

Math 338 Linear Algebra Spring 13 Final a

Name: Solutions

- Do any 8 of the following 10 questions.
- You may use a calculator without symbolic algebra capabilities, but no notes.

1	10	
2	10	
3	10	
4	10	
5	10	
6	10	
7	10	
8	10	
9	10	
10	10	
	80	

Final	
Overall	

2

(1) Find all solutions to the following system of linear equations.

$$x_1 - x_2 + x_3 + 2x_4 = 0$$

$$3x_1 - x_2 - x_3 + 9x_4 = 0$$

$$2x_1 - x_2 + 6x_4 = 0$$

$$\begin{bmatrix} 1 & -1 & 1 & 2 \\ 3 & -1 & -1 & 9 \\ 2 & -1 & 0 & 6 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 2 & -4 & 3 \\ 0 & 1 & -2 & 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 2 & -4 & 3 \\ 0 & 0 & 0 & 1/2 \end{bmatrix}$$

$$x_4 = 0, \quad x_3 = t, \quad 2x_2 - 4x_3 + 3x_4 = 0, \quad x_2 = 2t$$

$$x_1 - x_2 + x_3 + 2x_4 = 0, \quad x_1 = 2t - t = t$$

solutions:

$$t \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix}$$

- (2) (a) Write down a matrix for a linear transformation of \mathbb{R}^2 which rotates by $\pi/2$ anticlockwise about the origin.
- (b) Write down a matrix for a linear transformation of \mathbb{R}^2 which doubles lengths in the x -direction, and halves lengths in the y -direction.
- (c) Use your answers above to write down a matrix for the linear transformation of \mathbb{R}^2 obtained by first doubling lengths in the x -direction and halving lengths in the y -direction, and then rotating by $\pi/2$.

$$\text{a) } \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \quad \theta = \frac{\pi}{2} \quad \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$\text{b) } \begin{bmatrix} 2 & 0 \\ 0 & 1/2 \end{bmatrix}$$

$$\text{c) } \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1/2 \end{bmatrix} = \begin{bmatrix} 0 & -1/2 \\ 2 & 0 \end{bmatrix}$$

- (3) (a) Write down a spanning set in \mathbb{R}^4 which is not a basis.
 (b) Write down a basis for \mathbb{R}^4 which is orthogonal, but not orthonormal.
 (c) Write down a set of four distinct vectors which span a three-dimensional subspace of \mathbb{R}^4 .

a) $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

b) $\left\{ \begin{bmatrix} 2 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 2 \end{bmatrix} \right\}$

c) $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix} \right\}$

(4) Apply the Gram-Schmidt process to the following three vectors.

$$\underline{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \underline{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \underline{v}_3 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}.$$

What do you notice about \underline{v}_3 ? What does this tell you about the original three vectors?

$$\underline{q}_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

$$\underline{q}_2' = \underline{v}_2 - (\underline{v}_2 \cdot \underline{q}_1) \underline{q}_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{6}} (3) \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3/2 \\ 3/2 \\ 0 \end{bmatrix}.$$

$$\underline{q}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\underline{q}_3' = \underline{v}_3 - (\underline{v}_3 \cdot \underline{q}_1) \underline{q}_1 - (\underline{v}_3 \cdot \underline{q}_2) \underline{q}_2$$

$$= \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} - \frac{1}{\sqrt{6}} (-3) \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} - \frac{1}{\sqrt{2}} (3) \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$\underline{q}_3 = \underline{0}$

$\Rightarrow \underline{v}_1, \underline{v}_2$ independent but $\underline{v}_3 \in \text{span}\{\underline{v}_1, \underline{v}_2\}$.

(5)

$$A = \begin{bmatrix} 7 & 4 \\ -8 & -5 \end{bmatrix}$$

- (a) Find the eigenvalues of A .
 (b) Find the eigenvectors for A .

$$\begin{aligned} \text{a) } \begin{vmatrix} 7-\lambda & 4 \\ -8 & -5-\lambda \end{vmatrix} &= (7-\lambda)(-5-\lambda) + 32 = \lambda^2 - 2\lambda - 3. \\ &= (\lambda-3)(\lambda+1) \end{aligned}$$

$$\lambda = 3, -1.$$

$$\text{b) } \lambda_1 = 3: \begin{bmatrix} 4 & 4 \\ -8 & -3 \end{bmatrix} \Rightarrow \underline{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\lambda_2 = -1: \begin{bmatrix} 8 & 4 \\ -8 & -4 \end{bmatrix} \Rightarrow \underline{v}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

(10) Let A be the matrix given in the previous question. (a) Find the eigenvalues and eigenvectors of A . (b) Diagonalize A if possible. (c) Find the matrix of A in the basis of eigenvectors.

(a) $\lambda_1 = 1, \lambda_2 = 2$
 $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

(b) $P = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}, D = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$

(c) $P^{-1}AP = D$
 $\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$

(d) $A = PDP^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$

(e) $A^n = P D^n P^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1^n & 0 \\ 0 & 2^n \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$

(f) $A^{-1} = P D^{-1} P^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$

- (7) If A is a non-singular $n \times n$ matrix such that $A^{-1} = -A$, what can you say about the determinant of A ? (Hint: there are two cases depending on whether n is odd or even.)

$$A^{-1} = -A$$

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

$$\det(-A) = \begin{cases} \det(A) & n \text{ even} \\ -\det(A) & n \text{ odd} \end{cases}$$

n even :

$$\frac{1}{d} = d \Rightarrow d^2 = 1 \Rightarrow d = \pm 1$$

n odd :

$$\frac{1}{d} = -d \Rightarrow d^2 = -1 \Rightarrow d = \pm i$$

(8) Let A be a 4×5 matrix such that there are two different vectors x_1 and x_2 such that $Ax_1 = Ax_2$.

(a) What can you say about the kernel of A ?

(b) What can you say about the column rank of A ?

$$a) \quad A(x_1 - x_2) = 0 \quad \text{so} \quad \begin{matrix} x_1 - x_2 \in \ker(A) \\ \neq 0 \end{matrix} \Rightarrow \dim(\ker(A)) \geq 1$$

$$b) \quad 0 < \dim(C(A)) \leq 4$$

(9) Let B be the basis for \mathbb{R}^2 given by

$$B = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}.$$

- (a) Find a matrix which converts vectors written in the standard basis to vectors written with respect to the basis B .
- (b) Use your answer to (a) to write $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ (in the standard basis) as a linear combination of vectors in B .
- (c) Use your answer to (a) to write the matrix $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ with respect to the ~~matrix~~ *basis* B .

$$a) \quad \begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix}^{-1} = \frac{1}{3} \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix}$$

$$b) \quad \frac{1}{3} \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \text{check} \quad -\frac{1}{3} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \frac{2}{3} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$c) \quad \begin{array}{ccc} \mathbb{R}_E^2 & \xrightarrow{\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}} & \mathbb{R}_E^2 \\ \uparrow & & \uparrow \\ \mathbb{R}_B^2 & \longrightarrow & \mathbb{R}_B^2 \end{array}$$

$$\frac{1}{3} \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix}$$

$$\frac{1}{3} \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & -4 \\ 1 & 5 \end{bmatrix}$$

(10) Let $A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & -2 & 4 \end{bmatrix}$.

- (a) Find the eigenvalues and eigenvectors for A .
 (b) Can you diagonalize A ? Explain.

$$a) \begin{vmatrix} 2-\lambda & 0 & 0 \\ 0 & -\lambda & 2 \\ 0 & -2 & 4-\lambda \end{vmatrix} = (2-\lambda) \left[-\lambda(4-\lambda) + 4 \right] = (2-\lambda)(\lambda^2 - 4\lambda + 4) \\ = -(\lambda-2)^3.$$

$\lambda = 2$ with multiplicity 3.

$$b) \begin{bmatrix} 0 & 0 & 0 \\ 0 & -2 & 2 \\ 0 & -2 & 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 0 & 0 & 0 \\ 0 & -2 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 0 & -2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_3 = t \quad -2x_2 + 2x_3 = 0 \quad x_2 = t \quad x_1 = s.$$

eigenvectors $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

No, cannot diagonalize A , not enough eigenvectors.