradient vector is the rate of change in the direction of greatest increase.

Proof

$$D_{\underline{v}} f = \nabla f \cdot \underline{v} = \|\nabla f\| \|\underline{v}\| \cos\theta = \|\nabla f\| \cos\theta$$

$= 1$

max value of $\cos\theta = 1$ when $\theta = 0$.

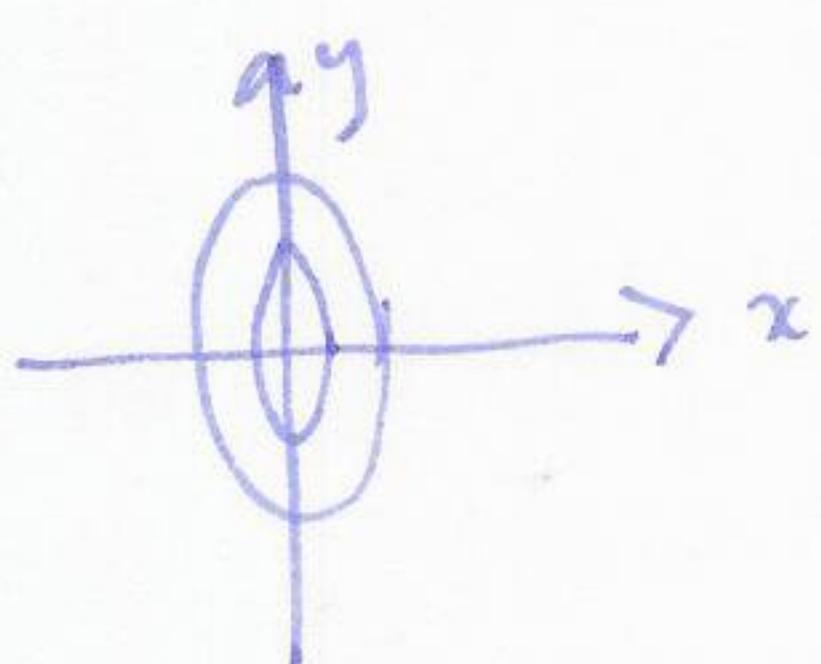
then $\|D_{\underline{v}} f\| = \|\nabla f\|$ in that special direction. \square .

Observation • $-\nabla f$ gives direction of greatest decrease.

• if $\nabla f = \underline{0}$ then $D_{\underline{v}} f = 0$ for all \underline{v} .

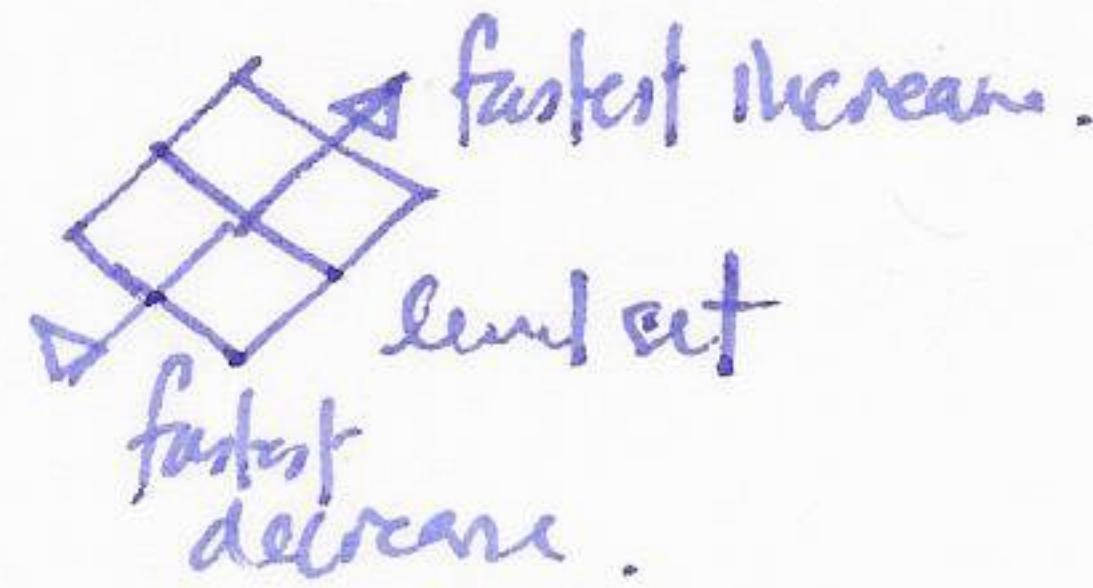
Example on the ellipse: $z = 4 - 4x^2 - y^2$ what's the fastest way down?

$$\nabla f = \langle -8x, -2y \rangle$$

Gradient vector and contour lines

The gradient vector is perpendicular to the contour lines / level sets.

linear approx:



tangent plane: $z = f_x(x_0, y_0)(x - x_0) + f_y(y_0, x_0)(y - y_0)$ normal vector $\langle f_x, f_y, -1 \rangle$