

Uniform Invariance Principles for Intersection Local Times

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1 Introduction

Let S_n be a strongly aperiodic stable random walk, i.e. in the domain of attraction of a non-degenerate stable random variable U of index β in \mathbf{R}^d . Thus

$$\frac{S_n}{b_n} \xrightarrow{\mathcal{L}} U$$

for some b_n which is regularly varying of order β .

Given k independent copies $S_n^{(1)}, \dots, S_n^{(k)}$ of S_n we define their k -fold intersection local time by

$$(1.1) \quad I_k(x, t) = \sum_{i_1, \dots, i_k=1}^t \delta(S_{i_2}^{(2)} - S_{i_1}^{(1)}, x_1) \cdots \delta(S_{i_k}^{(k)} - S_{i_{k-1}}^{(k-1)}, x_{k-1})$$

where

$$\delta(i, j) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

is the usual Kronecker delta function and $x = (x_1, \dots, x_{k-1}) \in (\mathbf{Z}^d)^{k-1}$, $t \in \mathbf{Z}_+$. This definition is extended to $x \in (\mathbf{R}^d)^{k-1}$, $t \in \mathbf{R}_+$ by linear interpolation.

Let Z_t denote the stable Levy process of index β in \mathbf{R}^d with $Z_1 = U$. We use $p_t(x)$ for the transition density of Z_t . If $Z_t^{(1)}, \dots, Z_t^{(k)}$ denote k independent copies of Z_t , we set

$$\alpha_k(\epsilon, x, t) = \int_{D_k} p_\epsilon(Z_{s_2}^{(2)} - Z_{s_1}^{(1)} - x_1) \cdots p_\epsilon(Z_{s_k}^{(k)} - Z_{s_{k-1}}^{(k-1)} - x_{k-1}) ds_1 \cdots ds_k$$

where $D_k = \{(s_1, \dots, s_k) \in \mathbf{R}^k \mid 0 \leq s_1 \leq \dots \leq s_k \leq t\}$. It is known that if $\beta > d - d/k$ then $\alpha_k(\epsilon, x, t)$ converges, as $\epsilon \rightarrow 0$, to a random variable, called the k -fold intersection local time, and denoted $\alpha_k(x, t)$. Convergence is locally uniform both a.s. and in all

L^p spaces. The k -fold intersection local time $\alpha_k(x, t)$ is jointly continuous in (x, t) .

Theorem 1 *If $\beta > d - d/k$ then*

$$I_k(b_n x, nt) b_n^{(k-1)d/n^k} \implies \alpha_k(x, t)$$

as $n \rightarrow \infty$, where we have weak convergence of processes in $C(\mathbf{R}^{d(k-1)} \times \mathbf{R}_+)$.

Such a theorem is referred to as a uniform invariance principle for intersection local times. It "uniformizes" our work in [5] where the convergence in Theorem 1 is proven for fixed x and t . Our present theorem was inspired by the work of Bass and Khoshnevisan [1, 2] who establish Theorem 1 for random walks with finite variance, in which case $\beta = 2$ and $b_n = \sqrt{n}$. Their work, in turn, was motivated by the uniform invariance principles of Perkins [4] and Borodin [3] for ordinary local times. We should also mention that in [2], Bass and Khoshnevisan obtain a strong invariance principle for intersection local times of certain random walks. More precisely, they show that if a random walk converges almost surely to Brownian motion at a certain rate, then this will also hold for their intersection local times.

2 Proof of Theorem 1

The proof of a uniform invariance principle consists of two parts: a proof that the finite dimensional distributions converge, and a proof of tightness. The proof that the finite dimensional distributions converge proceeds almost exactly as in [5] where convergence of the marginal distributions is established. We shall only recall the basic ideas and mention the necessary modifications.

By a change of variables, for $x \in (\mathbf{Z}^d)^{k-1}/b_n$, $t \in \mathbf{Z}_+/n$ we have

$$(2.1) \quad L_k(n, x, t) \stackrel{\text{def}}{=} I_k(b_n x, nt) b_n^{(k-1)d/n^k} \\ = \sum_{i_1, \dots, i_k=1}^{nt} \frac{1}{n^k} \prod_{j=2}^k \frac{1}{(2\pi)^d} \int_{|p_j|_0 \leq \pi b_n} \exp(ip_j \frac{S_{i_j}^{(j)} - S_{i_{j-1}}^{(j-1)} - b_n x_{j-1}}{b_n}) dp_j$$

where for a vector $y = (y_1, \dots, y_d) \in \mathbf{R}^d$ we use $|y|_0 \stackrel{\text{def}}{=} \max_i |y_i|$.

We then define a 'link'

$$(2.2) \quad L_k(\epsilon, n, x, t) \stackrel{\text{def}}{=} \sum_{i_1, \dots, i_k=1}^{nt} \frac{1}{n^k} \prod_{j=2}^k \frac{1}{(2\pi)^d} \int_{|p_j|_0 \leq \pi b_n} \exp(ip_j \frac{S_{i_j}^{(j)} - S_{i_{j-1}}^{(j-1)} - b_n x_{j-1}}{b_n}) \Phi_\epsilon(p_j) dp_j$$

where $\Phi_\epsilon(p)$ is the characteristic function of Z_ϵ , i.e. the Fourier transform of $p_\epsilon(x)$.

In lemma 1 of [5] we essentially prove that

$$\|L_k(n, x, t) - L_k(\epsilon, n, x, t)\|_2 \leq c\epsilon^\gamma$$

for some $c < \infty, \gamma > 0$ uniformly in $(x, t) \in \mathbb{R}^{d(k-1)} \times [0, T]$ for any $T < \infty$.

Hence for any fixed $\lambda_i, z_i, t_i \quad i = 1, \dots, m$, if we set

$$L(\epsilon, n) \stackrel{\text{def}}{=} \sum_{i=1}^m \lambda_i L_k(\epsilon, n, z_i, t_i)$$

and

$$L(n) \stackrel{\text{def}}{=} \sum_{i=1}^m \lambda_i L_k(n, z_i, t_i)$$

we have that

$$(2.3) \quad |E(e^{iL(n)}) - E(e^{iL(\epsilon, n)})| \leq c\epsilon^\gamma.$$

On the other hand, it follows from the locally uniform convergence of $\alpha_k(\epsilon, x, t)$ to $\alpha_k(x, t)$ that if we set

$$\alpha(\epsilon) \stackrel{\text{def}}{=} \sum_{i=1}^m \lambda_i \alpha_k(\epsilon, z_i, t_i)$$

and

$$\alpha \stackrel{\text{def}}{=} \sum_{i=1}^m \lambda_i \alpha_k(z_i, t_i)$$

we can choose $\epsilon_0 > 0$ such that for any given $\delta > 0$ we have both $c\epsilon_0^\gamma \leq \delta$ and

$$(2.4) \quad |E(e^{i\alpha}) - E(e^{i\alpha(\epsilon_0)})| \leq \delta.$$

From (2.2) we see that

$$(2.5) \quad L_k(\epsilon, n, x, t) = \sum_{i_1, \dots, i_k=1}^{nt} \frac{1}{n^k} \prod_{j=2}^k p_{\epsilon_0} \left(\frac{S_{i_j}^{(j)} - S_{i_{j-1}}^{(j-1)} - b_n x_{j-1}}{b_n} \right) dp_j + O(e^{-\epsilon_0 n^{1/2}}).$$

We see from this, using [6], that we can find n_0 such that for all $n \geq n_0$ we have

$$|E(e^{iL(\epsilon_0, n)}) - E(e^{i\alpha(\epsilon_0)})| \leq \delta.$$

Together with (2.4) and (2.5) this shows the convergence of finite dimensional distributions.

To prove tightness it suffices to show that we can find some $\gamma > 0$ such that for any even m

$$(2.6) \quad E\{(L_k(n, x, t) - L_k(n, x', t'))^m\} \leq c|(x, t) - (x', t')|^{m\gamma}$$

uniformly over $n \in \mathbf{Z}_+$, $x, x' \in \mathbf{R}^d$ and $t, t' \in [0, T]$.

We begin by showing how to get a bound on

$$E\{(L_k(n, x, t))^m\}$$

which is uniform in $n \in \mathbf{Z}_+$, $x \in \mathbf{R}^d$ and $t \in [0, T]$. Once we see how to accomplish this, it will be easy to establish (2.6).

Recalling (2.1) we have

$$\begin{aligned} (2.7) \quad & E\{(L_k(n, x, t))^m\} \\ &= E\left\{\prod_{h=1}^m \sum_{i_{1,h}, \dots, i_{k,h}=1}^{nt} \frac{1}{n^k} \prod_{j=2}^k \frac{1}{(2\pi)^d} \right. \\ & \quad \left. \int_{|p_{j,h}|_0 \leq \pi b_n} \exp(ip_{j,h} \frac{S_{i_{j,h}}^{(j)} - S_{i_{j-1,h}}^{(j-1)} - b_n x_{j-1}}{b_n}) dp_{j,h}\right\} \\ &= \frac{1}{(2\pi)^{d(k-1)m}} \int_{|p_{j,h}| \leq \pi b_n} F(p, x) \prod_{j=1}^k \frac{1}{n^{km}} \\ & \quad \sum_{i_{j,1}, \dots, i_{j,m}=1}^{nt} E\left\{\exp\left(i \sum_{h=1}^m \frac{(p_{j,h} - p_{j+1,h})}{b_n} S_{i_{j,h}}^{(j)}\right)\right\} dp \end{aligned}$$

where

$$F(p, x) = \exp\left(i \sum_{h=1}^m \sum_{j=2}^k p_{j,h} x_{j-1}\right)$$

and we have set $p_{1,h} = p_{k+1,h} = 0$.

Let π^1, \dots, π^k be k not necessarily distinct permutations of $\{1, \dots, m\}$ and let

$$\Delta(\pi^1, \dots, \pi^k) = \{i_{j,h} \mid i_{j,\pi_l^j} \leq i_{j,\pi_{l+1}^j}; j = 1, \dots, k; l = 1, \dots, m\}$$

and note that on $\Delta(\pi^1, \dots, \pi^k)$ we have

$$\begin{aligned} (2.8) \quad & E\left\{\exp\left(i \sum_{h=1}^m \frac{(p_{j,h} - p_{j+1,h})}{b_n} S_{i_{j,h}}^{(j)}\right)\right\} \\ &= E\left\{\exp\left(i \sum_{h=1}^m u_{j,h} (S_{i_{j,\pi_h^j}}^{(j)} - S_{i_{j,\pi_{h-1}^j}}^{(j)})/b_n\right)\right\} \\ &= \prod_{h=1}^m \varphi^{\pi_h^j - \pi_{h-1}^j}(u_{j,h}/b_n) \end{aligned}$$

where

$$\varphi(u) = E(\exp(iuS_1))$$

and

$$u_{j,h} = \sum_{l=1}^h (p_{j,\pi_l^j} - p_{j+1,\pi_l^j}).$$

Note that

$$(2.9) \quad \text{span}\{u_{j,h} \mid h = 1, \dots, m\} = \text{span}\{p_{j,h} - p_{j+1,h} \mid h = 1, \dots, m\}$$

and that if $\tilde{\pi}^j$ denotes the inverse of the permutation π^j we have

$$(2.10) \quad p_{j,h} - p_{j+1,h} = u_{j,\tilde{\pi}_h^j} - u_{j,\tilde{\pi}_{h-1}^j}$$

If we define

$$G_r(n, u) = \frac{1}{n} \sum_{j=0}^{nT} |\varphi(u/b_n)|^{jr}$$

then it is clear from the above that (2.7) can be bounded by a sum over regions $\Delta(\pi^1, \dots, \pi^k)$ of integrals of the form

$$(2.11) \quad \int_{|p_{j,h}| \leq \pi b_n; j=2, \dots, k} \prod_{j=1}^k \prod_{h=1}^m G_1(n, u_{j,h}) dp$$

$$\leq \prod_{i=1}^k \left\{ \int_{|p_{j,h}| \leq \pi b_n; j=2, \dots, k} \prod_{j=1; j \neq i}^k \prod_{h=1}^m G_1^{k/(k-1)}(n, u_{j,h}) dp \right\}^{(k-1)/k}.$$

By [5] we know that for any $\epsilon, r > 0$ and $T < \infty$ we have

$$G_r(n, u) \leq \frac{c}{1 + ((u))^{\beta-\epsilon}}$$

where $((u))$ denotes the norm of the smallest vector which equals u mod 2π . Since, by (2.9), for any i

$$\text{span}\{u_{j,h} \mid h = 1, \dots, m; j = 1, \dots, k; j \neq i\}$$

$$= \text{span}\{p_{j,h} \mid h = 1, \dots, m; j = 2, \dots, k\}$$

we have that (2.11) and hence (2.7) is bounded uniformly if $k/(k-1)\beta > d$.

We now show how to modify the above estimates to get (2.6). First, we have

$$(2.12) \quad E\{(L_k(n, x, t) - L_k(n, x', t'))^m\}$$

$$\leq E\{(L_k(n, x, t) - L_k(n, x', t))^m\} + E\{(L_k(n, x', t) - L_k(n, x', t'))^m\}$$

and we can handle the x and t variation separately.

The first term in (2.12), the x variation, can be written as in (2.7) except that the factor $F(p, x)$ will be replaced by

$$H(p, x, x') = \prod_{h=1}^m \left\{ \exp\left(i \sum_{j=2}^k p_{j,h} x_{j-1}\right) - \exp\left(i \sum_{j=2}^k p_{j,h} x'_{j-1}\right) \right\}.$$

Since for any $0 \leq \delta \leq 1$ we have

$$|H(p, x, x')| \leq c \prod_{h=1}^m \left(\sum_{j=2}^k |p_{j,h}| \right)^\delta |x - x'|^\delta$$

and using (2.10) for any $i = 1, \dots, k$ we have

$$\begin{aligned} & \prod_{h=1}^m \sum_{j=2}^k |p_{j,h}| \\ & \leq c \prod_{h=1}^m \sum_{j=1; j \neq i}^k |p_{j,h} - p_{j-1,h}| \\ & \leq c \prod_{h=1}^m \prod_{j=1; j \neq i}^k 1 + |p_{j,h} - p_{j-1,h}| \\ & \leq c \prod_{h=1}^m \prod_{j=1; j \neq i}^k 1 + |u_{j, \bar{\pi}_h^j} - u_{j-1, \bar{\pi}_h^{j-1}}| \\ & \leq c \prod_{h=1}^m \prod_{j=1; j \neq i}^k 1 + |u_{j,h}|^2 \end{aligned}$$

it is clear that by choosing $\delta > 0$ sufficiently small we can achieve the desired bound.

The second term in (2.12), the t variation, gives rise to a term similar to (2.7) except that for each l ; $l = 1, \dots, m$ the indices $\{i_{1,l}, \dots, i_{k,l}\}$ run through the set $A = [0, nt]^k - [0, nt']^k$. Using (2.8), we can bound the t variation by a sum over regions $\Delta = \Delta(\pi^1, \dots, \pi^k)$ of integrals of the form (2.11), except that the integrand is replaced by

$$\begin{aligned} & \frac{1}{n^{km}} \sum_{A^m \cap \Delta} \prod_{j=1}^k \prod_{h=1}^m |\varphi(u_{j,h}/b_n)|^{\pi_h^j - \pi_{h-1}^j} \\ & \leq \left(\frac{1}{n^{km}} |A|^m \right)^{1/q} \left\{ \prod_{j=1}^k \prod_{h=1}^m G_{q'}(n, u_{j,h}) \right\}^{1/q'} \\ & \leq c |t - t'|^{m/q} \prod_{j=1}^k \prod_{h=1}^m \frac{1}{1 + ((u_{j,h}))^{(\beta-c)/q'}} \end{aligned}$$

for any q, q' satisfying $1/q + 1/q' = 1$. It is now clear that by taking q' sufficiently close to 1 we can obtain the desired bound on the t variation in (2.12). This completes the proof of our theorem. \square

References

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