

Math 233 Calculus III

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prerequisites : Calc I, II derivatives, integrals, etc.

- Math tubing : 1S-214

- Students with disabilities.

Text : Calculus ^{Larson}_{Hostetler, Edwards} 8th edition.

§ 11.1 Vectors in the plane

scalar / number

size only $(7, 4 \cdot 3)$

examples : temperature
pressure
time

speed = length of
velocity vector

vector

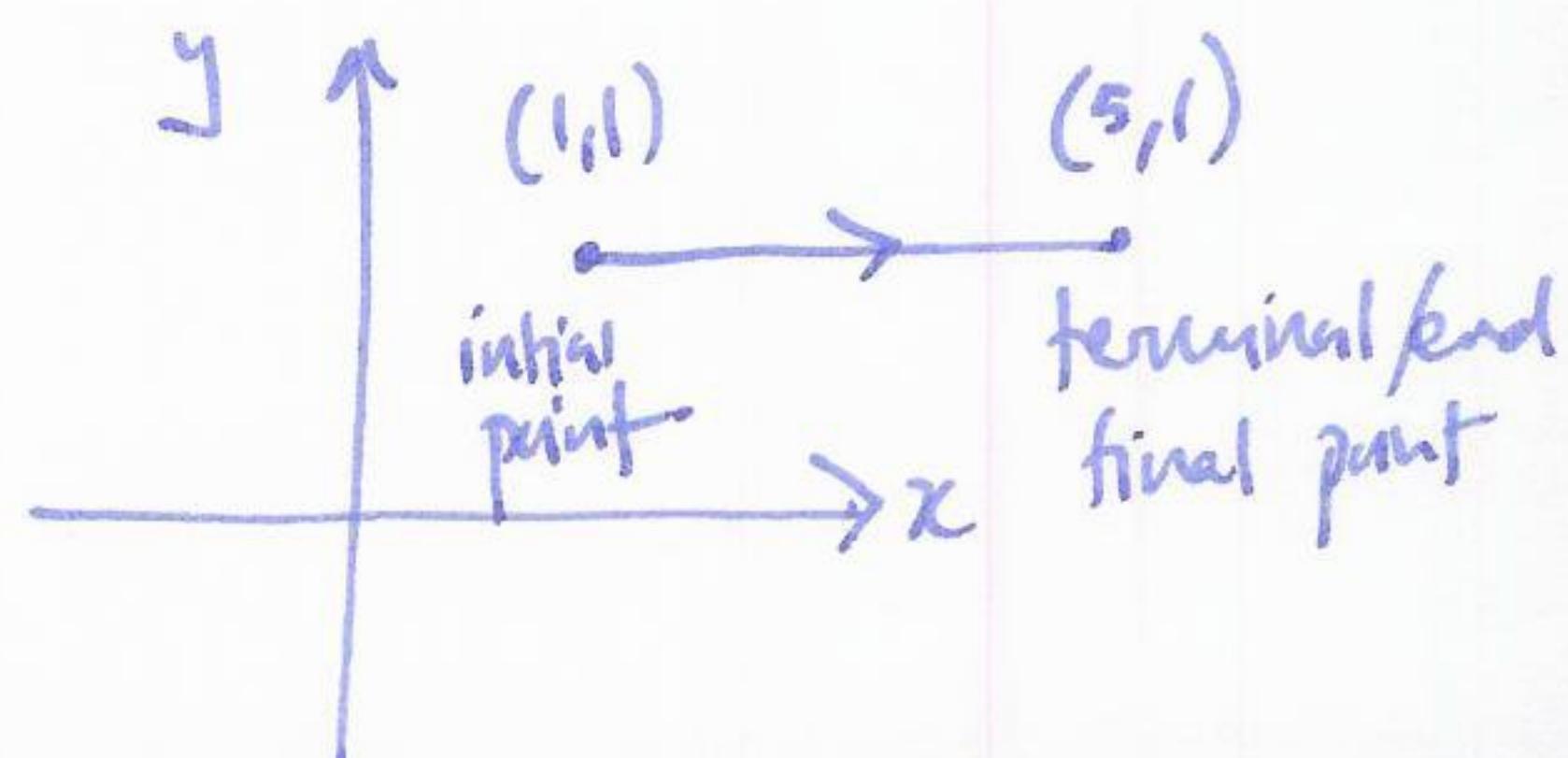
size and direction

examples : force
velocity

\underline{v} \overrightarrow{v}

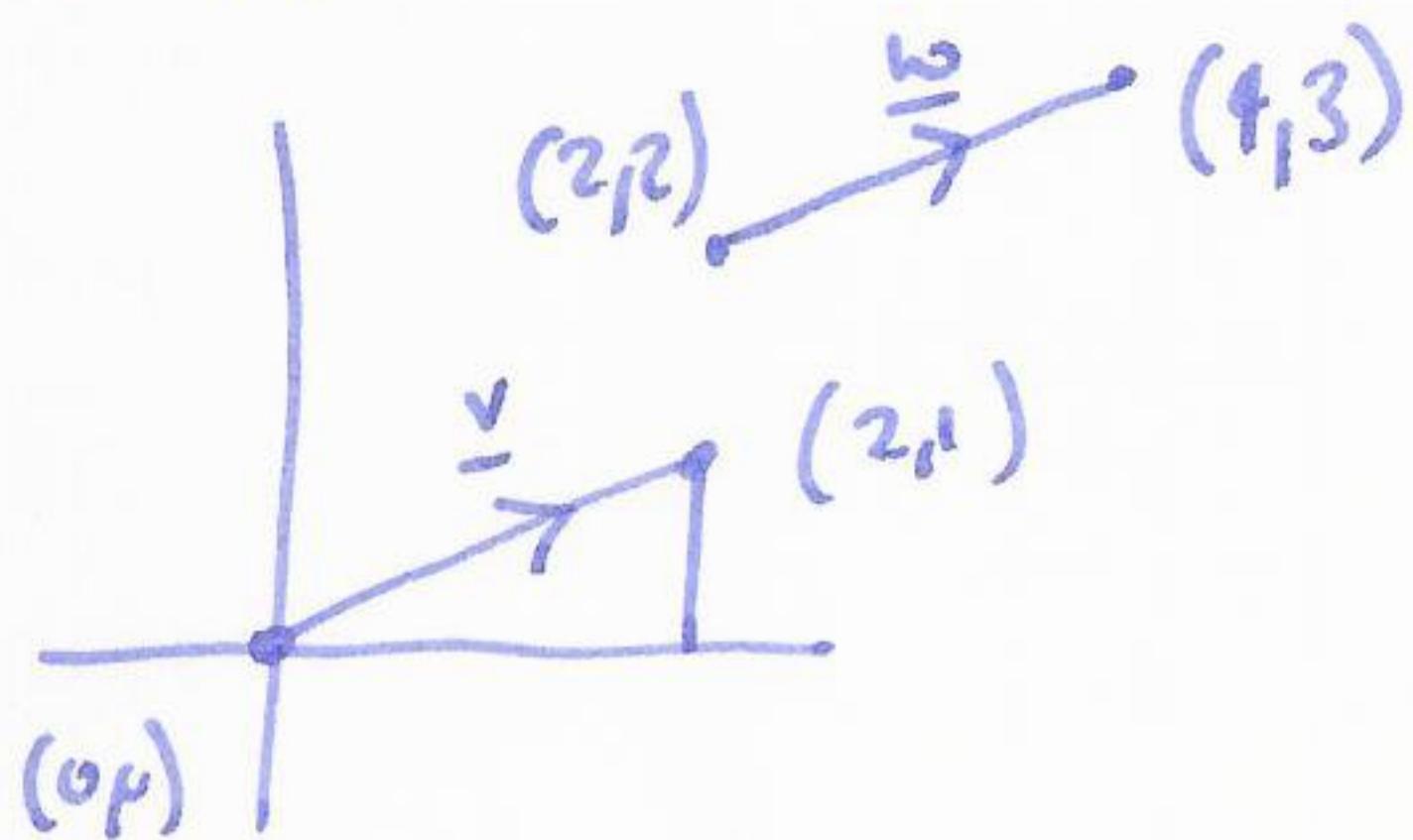
"length 4, in direction of x-axis"

picture



- two vectors with the same length and direction are equal.

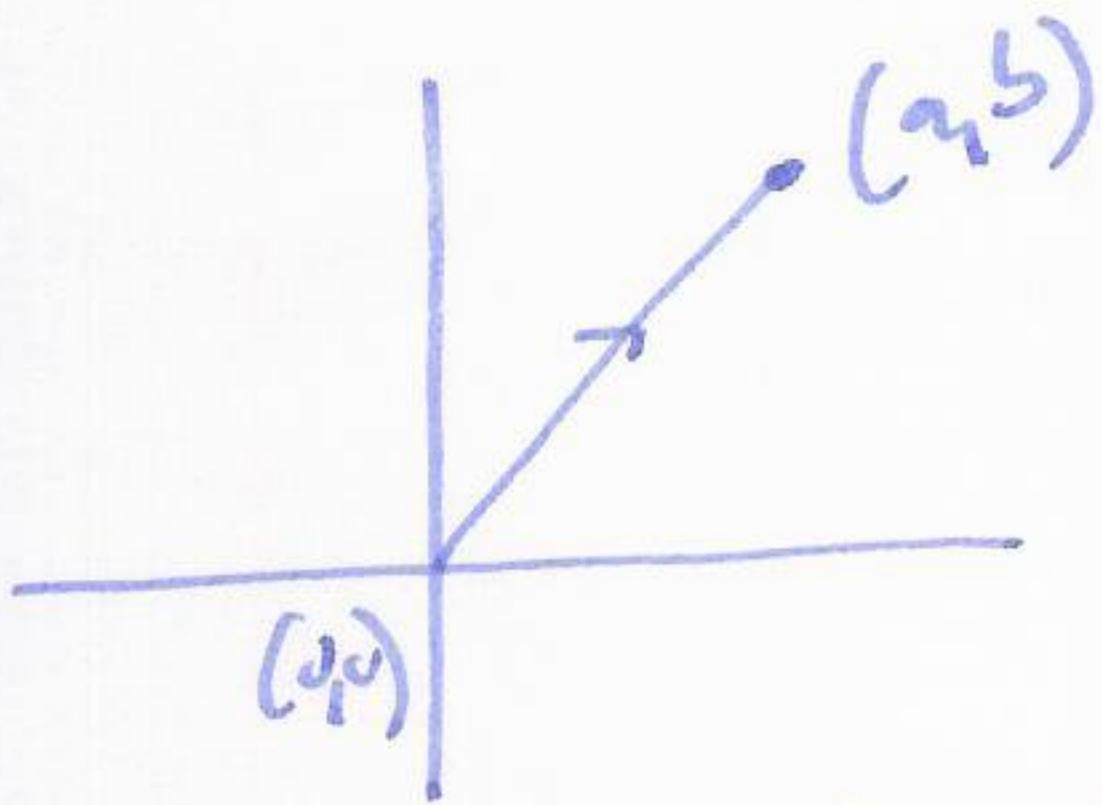
i.e.



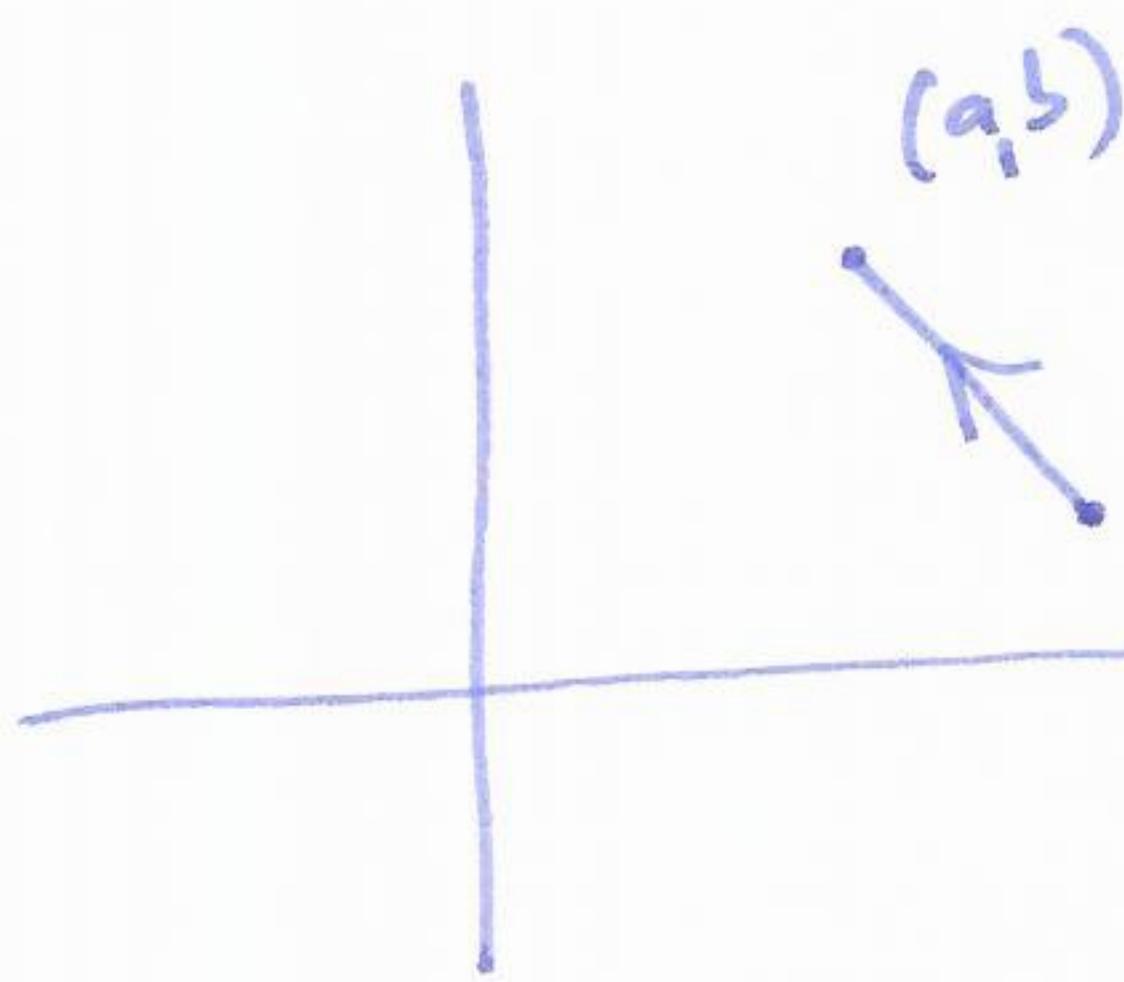
these two pictures describe the same vector, i.e. $\underline{v} = \underline{w}$.

- special zero vector: $\underline{0} \xrightarrow{\quad}$ vector of length 0, its direction is undefined.

- position vectors: given a point (a,b) in \mathbb{R}^2 , we say the position vector for (a,b) is the vector which starts at the origin $(0,0)$, and ends at (a,b)

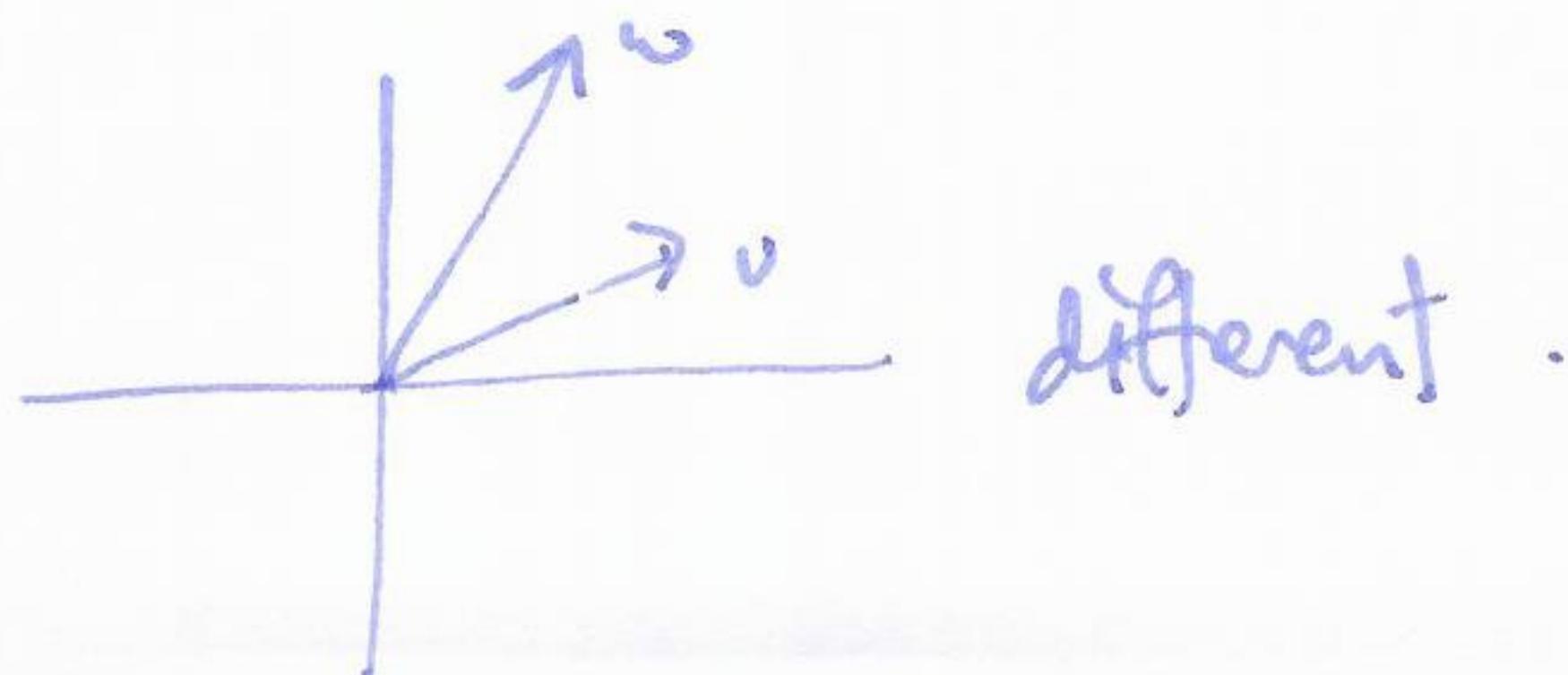
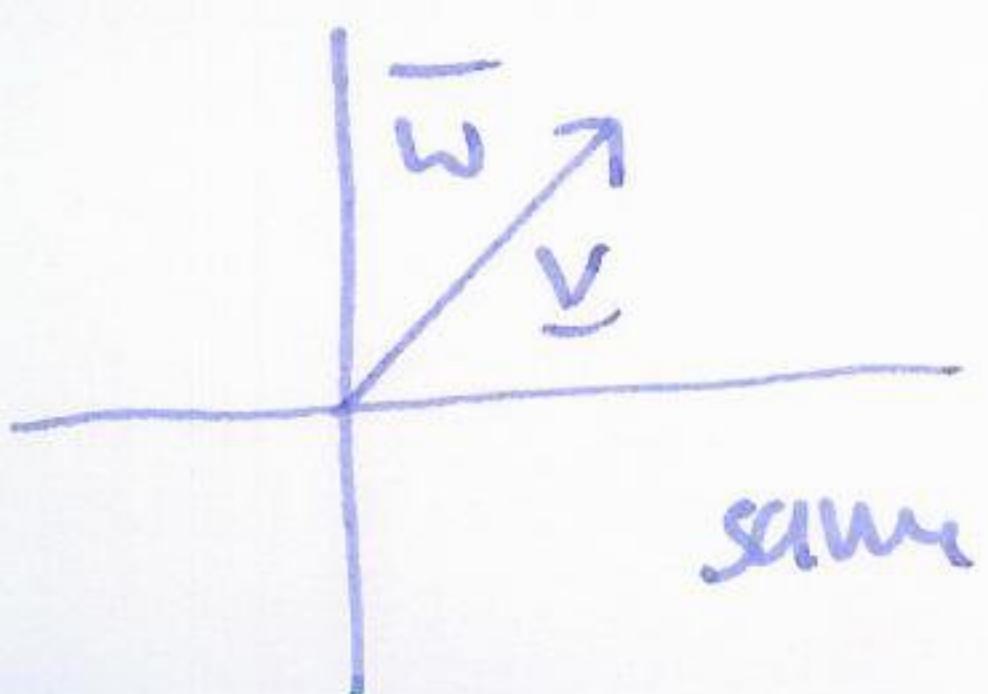


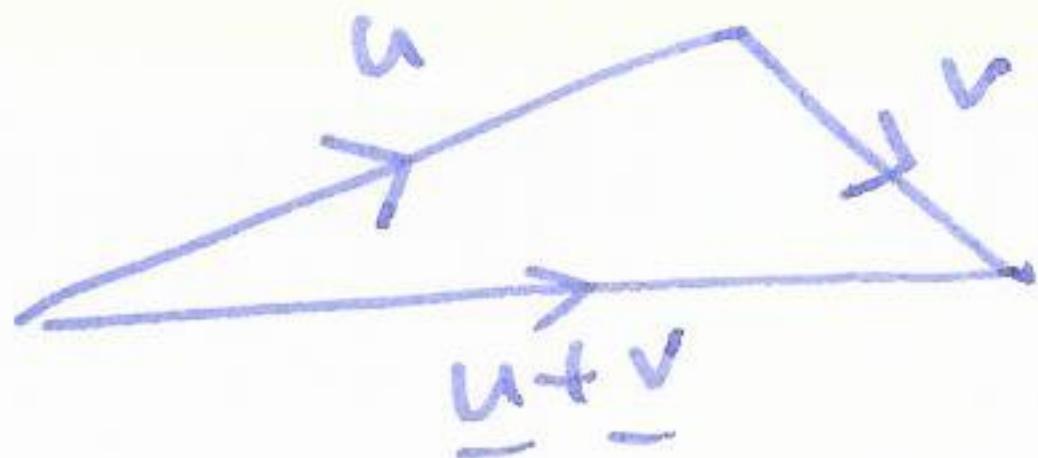
position vector for (a,b)



not the position vector for (a,b) .

observation: given a vector \underline{v} in \mathbb{R}^2 , we may choose to draw it starting at any point in \mathbb{R}^2 , in particular, we may choose to draw it starting at $(0,0)$. Two vectors starting at $(0,0)$ are the same iff they have the same endpoint.

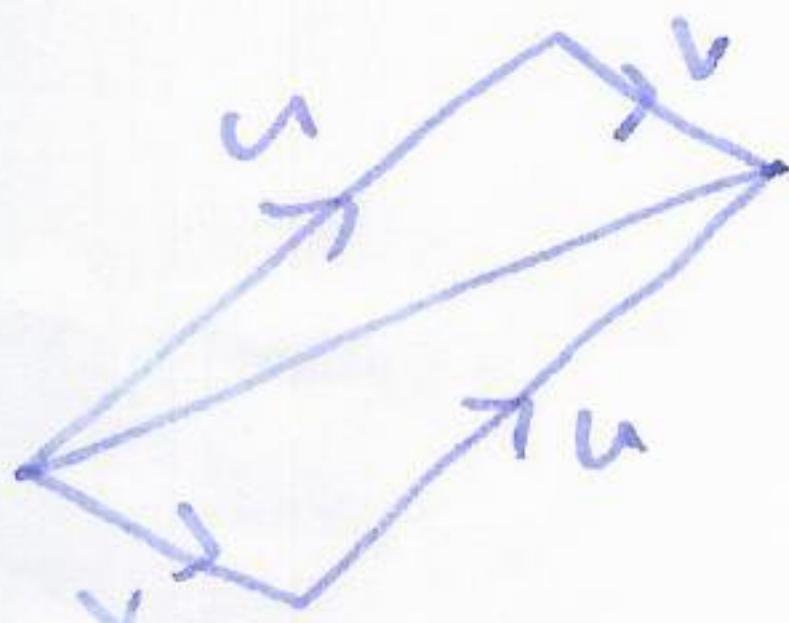


vector addition

if \underline{u} and \underline{v} are vectors, drawn so that the start of \underline{v} is the end of \underline{u} , then $\underline{u}+\underline{v}$ is the vector whose start is the start of \underline{u} , and whose end is the end of \underline{v} .
 (vector addition is sometimes called the triangle rule).

vector addition commutes

$$\text{i.e. } \underline{u}+\underline{v} = \underline{v}+\underline{u}$$



(this is sometimes called the parallelogram rule).

scalar multiplication

let c be a scalar / number

let \underline{v} be a vector

then $c\underline{v}$ is the vector whose length is $|c|$ times the length of \underline{v} , and which points in the same direction as \underline{v} if $c > 0$
opposite direction to \underline{v} if $c < 0$

(if $c=0$ get zero vector $\underline{0}$, direction undefined).

$c\underline{v}$ is the scalar multiple of \underline{v} by c .

Examples

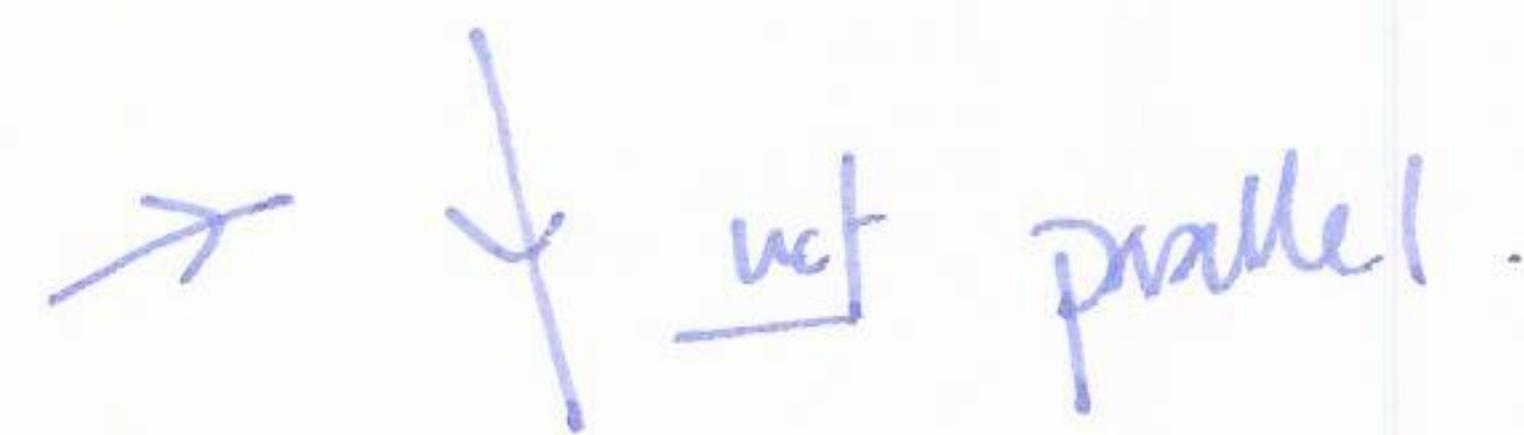
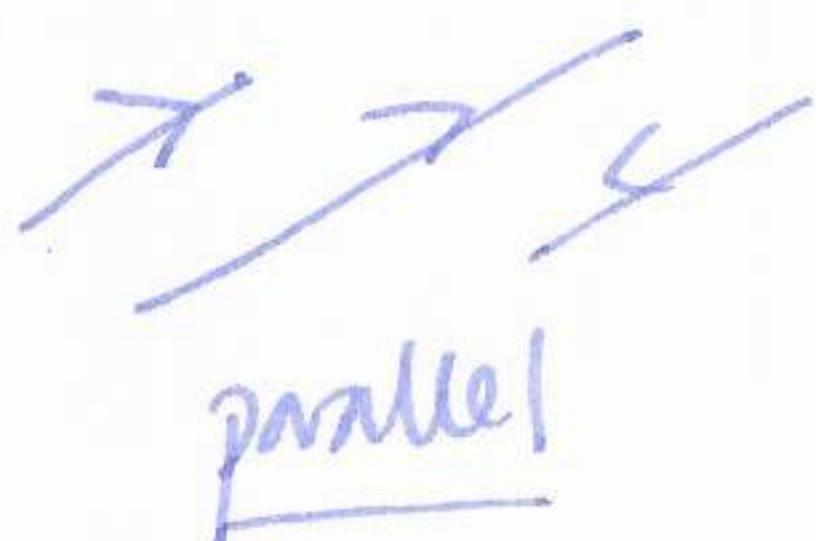
$$\underline{v} \quad 2\underline{v}$$

$$\underline{-v}$$

$$\underline{0} \cdot \underline{v}$$

Defn We say two non-zero vectors are parallel if they are scalar multiples of each other, i.e. if they have the same (or opposite) direction.

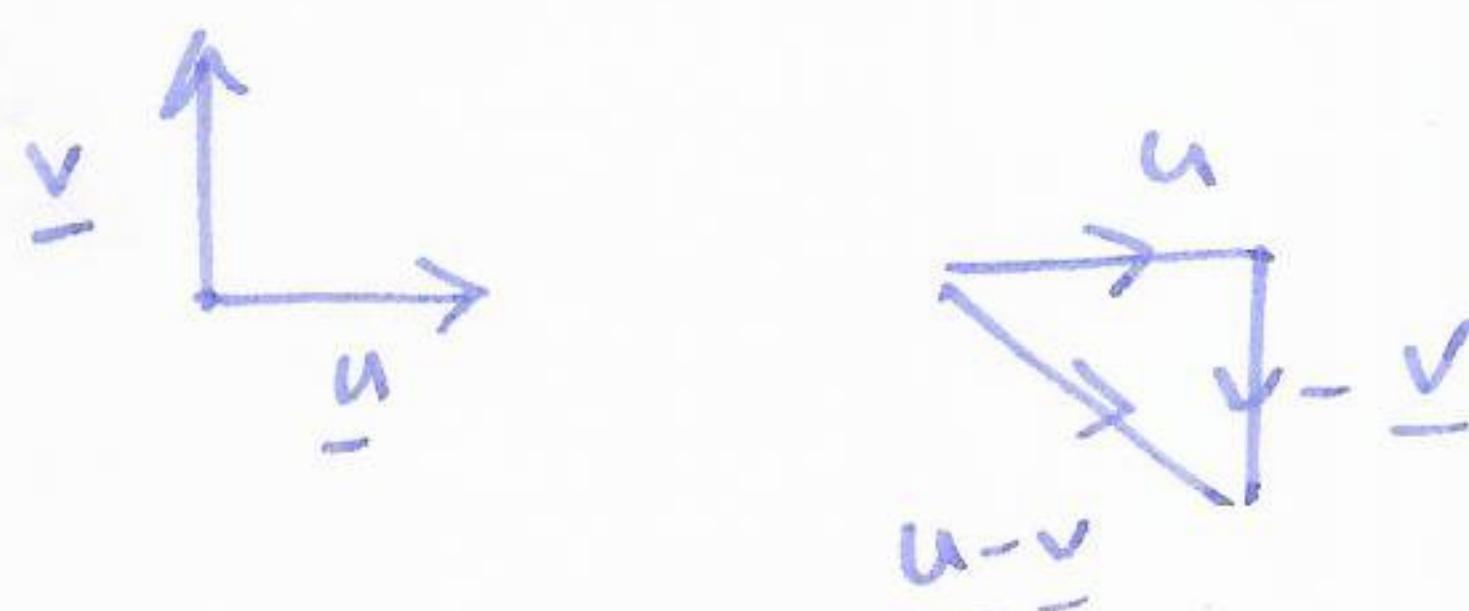
example:



Defn The difference of two vectors \underline{u} and \underline{v} is

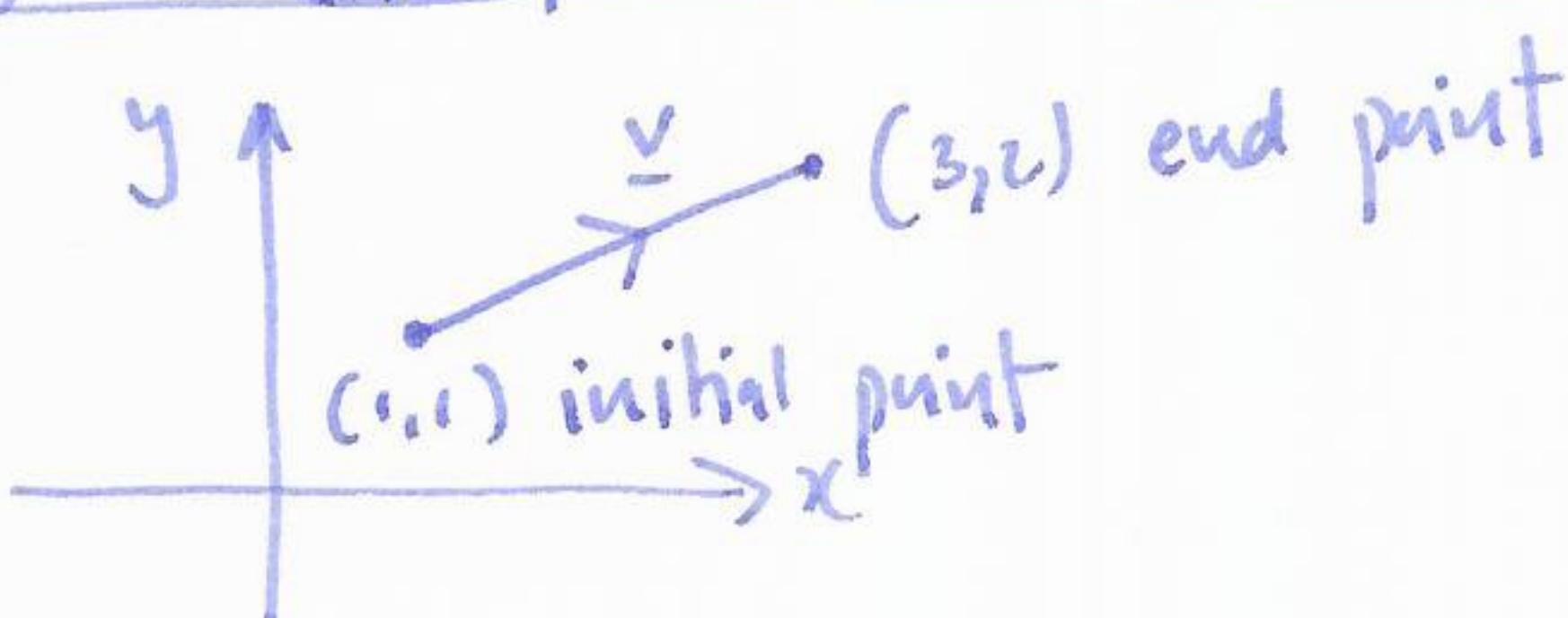
$$\underline{u} - \underline{v} = \underline{u} + (-1) \cdot \underline{v} \quad (\text{does not commute!})$$

example



Coordinate systems / special unit vectors

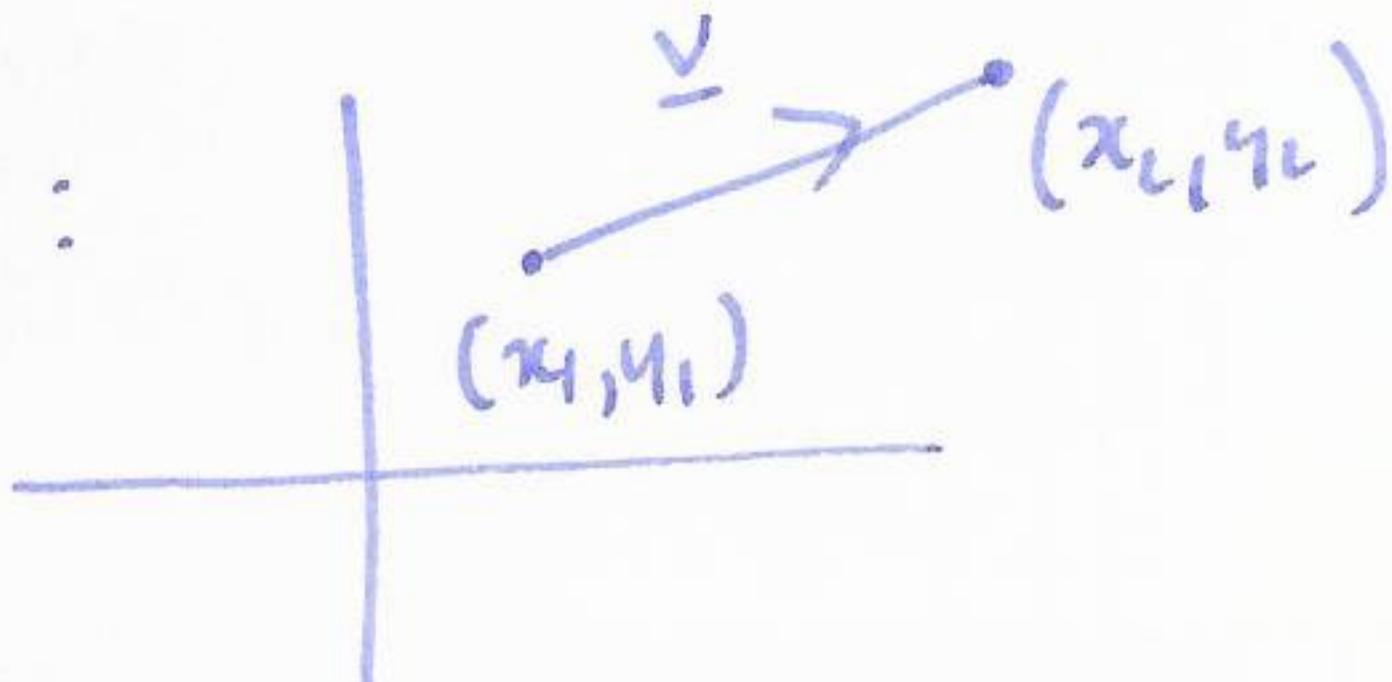
in the plane:



notation: we will write $\underline{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

↑ ↑
 go 2 units in x-direction
 |
 go 1 unit in y-direction.

in general:

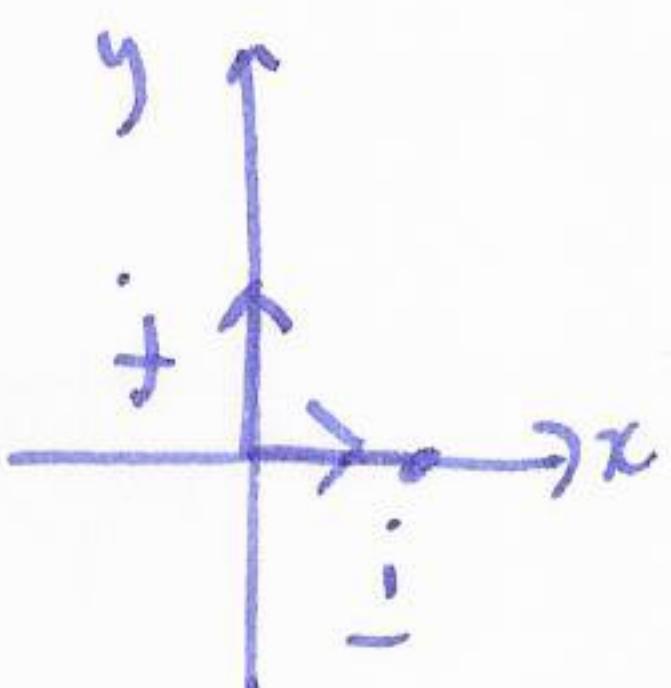


if \underline{v} starts at (x_1, y_1) and ends at (x_2, y_2) , then $\underline{v} = \begin{pmatrix} x_2 - x_1 \\ y_2 - y_1 \end{pmatrix}$
 (we're using the coordinate system to describe vectors)

(5)

recall position vectors: if $p = (x_1, y_1)$ is a point, then the position vector for p is the vector from $(0,0)$ to (x_1, y_1) , i.e. $\langle x_1, y_1 \rangle$.

standard coordinate vectors

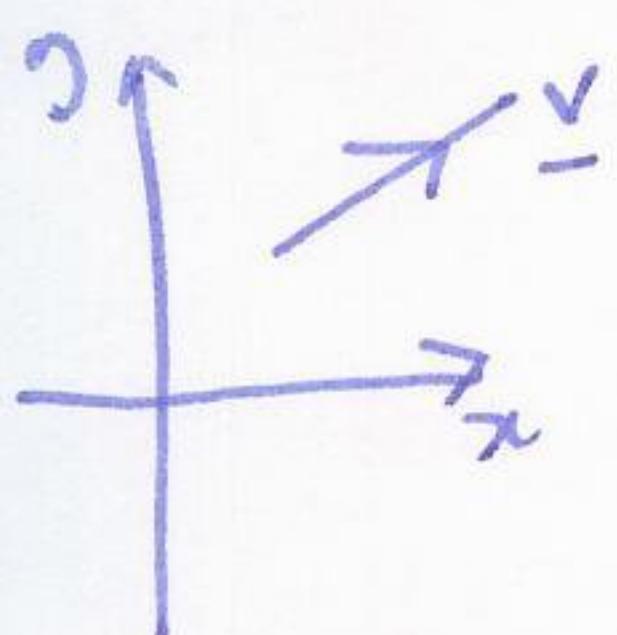
 \mathbb{R}^2 

let $\underline{i} = \langle 1, 0 \rangle$ (position vector for $(1, 0)$)
 $\underline{j} = \langle 0, 1 \rangle$ (" " " " $(0, 1)$)

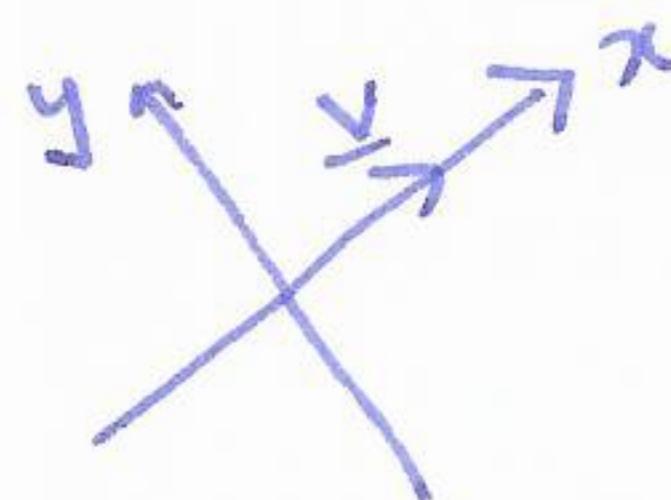
then any vector $\underline{a} = \langle a_1, a_2 \rangle$ can be written as a sum of these, i.e.

$$\begin{aligned}\langle a_1, a_2 \rangle &= a_1 \langle 1, 0 \rangle + a_2 \langle 0, 1 \rangle \\ &= a_1 \underline{i} + a_2 \underline{j}\end{aligned}$$

Remark if possible, choose coordinates to make your life easier.



why not choose:



useful properties of vectors

$\underline{u}, \underline{v}, \underline{w}$ vectors c, d scalars

- $\underline{u} + \underline{v} = \underline{v} + \underline{u}$ (commutativity)
- $(\underline{u} + \underline{v}) + \underline{w} = \underline{u} + (\underline{v} + \underline{w})$ (associativity)
- $\underline{u} + \underline{0} = \underline{u}$ (additive identity)
- $\underline{u} + (-\underline{u}) = \underline{0}$ (additive inverse)
- $c(d\underline{u}) = (cd)\underline{u}$ (scalar associativity)

- $(c+d)\underline{u} = c\underline{u} + d\underline{u}$ (scalar distribution).
- $c(\underline{u} + \underline{v}) = c\underline{u} + c\underline{v}$ (scalar distribution)
- $1\underline{u} = \underline{u}$ (scalar identity)
 $0\underline{u} = \underline{0}$